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# Two-dimensional numerical analysis on the rock-bolt interaction considering shear and normal relative displacements

Pierpaolo Oreste<sup>1</sup>, Giovanni Spagnoli<sup>2\*</sup>

<sup>1</sup> Department of Environment, Land and Infrastructure Engineering, Politecnico di Torino, Corso Duca Degli Abruzzi 24, 10129 Torino, Italy; [pierpaolo.oreste@polito.it](mailto:pierpaolo.oreste@polito.it)

<sup>2</sup> DMT GmbH & Co. KG, Am TÜV 1, 45307 Essen, Germany, [giovanni.spagnoli@dm-group.com](mailto:giovanni.spagnoli@dm-group.com) ORCID: 0000-0002-1866-4345 (CORRESPONDING AUTHOR)

## Abstract

Fully grouted passive bolts are widely used in underground or surface rock excavations and in particular in stabilizing potentially unstable blocks of rock due to sliding on natural discontinuities. Their operating mechanism is complex, but it is possible to consider two stabilizing forces that each bolt applies to the block of rock. These forces depend on the mechanical parameters governing the bolt-rock interaction, which are difficult to evaluate. In this work, specific numerical analyzes of great detail have been developed, able of evaluating the bolt-rock interaction (in shear and perpendicular to the interface that separates them) for numerous cases that were obtained by varying the main geometric parameters of the bolt, the mechanical properties of the binder material and rock. Thanks to this complex study, it was possible to describe the variability of the interaction parameters and to define, through graphs, the trend of the stabilization forces as the main geometric and mechanical parameters that can be encountered in practice change. The graphs obtained are a useful tool for the correct design of fully geouted passive bolts and the stabilization of potentially unstable rock blocks on the walls of underground cavities or on the faces of surface excavations.

24 **Key words:** passive bolt, cement grout, rock block stabilization, rock reinforcement, bolt-  
25 rock interaction; stabilizing forces

26

27 **Nomenclature**

28	$E_{binder}$	Elastic modulus of the material constituting the annular binder
29	$E_{rock}$	Elastic modulus of rock
30	$(EA)_{bolt}$	axial bolt stiffness
31	$(EJ)_{bolt}$	flexural bolt stiffness
32	$k$	stiffness of the normal interaction springs
33	$L_a$	length of the bolt section that crosses the potentially unstable block
34	$L_p$	length of the bolt section in the stable rock (anchoring length)
35	$N_{0,max}$	axial stabilizing force that the bolt applies to the rock block
36	$N_{slip}$	force for a unit bolt length which causes the bolt-rock interface to fail
37	$N_{test}$	applied axial force at the bolt head during a slip test
38	$N_{yield}$	force causing the steel bar failure under a tensile stress
39	$t_{binder}$ :	thickness of the binder annulus
40	$T_{0,max}$	transversal stabilizing forces that the bolt applies to the rock block
41		(perpendicular to the bolt axis, directed upward, in the plane of the bolt axis
42		and the block displacement vector)
43	$T_{test}$	transversal force applied to the bolt head during an in situ test
44	$v$	relative axial displacement between the bolt and the surrounding rock
45	$y$	transversal displacement of the bolt (against the surrounding rock) as it
46		undergoes deformation due to the movement of the block

47	$\alpha$	parameter characterising the rock-bolt interaction in the axial direction
48		between the bolt and the surrounding rock $\alpha = \sqrt{\frac{\beta_c \cdot P_{hole}}{EA}}$
49	$\beta$	parameter characterizing the rock-bolt interaction in the transversal direction
50		between the bolt and the surrounding rock $\beta = \sqrt[4]{\frac{k \cdot \Phi_{hole}}{4 \cdot EJ}}$
51	$\beta_c$	stiffness of the shear interaction springs at the bolt-rock interface
52	$\delta$	displacement vector of the rock block (parallel to the slip surface)
53	$\delta_{ax,test}$	measured axial displacement of the bolt head
54	$\delta_{tr,test}$	measured transversal displacement of the bolt head
55	$\Phi_{bar}$	diameter of the steel bar
56	$\Phi_{hole}$	diameter of the hole (of the bolt)
57	$\sigma$	normal stress (perpendicular) to the outer surface of the bolt
58	$\tau$	shear stress that exists at the rock-bolt interface
59	$\vartheta$	angle which forms the displacement vector of the block $\delta$ with the direction of
60		the bolt axis
61		

## 62 **Introduction**

63 Passive bolts have long been employed in geotechnical engineering to stabilize soils and  
64 rocks. A passive bolt is made up of a bar that is placed into a borehole that is dug into the  
65 soil or rock mass nearby and fastened to it with a cementitious or resin-based injection.  
66 According to Windsor and Thompson (1993), 1) the rock or soil, 2) the reinforcing bar, 3)  
67 the internal fixture to the borehole wall, and 4) the exterior fixture to the excavation surface  
68 are the four main parts of a rock bolt reinforcement system. For example, by eliminating joint  
69 movements and pushing the rock mass to maintain itself, the rock bolting system in particular  
70 may increase the competency of disturbed rock masses (Kaiser et al., 1992).

71 Tensile, compressive, shear, and bending stresses can be supported by fully grouted rock  
72 bolts, which have the ground's gap between the rod and the ground totally filled with a  
73 binding material. A debonding process that begins if the axial stress on the bar exceeds a  
74 certain value and spreads throughout the interface is thought to be the most likely place for  
75 fully grouted bolt failure, according to experience from around the world (e.g. Stillborg, 1994;  
76 Li and Stillborg, 1999; Moosavi et al., 2005). For instance, due to an increase in axial, shear,  
77 and bending moments in the bolt rod, a fully grouted bolt intersected by a joint may affect  
78 the shearing of a joint and increase bolt resistance (Ranjbarnia et al., 2016; Oreste & Dias,  
79 2012). According to Lang (1961), rock bolts can be used to "lock together" blocks in highly  
80 fractured rock masses to form a "reinforced arch" around an underground aperture that can  
81 stabilize the hollow. Rock bolting significantly affects the rigidity of a jointed rock mass in  
82 addition to strengthening or stabilizing it (Chappell, 1989). Because they are simple to install,  
83 versatile, and relatively inexpensive compared to other options, rock bolts are frequently  
84 used to support jointed surrounding rock and reinforce the rock mass (Indraratna and Kaiser,  
85 1990).

86 While for active bolts the tensile load transfers from the element as an active compressive  
87 load, increasing therefore the resulting stress confinement in the rock, for passive bolts the  
88 initial load on passive reinforcing parts is zero, and when the potentially unstable rock block  
89 is moved, transmit stabilizing forces and the mobilized stabilizing load rises until the block  
90 is fully stabilized (Carranza-Torres, 2009). It is crucial to consider the physical and  
91 mechanical properties of the binder, either cementitious or resin-based during the design  
92 phase of the bolt, because it interacts with the surrounding rock.

93 Cementitious and resin materials are typically used to secure the bolt within the hole, and  
94 this type of set up is known as Continuous Mechanically Coupled (CMC) elements. For  
95 cementitious binders, a common water to cement (w/c) ratio is between 0.35 and 0.5, and  
96 the grout should be easily pumpable without being overly fluid (Kilic et al., 2002; Bawden,  
97 2011). As for resin-based binders, a plastic cartridge containing two components (i.e. a resin  
98 and catalyst in separate compartments) is inserted in the drilled hole ahead of the bolt  
99 element (Bawden, 2011). Epoxy resins, silicate resins, polyester resins, and polyurethane  
100 resins are examples of common forms of resin. The catalyst and resin are mixed via an  
101 exothermic reaction as the cartridge is spun into the hole. Depending on the mix  
102 requirements, the resin sets in 20 seconds to 3 minutes, forming a solid anchor. Aldrian et  
103 al. (2019) claim however that very little grout can enter the surrounding cracks because the  
104 cartridge capacity is fixed and the inserted steel is creating only the "pressure" necessary to  
105 completely fill the annular gap.

106 Numerous laboratory and field studies have been conducted to examine the behavior of the  
107 rock-bolt grouted system. Pull-out tests (tension loading) or shear tests (shear loading) can  
108 be used to test the load capacity of bolt in the field or the lab. Standards like DIN-21521  
109 (1990) or ISRM recommendations for rock bolt testing should be followed while conducting  
110 rock bolt tests. There are three primary failure scenarios in the event of a grouted anchor in

111 the bedrock or concrete: failure of the rod, rock failure and failure at the interface rock/grout  
112 or steel grout. The failure mode is frequently a rock failure for cases with minor embedment  
113 depths where the embedment depth is between three and five times the diameter of the bolt  
114 (Ljungberg 2016).

115 According to Gambarova (1981) and Li and Stillborg (1999), adhesion, mechanical interlock,  
116 and friction made up the majority of the interfacial bond strength under the pullout test. Kilic  
117 et al. (2002) concluded that the mechanical properties of the grouting materials, which can  
118 be altered by the water to cement ratio, mixing time, additives, and curing time, are mostly  
119 what determine the bolt capacity. The bolt bearing capacity improves with increasing bolt  
120 diameter and length, which is limited to the ultimate tensile strength of the bolt materials.  
121 Craig and Murnane (2013) tested polyurethane-based resin binders with bolts with the scope  
122 of accelerating ground support activities. Li et al. (2016) observed that the unconfined  
123 compressive strength (UCS) of the grout and bond strength are linearly related. As long as  
124 the bolt shank's yield strain is not excessively high, the bond strength of the rock bolt—that  
125 is, the average shear stress at the bolt-grout interface when the bolt begins to slide along  
126 the interface—seems to rise with embedment length instead of remaining parameters.

127 Chen et al. (2017) observed that the bonding capacity from pull-out tests in the unconfined  
128 situation grew linearly with sample diameter up to 356 mm before remaining constant after  
129 that. The bonding capacity, however, increased linearly with sample diameter up to 300 mm  
130 in confined conditions. After that, it seemed like bonding capability peaked. Additionally, the  
131 bonding capacity was always greater in the restricted setting than it was in the unconfined  
132 one. Similar results were obtained by Moosavi et al. (2002).

133 Li et al. (2017) observed that the pullout strength of a rock bolt is somewhat influenced by  
134 their temperatures. Temperature improves the pullout strength for temperatures between  
135 20°C and 35°C. Temperature causes a decrease in pullout strength at temperatures

136 between 50°C and 70°C. Salcher and Bertuzzi (2018) performed in situ pull-out test in an  
137 Australian sandstone, with a cementitious and resin binder. Cement-grouted bolts  
138 consistently performed in a stiff manner. It was demonstrated that rock bolts cement-grouted  
139 in large diameter shale holes produced the least stiff results as well as the stiffest outcomes.  
140 Shale resin bolts had more constant behavior. In shale, one may use cement-grouted bolts  
141 in holes of a large diameter if a great rigidity is desired. The pull test findings showed no  
142 correlation between bolt performance and resin annulus width. Bajwa et al (2017),  
143 comparing grout and resin binders, observed that in small borehole the cementitious grouted  
144 bolts achieved higher peak pull-out load in comparison with resin-grouted bolts, whereas for  
145 larger boreholes the contrary was true. Aziz et al. (2018) evaluated the shear performance  
146 of various pretensioned fully grouted cable bolts using a novel experimental single shear  
147 testing technique. 19 single shear tests were performed to examine the effects of the bolt  
148 type, surface profile type, pretension load, structure, bonding and debonding, and failure  
149 modes. Comparing plain strand cable bolts to rough surface strand cables, it was discovered  
150 that plain strand cable bolts debonded more easily for the same length of the cable  
151 encapsulated in the host material. Spagnoli et al. (2021) presented promising data about  
152 the mechanical properties of polyurea silicate with a true thixotropic behavior and pull-out  
153 test results on anchors (rebars and hollow). About the half of tests ended up with the failure  
154 of the bar rather than through an interface failure bolt/resin.

155 In this paper, the mechanical behavior of fully grouted passive bolts for the stabilization of  
156 potentially unstable rock blocks on underground cavity walls or surface rock faces is  
157 analyzed in detail. Some simplified equations (Oreste and Spagnoli, 2020) allow to  
158 determine the stabilization forces of the bolt, on the basis of different geometric and  
159 mechanical parameters. Two of these are of great importance because they are able to  
160 describe the bolt-rock interaction in the axial and transverse directions. Unfortunately, these  
161 interaction parameters are difficult to evaluate, even by resorting to specific in situ tests. A

162 detailed analysis through numerical modeling has made it possible to obtain these  
163 parameters with a certain precision. Several cases have been considered, varying the  
164 characteristics of the bolt and the rock, in a typical field of variability that can be encountered  
165 in practice. The developed study allows to define the interaction parameters for different  
166 types of bolt and rock and thus arrive at a quick evaluation of the stabilizing forces of the  
167 bolt, a fundamental step for the design phase.

168

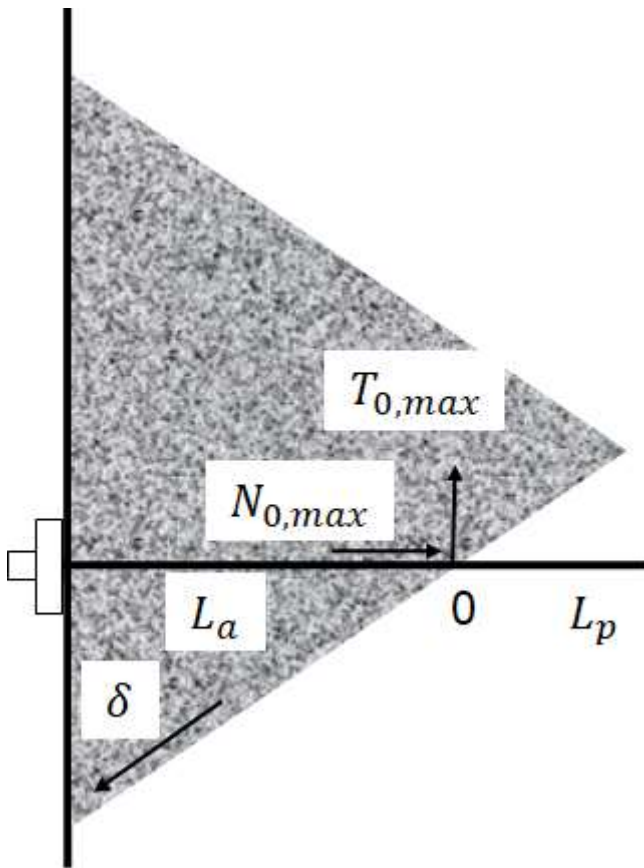
### 169 **Simplified equations and required parameters to analyse the stabilizing contribution** 170 **of a passive bolt to a rock block**

171 The analysis of the interaction between the fully grouted passive bolt and the surrounding  
172 rock, was carried out by Oreste and Cravero (2008), Oreste (2009a; 2009b), Ranjbarnia et  
173 al. (2014), Oreste and Spagnoli (2020). It is possible to identify the stabilizing forces that the  
174 single bolt applies to a potentially unstable block of rock, which tends to move (even with  
175 very small displacement values) along a sliding surface (Fig. 1). This analysis is based on  
176 the assumption that the reaction of the rock to the displacements of the bolt can be  
177 represented with independent springs (Winkler springs), capable of manifesting reaction  
178 forces as a function of the relative displacements of each point of the bolt with respect to the  
179 surrounding rock. The following hypotheses were considered:

- 180 • The bolt (steel bar and binder annulus) is represented by a one-dimensional linear  
181 element, i.e. characterized only by the length and by the axial  $(EA)_{bolt}$  and bending  
182  $(EJ)_{bolt}$  stiffness;
- 183 • Two different zones of the bolt are identified, the crossing zone of the potentially  
184 unstable block  $L_a$  and the anchorage length in the stable rock portion  $L_p$ , beyond the  
185 potentially unstable block; the intersection of the bolt with the internal surface of the  
186 block allows to identify the point 0, which separates the crossing area from the

187 anchoring area and divides the total length of the bolt into two parts of length  $L_a$  and  
188  $L_p$ ;

- 189 • Each point of the bolt is connected to the surrounding rock through two different  
190 Winkler springs, one normal (perpendicular to the bolt) and the other parallel to it; the  
191 first allows to consider the normal reaction of the rock to the transversal  
192 displacements of the bolt, the second the shear reaction to the axial (relative)  
193 displacements on the bolt-rock interface;
- 194 • The displacement of the rock block in the direction of the slip surface deforms the bolt  
195 and activates the reaction of the rock around it, as foreseen by the interaction springs;  
196 as the displacement of the block increases, the stresses along the bolt also increase;
- 197 • Upon reaching the limit operating condition of the bolt, when the approach to failure  
198 of the steel bar or of the connection of the bolt to the surrounding rock occurs, in  
199 correspondence with a certain value of the displacement of the block, the maximum  
200 static contribution offered by the bolt to the block stabilization occurs.



201

202 Fig. 1 Diagram of a potentially unstable block of rock in presence of a fully cemented passive  
 203 bolt. Key:  $L_a$  and  $L_p$  are respectively the lengths of the bolt section that crosses the  
 204 potentially unstable rock block, and of anchorage in the stable rock;  $\delta$  is the displacement  
 205 vector of the block (parallel to the slip surface);  $N_{0,max}$  and  $T_{0,max}$  are the stabilizing forces  
 206 that the bolt applies to the block of rock.

207

208 The maximum stabilization forces offered by the bolt to the potentially unstable block of rock,  
 209 in the limit operating condition, are the forces that must be considered to design of the bolting  
 210 intervention, i.e. to define the number and diameter of the bolts necessary to stabilize a rock  
 211 block. The stabilization forces offered by the single bolt are two, one is directed in the axial  
 212 direction of the bolt ( $N_{0,max}$ ), and the other one ( $T_{0,max}$ ) is directed in a perpendicular  
 213 direction to the bolt, in a plane which includes both the bolt and the displacement vector of  
 214 the block ( $\delta$ ).

215 Oreste and Spagnoli (2020) have identified some simplified equations capable of providing  
 216 the stabilizing forces that a fully cemented passive bolt is able to apply to a potentially  
 217 unstable block of rock. This study is based on an extensive parametric analysis, varying all  
 218 the main input data (geometric and mechanical) that influence the bolt-rock interaction  
 219 problem:

$$220 \quad N_{0,max} = \min \left( \frac{N_{yield}}{F_{s,adm,yield}} \cdot \frac{\xi \cdot (1 + e^{-2\alpha L_a})}{\chi \cdot \tan(\vartheta) + \xi \cdot \eta}; \frac{N_{slip}}{F_{s,adm,slip}} \cdot \frac{\omega}{\alpha} \right) \quad (1)$$

$$221 \quad T_{0,max} = \min \left( \frac{N_{yield}}{F_{s,adm,yield}} \cdot \frac{\rho}{\chi + \frac{\xi}{\tan(\vartheta)} \eta}; \frac{N_{slip}}{F_{s,adm,slip}} \cdot \frac{2 \cdot \tan(\vartheta)}{\lambda \cdot \psi \cdot \alpha} \right) \quad (2)$$

222 Where  $N_{yield}$  is the force causing bar failure under a tensile stress  $N_{yield} = \sigma_{yield} \cdot A_{bar}$ ;  $N_{slip}$   
 223 is the force which causes the bolt-rock interface to fail for a unit bolt length  $N_{slip} = \tau_{lim} \cdot \pi \cdot$   
 224  $\Phi_{hole}$ ;  $(EA)_{bolt}$  is the axial stiffness of the bolt, considering both the steel bar and the binder  
 225 annulus, i.e.  $(EA)_{bolt} = E_{st} \cdot \left( \frac{\pi}{4} \cdot \Phi_{bar}^2 \right) + E_{binder} \cdot \left[ \frac{\pi}{4} \cdot (\Phi_{hole}^2 - \Phi_{bar}^2) \right]$ ;  $(EJ)_{bolt}$  is the  
 226 bending stiffness of the bolt, considering both the steel bar and the binder annulus, i.e.

$$227 \quad (EJ)_{bolt} = E_{st} \cdot \left( \frac{\pi}{64} \cdot \Phi_{bar}^4 \right) + E_{binder} \cdot \left[ \frac{\pi}{64} \cdot (\Phi_{hole}^4 - \Phi_{bar}^4) \right]; \quad \alpha = \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}; \quad \beta = \sqrt[4]{\frac{k \cdot \Phi_{hole}}{4 \cdot (EJ)_{bolt}}};$$

$$228 \quad \lambda = \left[ \frac{(EA)_{bolt} \cdot \alpha}{(EJ)_{bolt} \cdot \beta^3} \right]; \quad \xi = 2 \cdot (EA)_{bolt} \cdot \alpha \cdot \Phi_{bar} \cdot (1 - e^{-2\alpha L_p}); \quad \chi = 16 \cdot \sqrt{2} \cdot (1 + e^{-2\alpha(L_a + L_p)}) \cdot$$

$$229 \quad (EJ)_{bolt} \cdot \beta^2 \cdot e^{-\frac{\pi}{4}}; \quad \eta = \left( e^{-2\alpha L_a} \cdot e^{\alpha \frac{\pi}{4\beta}} + e^{-\alpha \frac{\pi}{4\beta}} \right); \quad \varrho = 4 \cdot (EJ)_{bolt} \cdot \beta^3 \cdot \Phi_{bar} \cdot (1 +$$

$$230 \quad e^{-2\alpha(L_a + L_p)}); \quad \psi = \left[ \frac{(1 + e^{-2\alpha L_a}) \cdot (1 + e^{-2\alpha L_p})}{(1 + e^{-2\alpha(L_a + L_p)})} \right] \text{ and } \omega = \left[ \frac{(1 - e^{-2\alpha L_p})}{(1 + e^{-2\alpha L_p})} \right].$$

231

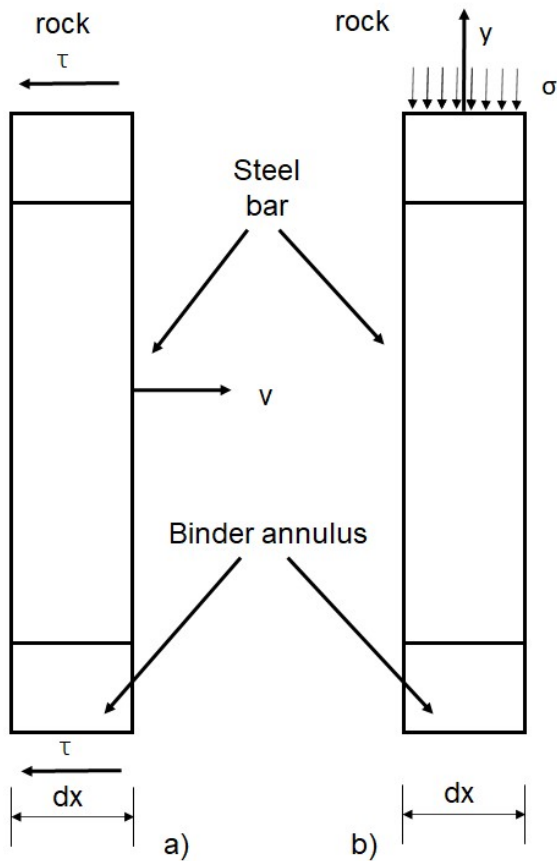
232 Two fundamental parameters condition the values of the stabilization forces  $N_{0,max}$  and  
 233  $T_{0,max}$  (Figure 2), i.e.  $\beta_c$  and  $k$ ; which represent respectively the stiffness of the shear  
 234 interaction springs at the bolt-rock interface and the stiffness of the normal interaction  
 235 springs.

236  $\tau = \beta_c \cdot v$  (3)

237 where  $\tau$  is the shear stress that exists at the rock-bolt interface, and  $v$  is the relative axial  
 238 displacement between the bolt and the surrounding rock.

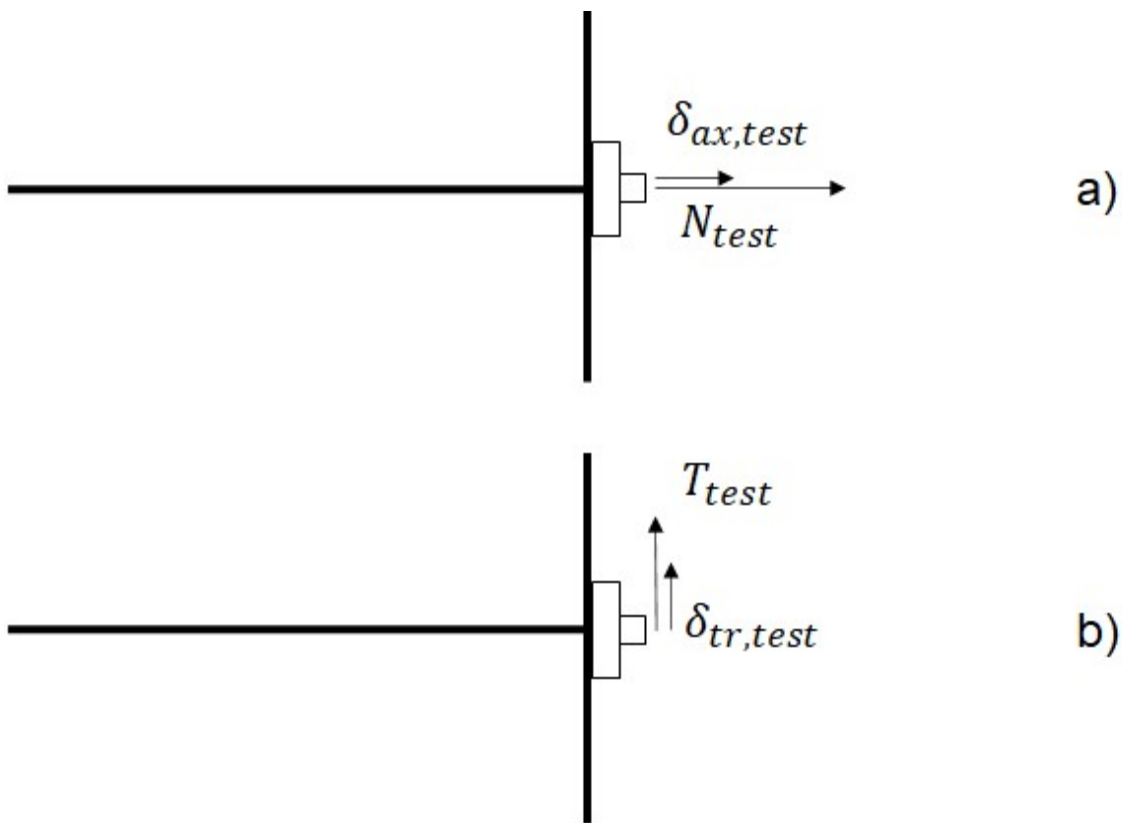
239  $\sigma = k \cdot y$  (4)

240 where  $\sigma$  is the normal (perpendicular) stress applied to the outer surface of the bolt, and  $y$   
 241 is the transverse displacement of the bolt (against the rock) as it undergoes deformation due  
 242 to the movement of the block.



243  
 244 Figure 2. Representation of the stresses applied by the rock ( $\tau$  and  $\sigma$ ) on the external  
 245 surface of an infinitesimal element of a  $dx$  bolt following the relative displacements ( $v$  and  
 246  $y$ ) of the bolt. Key: a) represents the shear interaction; b) represents the normal interaction  
 247 (perpendicular to the bolt);  $\tau$  is the shear stress applied by the rock on the external surface  
 248 of the bolt;  $\sigma$  is normal stress applied by the rock on the external surface of the bolt.

249 Parameters  $\beta_c$  and  $k$  describe the rock response during the bolt deformation. They depend  
 250 on the elastic modulus of the rock, on the geometry of the bolt (diameter of the bar, thickness  
 251 of the binder annulus) and on the elastic modulus of the steel and the binder material. In situ  
 252 tests on test bolts (Figure 3) can help in estimating  $\beta_c$  and  $k$  starting from the applied forces  
 253 and the measurement of the induced displacements, but unfortunately in general there are  
 254 very high forces applied on the bolt head and relatively small displacements. The reduced  
 255 precision and errors in the measurement of the displacements of the bolt head can lead to  
 256 large uncertainties on the two parameters which are fundamental for obtaining a reliable  
 257 estimate of the stabilizing forces  $N_{0,max}$  and  $T_{0,max}$ .



258  
 259 Figure 3. In situ tests on test bolts for the determination of the parameters  $\beta_c$  and  $k$ . Key: a)  
 260 is the pull-out test with application of an axial force to the bolt head; b) is the shear test with  
 261 application of a transversal force to the bolt head;  $N_{test}$  is the applied axial force;  $T_{test}$  is the  
 262 applied transversal force;  $\delta_{ax,test}$  is the measured axial displacement of the bolt head;  $\delta_{tr,test}$   
 263 is the measured transverse displacement of the bolt head.

264 More specifically, from in situ tests it is possible to determine the parameters  $\beta_c$  and  $k$  using  
 265 the following two equations:

$$266 \quad \delta_{ax,test} = \frac{N_{test}}{(EA)_{bolt} \cdot \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}} \cdot \frac{\left( \frac{1+e^{-2 \cdot \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}} \cdot L_{test}}}{1-e^{-2 \cdot \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}} \cdot L_{test}}} \right)}{\left( \frac{1+e^{-2 \cdot \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}} \cdot L_{test}}}{1-e^{-2 \cdot \sqrt{\frac{\beta_c \cdot \pi \cdot \Phi_{hole}}{(EA)_{bolt}}}} \cdot L_{test}}} \right)} \quad (4)$$

$$267 \quad k = \left( \frac{T_{test}}{2 \cdot (EJ)_{bolt} \cdot \delta_{tr,test}} \right)^{\frac{4}{3}} \cdot \frac{4 \cdot (EJ)_{bolt}}{\Phi_{hole}} \quad (5)$$

268 To obtain  $\beta_c$  from equation 4 it is necessary to resort to a numerical solution.

269

## 270 **The analysis of the bolt-rock interaction through numerical modeling**

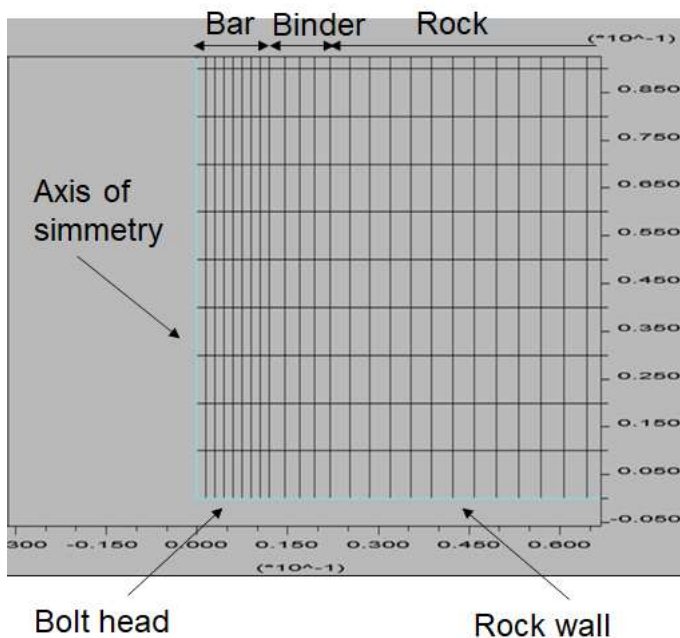
271 It is possible to analyze in detail the complex interaction between the fully cemented passive  
 272 bolt and the surrounding rock thanks to numerical modelling. More specifically, through two-  
 273 dimensional numerical modeling, the axial interaction (in the axisymmetric configuration)  
 274 and the transverse interaction (in a cross section of the bolt) can be simulated.

275 In this work the calculation code FLAC 2D ver 8.1 of the Itasca Company was used. This  
 276 code is able to solve the stress-strain problem through a finite difference solution. In the first  
 277 case, after applying an axial force  $N_{test}$  to the bolt head, the displacement of the bolt head  
 278  $\delta_{ax,test}$  can be determined as a result of the calculation. Based on the pair of values  $N_{test}$ -  
 279  $\delta_{ax,test}$ ,  $\beta_c$  can be determined (equation 4).

280 Figure 4 shows the detail of the numerical model developed to analyze the axial interaction  
 281 of the bolt; in this model, only half of the bolt and the surrounding rock is represented,  
 282 exploiting the axisymmetric symmetry of the problem (vertical y-axis represents the axis of

283 the steel bar). The model allows the study of the axial interaction with great precision and  
284 has the following main characteristics:

- 285 • Total number of elements: 60000
- 286 • Thickness of the rock considered around the bolt: 1.5 m
- 287 • Length of the bolt simulated in the model: 2 m
- 288 • Overall length of the model in the axial direction of the bolt: 4 m
- 289 • Number of elements dedicated to the semi-section of the steel bar: 8
- 290 • Number of elements dedicated to the annular binder: 4



291

292 Figure 4. Detail of the two-dimensional axisymmetric numerical model developed to study the axial  
293 interaction between the bolt and the surrounding rock. Key: the left edge represents the axis of  
294 symmetry of the bolt, the lower one the rock face where the head of the bolt is located; the first 8  
295 elements represent half of the steel bar in the analyzed section, the next 4 the annular binder that  
296 connects the steel bar to the surrounding rock.

297

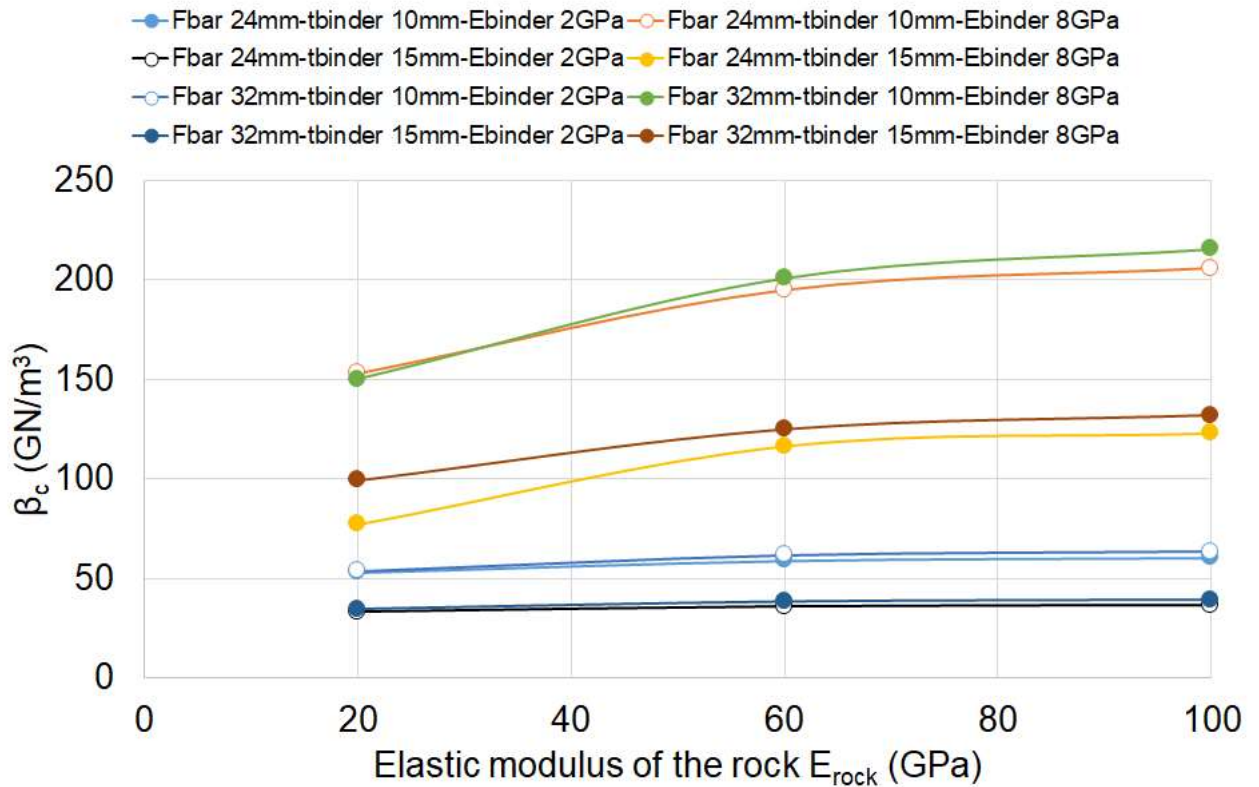
298 Different values of the diameter of the steel bar, of the thickness of the annular binder, of  
299 the elastic models of the rock and of the material that constitutes the annular binder were  
300 analysed:

- 301 • Diameter of the steel bar  $\Phi_{bar}$ : 24 mm and 32 mm
- 302 • Thickness of the annular binder  $t_{binder}$ : 10 mm and 15 mm
- 303 • Elastic modulus of rock  $E_{rock}$ : 20 GPa, 60 GPa, 100 GPa
- 304 • Elastic modulus of the material constituting the annular binder  $E_{binder}$ : 2 GPa and 8  
305 GPa

306

307 The considered cases, 24 in total, allow us to investigate the axial interaction of the bolt for  
308 all possible cases that may arise in reality when passive bolting (fully grouted) is adopted in  
309 rock masses. More specifically, a bar with a small diameter (24 mm) and a large diameter  
310 (32 mm), a reduced (10 mm) and high (15 mm) thickness of the annular binder, a rock with  
311 low (20 GPa), intermediate (60 GPa) and high (100 GPa) mechanical characteristics, a  
312 material constituting the binder having an elastic modulus 2 GPa (resin) and 8 GPa  
313 (traditional cementitious grout) were considered.

314 For each of the 24 cases analyzed it was possible to determine the parameter  $\beta_c$ . Figure 5  
315 shows the graph that allows to synthetically represent the values calculated on the basis of  
316 the results of the numerical modeling.



317

318 Figure 5. Trend of the parameter  $\beta_c$ , which governs the axial interaction of the passive bolt,  
 319 as the elastic modulus of the rock varies, for different combinations of the diameter of the  
 320 bar ( $\Phi_{bar}$ ), the thickness of the binder ( $t_{binder}$ ), the elastic of the material that constitutes  
 321 the binder ( $E_{binder}$ ).

322 From the analysis of Figure 5, the following observations can be made:

- 323 • The diameter of the bar has, in general, a small influence on the axial interaction  
 324 parameter  $\beta_c$ , with the sole exception of the case of weak rock, high thickness of the  
 325 annular binder and bar-rock connection with traditional cementitious grout (in this case  
 326  $\beta_c$  increases by about 30% when going from a small (24 mm) to a large (32 mm) bar  
 327 diameter. In the case of using the resin as a bolt-rock connection material, the stiffness  
 328 of the rock has no effect on the axial interaction parameter  $\beta_c$

- 329 • The thickness  $t_{binder}$  of the annular binder has an important effect on the interaction  
 330 parameter  $\beta_c$ : as it decreases from 15 mm to 10 mm,  $\beta_c$  increases considerably by 60-  
 331 65%, mostly with the use of traditional cementitious grout
- 332 • With the use of traditional cementitious grout ( $E_{binder}=8$  GPa) there are no significant  
 333 increases in  $\beta_c$  for values of the elastic modulus of the rock  $E_{rock}$  above 60 GPa; for  
 334 lower values of the elastic modulus of the rock ( $E_{rock}=20\div 60$  GPa)  $\beta_c$  grows considerably  
 335 with  $E_{rock}$ .

336 The results, therefore, can be summarized as follows. In the case of using resins for the bar-  
 337 rock connection,  $\beta_c$  essentially depends on the thickness  $t_{binder}$ :

$$338 \quad \beta_c \cong 103.3 - 4.48 \cdot t_{binder} \quad (\text{with } \beta_c \text{ expressed in GN/m}^3 \text{ and } t_{binder} \text{ in mm}) \quad (6)$$

339 In the case of using traditional cementitious grout,  $\beta_c$  depends on both  $E_{rock}$  and  $t_{binder}$ :

$$340 \quad \beta_c \cong (277.5 - 15 \cdot t_{binder}) + 1.125 \cdot E_{rock} \quad (\text{with } \beta_c \text{ expressed in GN/m}^3, \quad t_{binder} \text{ in mm and}$$

$$341 \quad E_{rock} \text{ in GPa, for } E_{rock} \leq 60 \text{ GPa}) \quad (7)$$

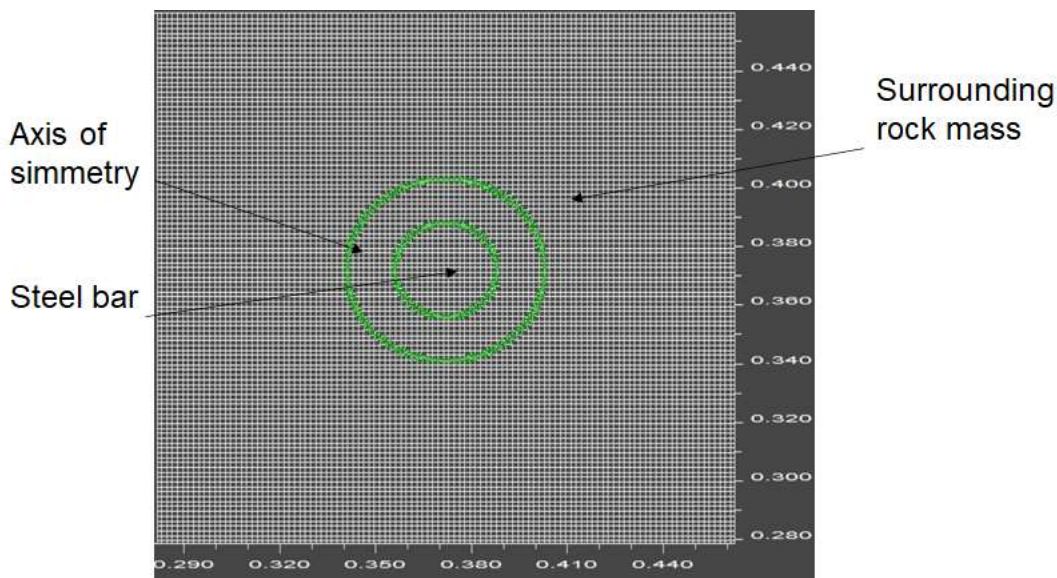
342 In the latter equation (for traditional cementitious grout), in the only case of weak rock  
 343 ( $E_{rock} \leq 20$  GPa) and high thickness of the annular binder ( $t_{binder}=15$  mm),  $\beta_c$  must be  
 344 increased by 15% when considering a intermediate diameter steel bar (28 mm) and 30% for  
 345 large diameter bar (32 mm). Furthermore, for  $E_{rock}$  greater than 60 GPa (rock with high  
 346 mechanical characteristics), the values of  $\beta_c$  calculated for  $E_{rock}=60$  GPa can be adopted  
 347 without making significant errors.

348 As regards the transverse interaction, a two-dimensional numerical model of the cross  
 349 section of the bolt has been developed; after applying a shear force  $T_{test}$  to the bolt (at the  
 350 center of the steel bar), the displacement of the bar axis  $\delta_{tr,test}$  was calculated. The pairs of  
 351 values  $T_{test}-\delta_{tr,test}$  then allow to determine the interaction parameter k (equation 5).

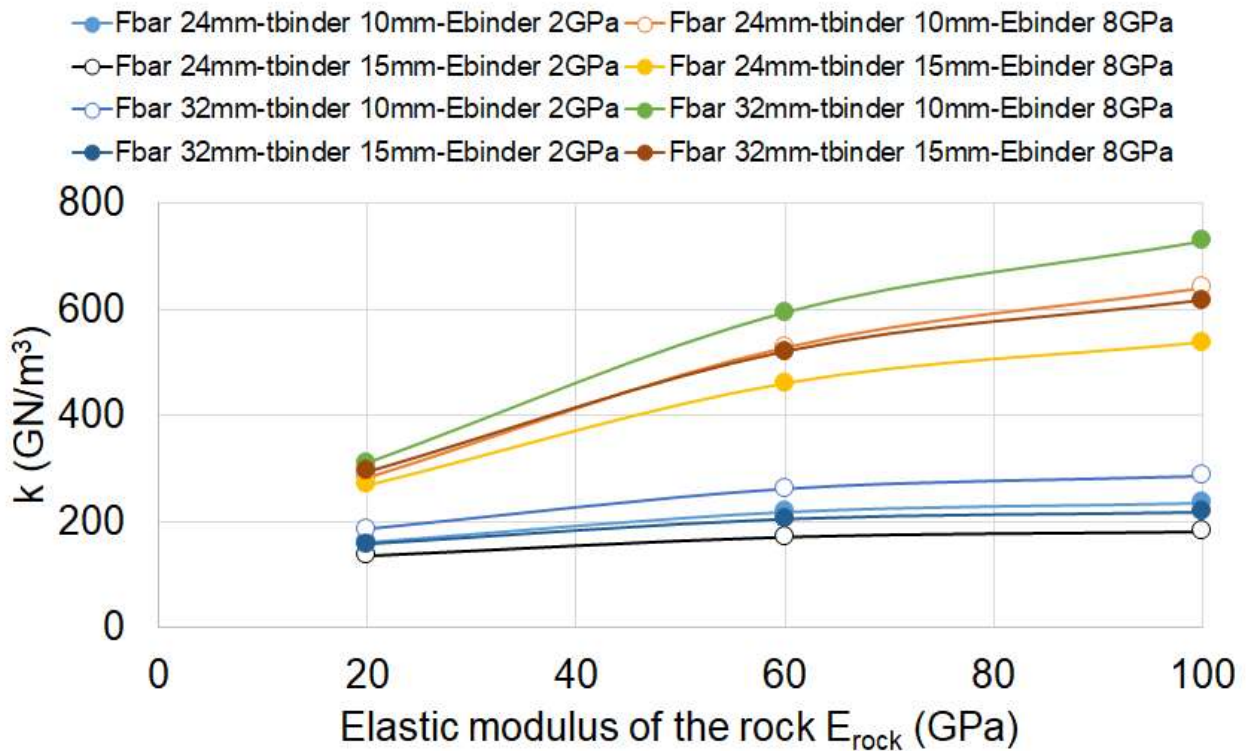
352 Figure 6 shows the detail of the numerical model used, which considers the entire cross  
353 section of the bolt and the surrounding rock. It is able to analyze in great detail the  
354 transversal interaction of the bolt and has the following main characteristics:

- 355 • Total number of elements: 200000
- 356 • Thickness of the rock considered around the bolt: 0.5 m
- 357 • Average dimension of each numeric element: 1.5 mm x 1.5 mm; 14/19 numerical  
358 elements were used to simulate the steel bar along its diameter ( $\Phi_{bar}=24/32$  mm);  
359 6/9 numerical elements have been used to represent the binder annulus along its  
360 thickness ( $t_{binder}=10/15$  mm)

361 The same 24 cases considered in the analysis of the axial interaction were analyzed also in  
362 the transversal one, by varying the diameter of the bar, the thickness of the binder around  
363 it, the elastic modulus of the rock and the elastic modulus of the binder. The obtained results  
364 of the numerical calculation have been summarized in Figure 7.



366 Figure 6. Detail of the two-dimensional transversal numerical model developed to study the  
367 transversal interaction between the bolt and the surrounding rock. The average size of the  
368 numerical elements used is 1.5 mm x 1.5 mm.



369

370 Figure 7. Trend of the parameter  $k$ , which governs the transversal interaction of the passive  
 371 bolt, as the elastic modulus of the rock varies, for different combinations of the diameter of  
 372 the bar ( $\Phi_{bar}$ ), the thickness of the binder ( $t_{binder}$ ), the elastic of the material that constitutes  
 373 the binder ( $E_{binder}$ ).

374 From the analysis of Figure 7, the following comments can be made:

- 375 • The parameter  $k$  tends to grow with  $E_{rock}$  according to a parabolic trend (the influence of  
 376  $E_{rock}$  is greater for traditional cementitious grout,  $E_{binder}=8$  GPa, less for resins,  $E_{binder}=2$   
 377 GPa)
- 378 • The values of  $k$  are 2÷3 times greater when the binder is made up of traditional  
 379 cementitious grout compared to the case of a binder made up of resins
- 380 •  $k$  tends to increase as the diameter of the bar increases and the thickness of the binder  
 381 decreases
- 382 • the influence of  $\Phi_{bar}$  and  $t_{binder}$  on  $k$  depends on the rock's elastic modulus  $E_{rock}$ : it is  
 383 smaller for low  $E_{rock}$ , it increases for high  $E_{rock}$

384 For each type of binder (traditional cementitious grout or resin), thickness of the binder  
385 annulus (10 or 15 mm) and diameter of the bar (24 or 32 mm) considered, it was possible  
386 to obtain the equations of the parabola which best describes the results of the numerical  
387 calculation in terms of  $k$  (GN/m<sup>3</sup>) as the elastic modulus of the rock  $E_{rock}$  (GPa) varies:

388 binder made of traditional cementitious grout:

389  $\Phi_{bar}=24$  mm;  $t_{binder}=10$  mm:  $k \cong -0.04156 \cdot E_{rock}^2 + 9.450 \cdot E_{rock} + 111.625$  (8)

390  $\Phi_{bar}=24$  mm;  $t_{binder}=15$  mm:  $k \cong -0.03594 \cdot E_{rock}^2 + 7.675 \cdot E_{rock} + 129.875$  (9)

391  $\Phi_{bar}=32$  mm;  $t_{binder}=10$  mm:  $k \cong -0.04688 \cdot E_{rock}^2 + 10.875 \cdot E_{rock} + 111.250$  (10)

392  $\Phi_{bar}=32$  mm;  $t_{binder}=15$  mm:  $k \cong -0.04063 \cdot E_{rock}^2 + 8.900 \cdot E_{rock} + 133.250$  (11)

393

394 binder made of resin:

395  $\Phi_{bar}=24$  mm;  $t_{binder}=10$  mm:  $k \cong -0.01281 \cdot E_{rock}^2 + 2.475 \cdot E_{rock} + 116.625$  (12)

396  $\Phi_{bar}=24$  mm;  $t_{binder}=15$  mm:  $k \cong -0.00813 \cdot E_{rock}^2 + 1.550 \cdot E_{rock} + 108.250$  (13)

397  $\Phi_{bar}=32$  mm;  $t_{binder}=10$  mm:  $k \cong -0.01625 \cdot E_{rock}^2 + 3.200 \cdot E_{rock} + 128.500$  (14)

398  $\Phi_{bar}=32$  mm;  $t_{binder}=15$  mm:  $k \cong -0.01094 \cdot E_{rock}^2 + 2.075 \cdot E_{rock} + 120.875$  (15)

399

400 **Estimation of the stabilization forces produced by the passive bolt on the basis of the**  
401 **mechanical parameters of the bolt-rock interaction**

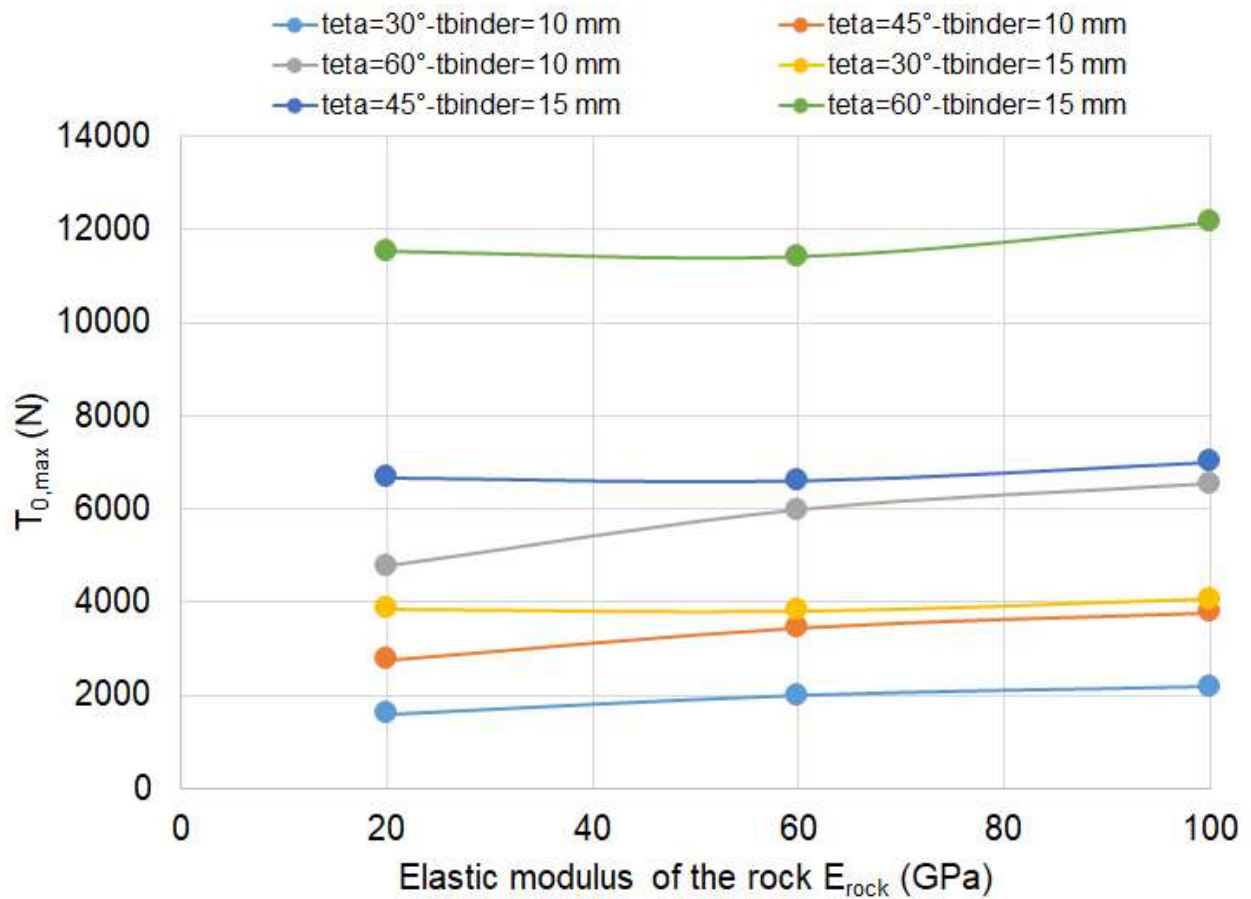
402 Thanks to the results obtained from the numerical modeling and the determination of the  
403 mechanical parameters of bolt-rock interaction in the axial ( $\beta_c$ ) and transversal ( $k$ ) direction,  
404 it is possible to proceed to the estimation of the stabilization forces on the basis of equations  
405 1 and 2 (Oreste and Spagnoli, 2020). More specifically, it is possible to have a reliable

406 estimate of the stabilization force acting in the axial direction ( $N_{0,max}$ ) and transversal  
407 upwards ( $T_{0,max}$ ), acting perpendicularly to the bolt with a vector belonging to the plane  
408 encompassing the bolt itself and the block displacement vector  $\delta$  (Fig. 1).

409 The following Figures (8-13) show the values of  $T_{0,max}$  and  $N_{0,max}$  as the elastic modulus of  
410 the rock  $E_{rock}$  varies, for traditional cementitious grout, ( $E_{binder}=8000$  MPa) and resin  
411 ( $E_{binder}=2000$  MPa), in the cases of steel bar with diameter  $\Phi_{bar}$  20 and 32 mm and  
412 thickness of the binder annulus  $t_{binder}$  of 10 and 15 mm. These graphs assume a fundamental  
413 design role, allowing the correct design of the fully grouted passive bolts in the different  
414 conditions that can be encountered in engineering practice, guaranteeing the stabilization  
415 of the potentially unstable blocks of rock, quickly defining the characteristics and the number  
416 of bolts that are necessary.

417 These graphs were obtained assuming the following parameters present in equations 1 and  
418 2:

- 419 • Length of the bolt in the two areas  $L_a$  (block crossing area) and  $L_p$  (anchor length in  
420 the stable rock behind the block): 2 m
- 421 • Elastic modulus of steel  $E_{steel}$ : 210 GPa
- 422 • Limit shear stress  $\tau_{lim}$  at the bolt-rock interface: 2.5 MPa
- 423 • Steel yield strength  $\sigma_y$ : 450 MPa
- 424 • Safety factors considered as minimum admissible against yield failure of the steel bar  
425 ( $F_{s,adm,yield}$ ) and pullout failure at the bolt-rock interface ( $F_{s,adm,slip}$ ): 1.3.



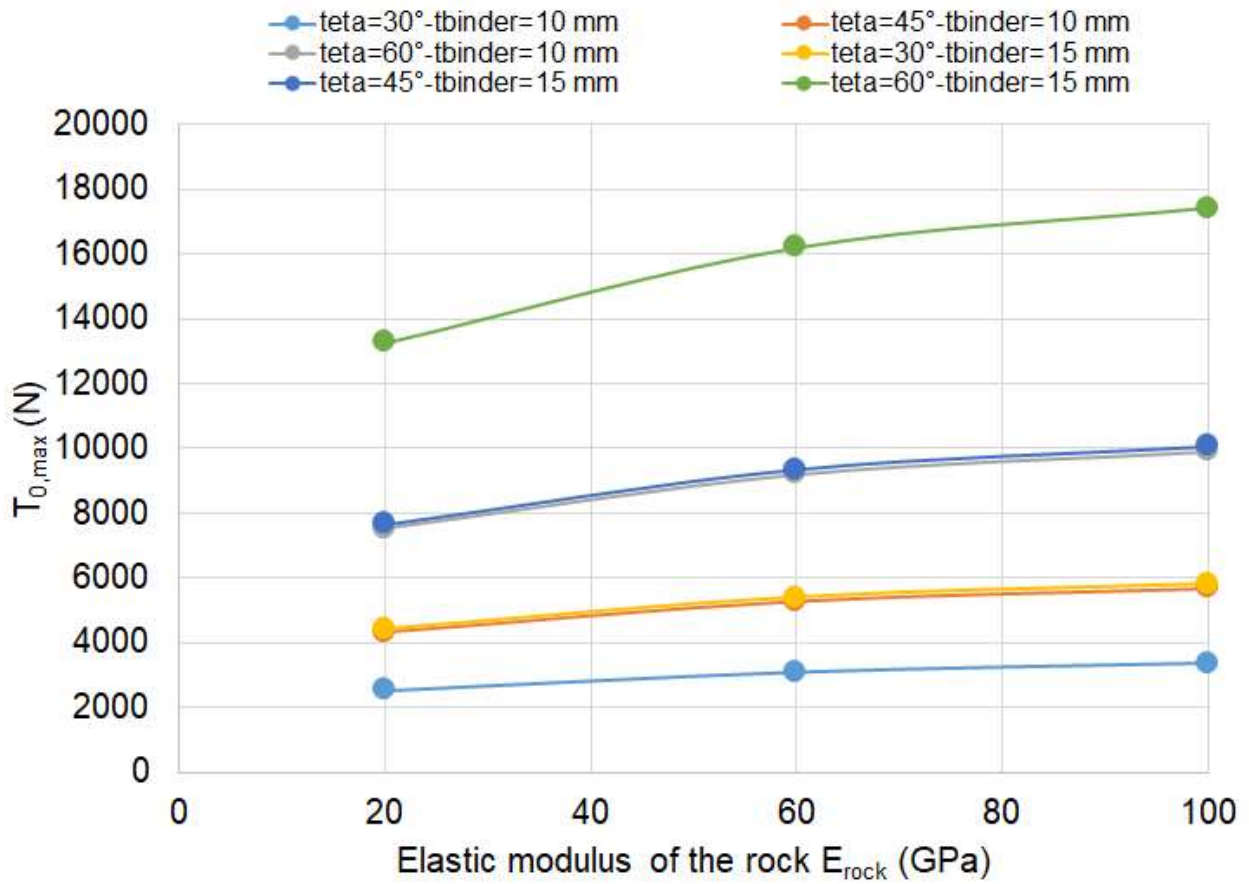
426

427 Figure 8. Trend of the transversal stabilization force  $T_{0,max}$ , as the elastic modulus of the  
 428 rock  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ )  
 429 and of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of  
 430 the bolt axis. Case of a traditional cementitious binder ( $E_{binder}=8$  GPa) and diameter of the  
 431 bar  $\Phi_{bar}=24$  mm.

432

433

434

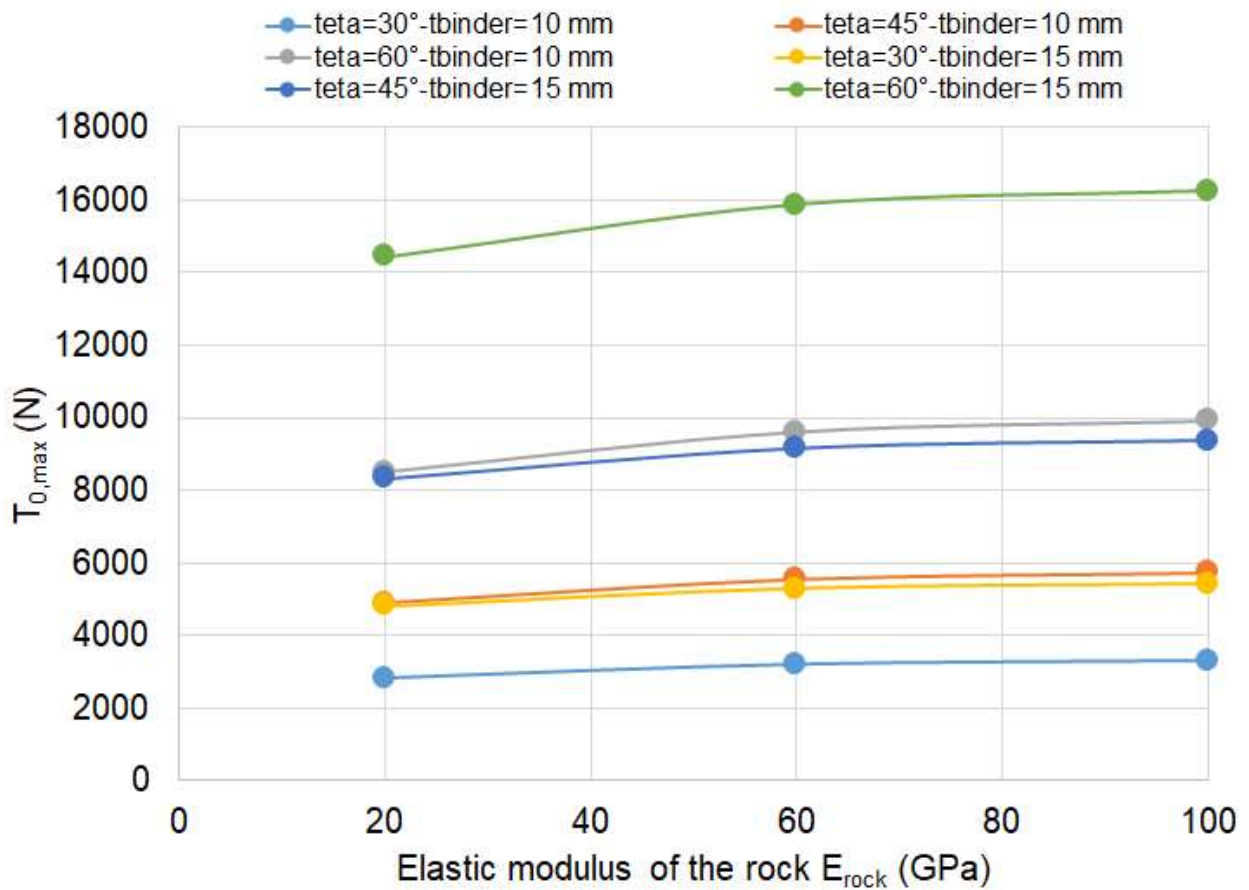


435

436 Figure 9. Trend of the transversal stabilization force  $T_{0,max}$ , as the elastic modulus of the  
 437 rock  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ )  
 438 and of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of  
 439 the bolt axis. Case of a traditional cementitious binder ( $E_{binder}=8$  GPa) and diameter of the  
 440 bar  $\Phi_{bar}=32$  mm.

441

442



443

444 Figure 10. Trend of the transversal stabilization force  $T_{0,max}$ , as the elastic modulus of the  
 445 rock  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ )  
 446 and of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of  
 447 the bolt axis. Case of a resin binder ( $E_{binder}=8$  GPa) and diameter of the bar  $\Phi_{bar}=24$  mm.

448

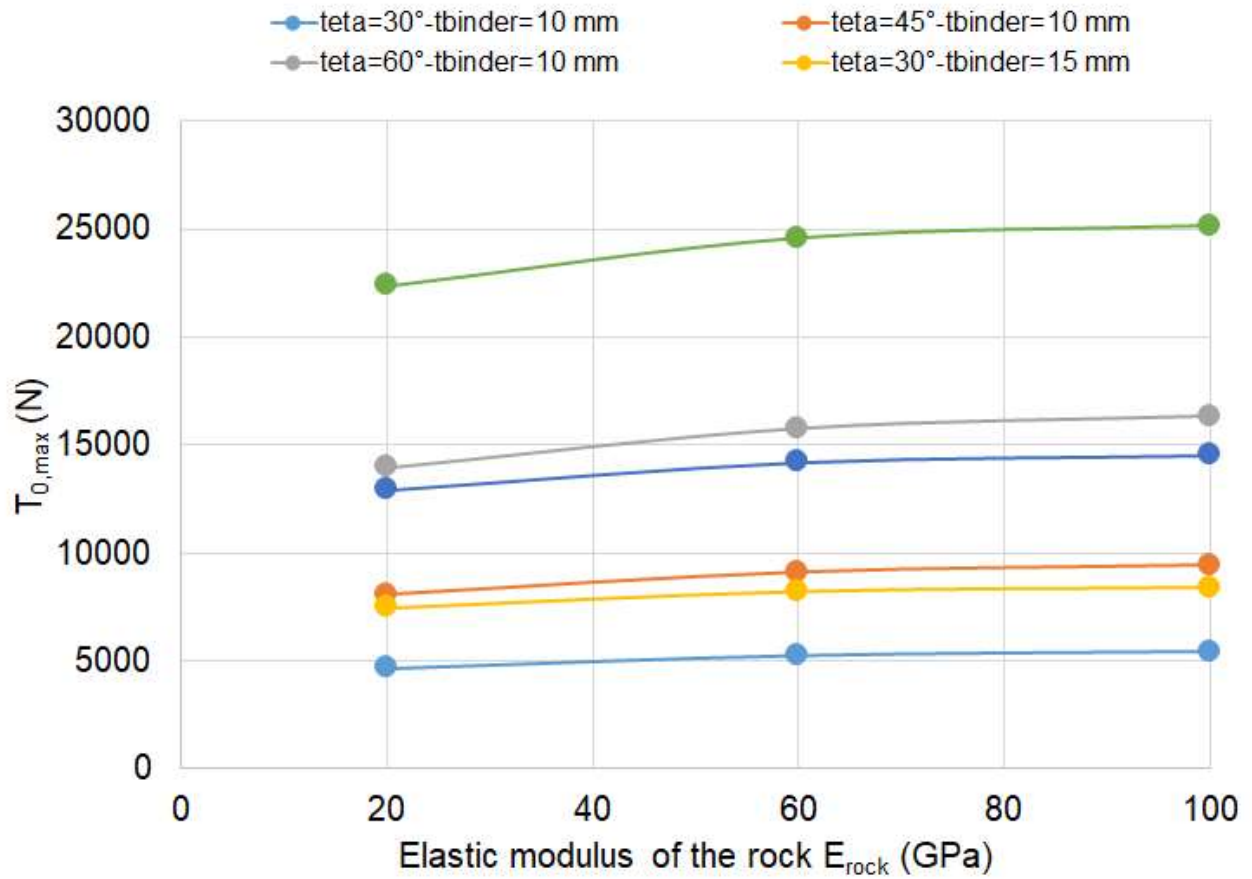
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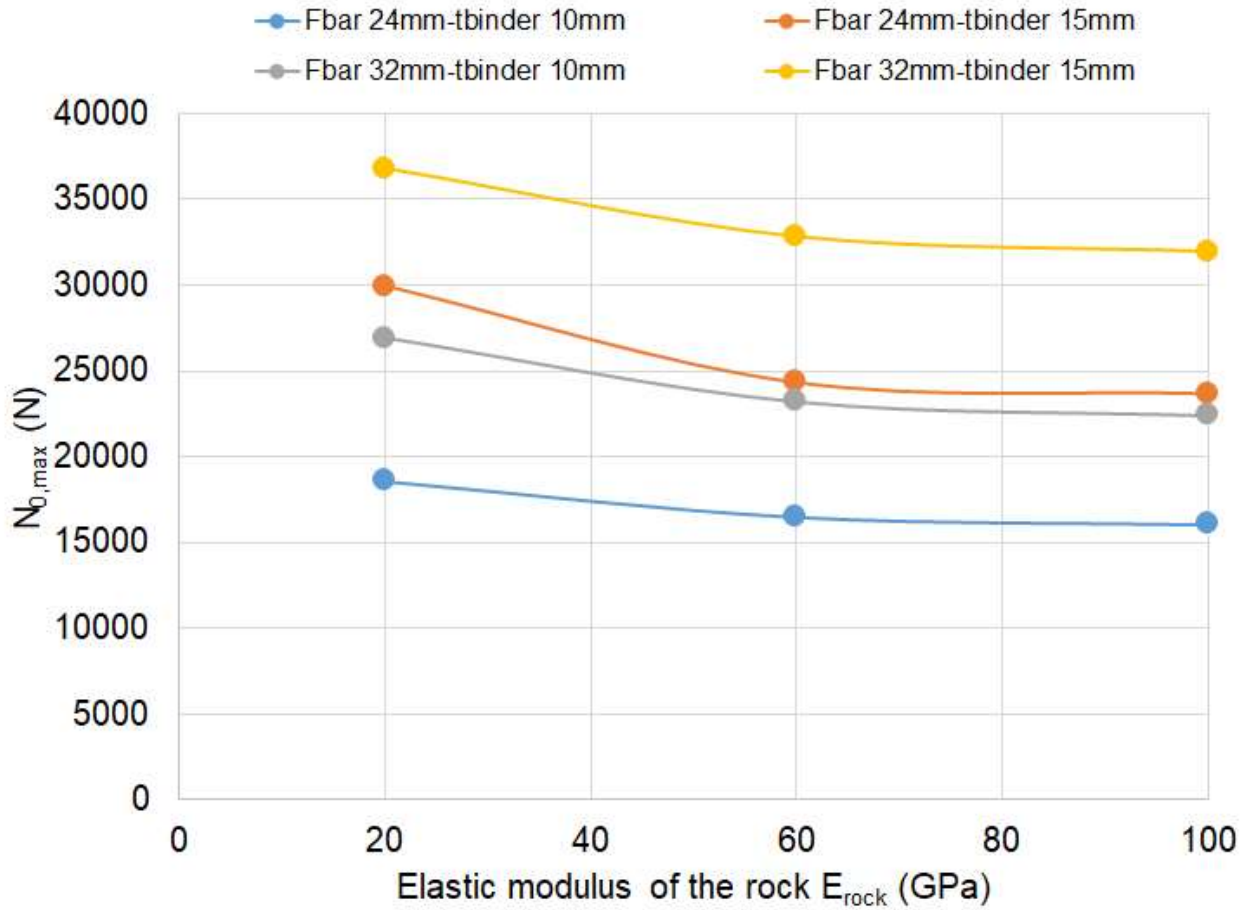
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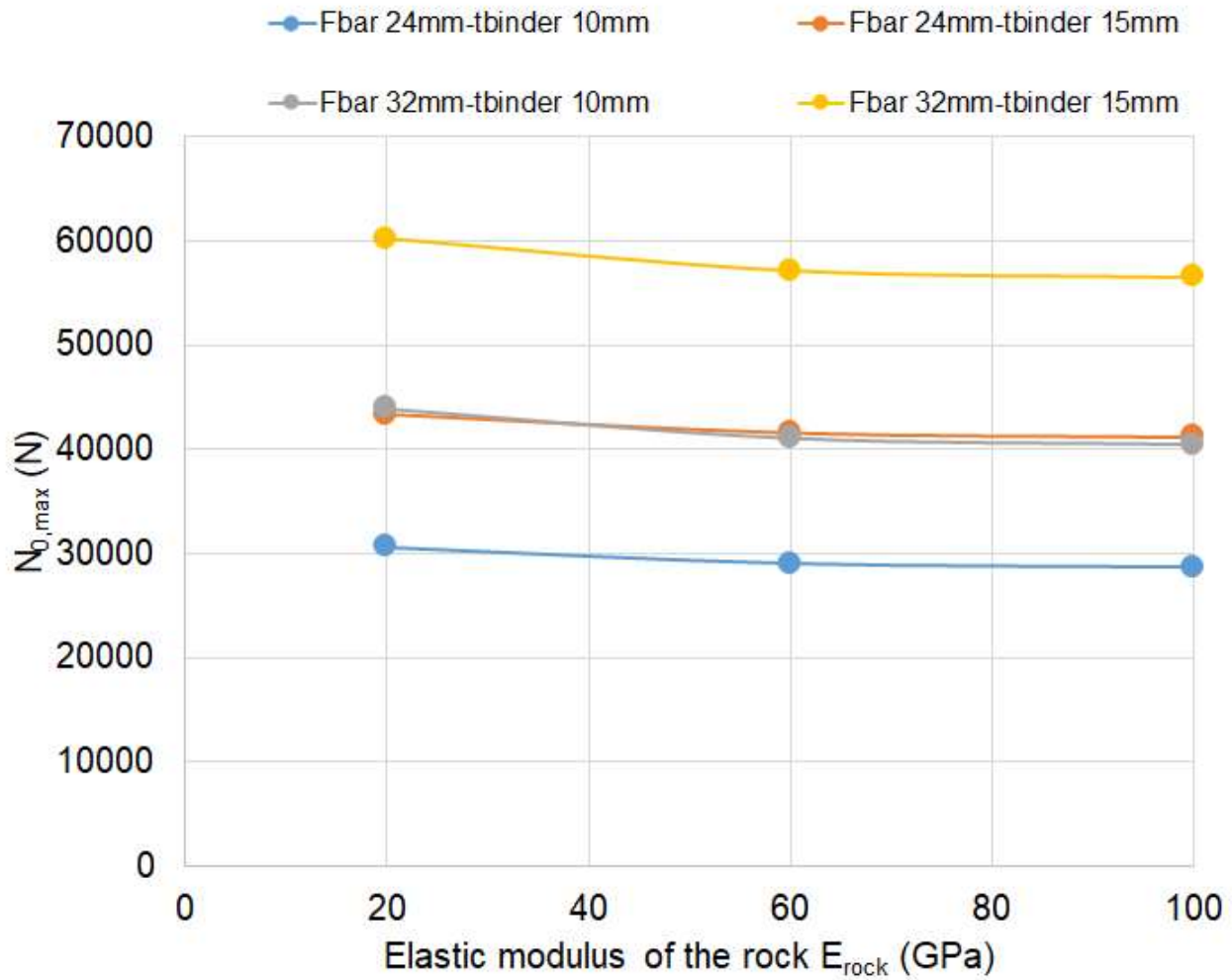
455 Figure 11. Trend of the transversal stabilization force  $T_{0,max}$ , as the elastic modulus of the  
 456 rock  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ )  
 457 and of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of  
 458 the bolt axis. Case of a resin binder ( $E_{binder}=8$  GPa) and diameter of the bar  $\Phi_{bar}=32$  mm.

459



460

461 Figure 12. Trend of the axial stabilization force  $N_{0,max}$ , as the elastic modulus of the rock  
 462  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ ) and  
 463 of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of the  
 464 bolt axis. Case of a traditional cementitious grout ( $E_{binder}=8$  GPa).



465

466 Figure 13. Trend of the axial stabilization force  $N_{0,max}$ , as the elastic modulus of the rock  
 467  $E_{rock}$  varies, for different combinations of the thickness of the binder annulus ( $t_{binder}$ ) and  
 468 of the angle  $\vartheta$  which forms the displacement vector of the block  $\delta$  with the direction of the  
 469 bolt axis. Case of a resin binder ( $E_{binder}=2$  GPa).

470

471 From an examination of the figures, it can be seen that:

- 472 • The elastic modulus of the rock  $E_{rock}$  does not always have a significant influence on  
 473 the value of the force  $N_{0,max}$
- 474 • the angle  $\vartheta$ , the thickness of the binder annulus, the diameter of the bar and the type  
 475 of binder used, greatly influence the value of the force  $N_{0,max}$

- 476 • as the rock's elastic modulus  $E_{rock}$  increases, the stabilization force  $N_{0,max}$  tends to  
477 decrease; this reduction is more evident when traditional cementitious grout is used  
478 as binder material
- 479 • the angle  $\vartheta$  has no effect on  $N_{0,max}$ , whose value, however, is influenced by the  
480 diameter of the bar, the thickness of the binder annulus and above all by the type of  
481 binder material used (traditional cementitious grout or resin)

482 The same graphs shown in this paragraph can be used for different values of the diameter  
483 of the bar, thickness of the binder annulus, angle  $\vartheta$  and elastic modulus of the rock: in these  
484 cases, linear interpolation can be used to estimate the stabilization forces for values different  
485 from those considered in the study, without committing significant errors. If, for example, it  
486 is necessary to determine the stabilization force  $T_{0,max}$  in the case of a bar diameter  $\Phi_{bar}$  of  
487 28 mm, thickness of the binder annulus  $t_{binder}$  of 13 mm, angle  $\vartheta$  of  $50^\circ$  and  $E_{rock}=50$  GPa,  
488 adopting the traditional cementitious grout, the following values of  $T_{0,max}$  can be obtained  
489 from Figures 8 and 9:

490

491  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =45^\circ; E_{rock}=20 \text{ GPa}) =2759 \text{ N}$

492  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =45^\circ; E_{rock}=60 \text{ GPa}) =3452 \text{ N}$

493 from which we have by interpolation:

494  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =45^\circ; E_{rock}=50 \text{ GPa}) =3278 \text{ N}$

495

496  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =60^\circ; E_{rock}=20 \text{ GPa}) =4778 \text{ N}$

497  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =60^\circ; E_{rock}=60 \text{ GPa}) =5978 \text{ N}$

498 from which we have by interpolation:

499  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =60^\circ; E_{rock}=50 \text{ GPa}) =5678 \text{ N}$

500

501 and then again by interpolation:

502  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =4078 \text{ N}$

503

504 Proceeding in the same way for  $\Phi_{bar}=32 \text{ mm}$  and  $t_{binder}=10 \text{ mm}$  we have:

505  $T_{0,max} (\Phi_{bar}=32 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =6286 \text{ N}$

506

507 For  $\Phi_{bar}=24 \text{ mm}$  and  $t_{binder}=15 \text{ mm}$  we obtain:

508  $T_{0,max} (\Phi_{bar}=24 \text{ mm}; t_{binder}=15 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =8231 \text{ N}$

509

510 For  $\Phi_{bar}=32 \text{ mm}$  and  $t_{binder}=15 \text{ mm}$  we obtain:

511  $T_{0,max} (\Phi_{bar}=32 \text{ mm}; t_{binder}=15 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =11109 \text{ N}$

512

513 And, therefore, by interpolating the last 4 values of  $T_{0,max}$  in pairs, we have:

514  $T_{0,max} (\Phi_{bar}=28 \text{ mm}; t_{binder}=10 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =5182 \text{ N}$

515  $T_{0,max} (\Phi_{bar}=28 \text{ mm}; t_{binder}=15 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =9670 \text{ N}$

516

517 And finally:

518  $T_{0,max} (\Phi_{bar}=28 \text{ mm}; t_{binder}=13 \text{ mm}; \vartheta =50^\circ; E_{rock}=50 \text{ GPa}) =7875 \text{ N}$

519

## 520 **Conclusions**

521 Fully grouted passive bolts take load when the block of rock tends to move, sliding along  
522 one or more surfaces formed by the natural discontinuities of the rock. The bolt is able to  
523 apply two stabilizing forces to the block: an axial force and a transversal one, perpendicular  
524 to the axis of the bolt, with vector belonging to the same plane of the bolt itself and the  
525 displacement vector of the rock block. In this paper it was possible to provide simplified  
526 equations able to determine the two stabilizing forces of the passive bolt.

- 527 • These equations require the determination of the two fundamental mechanical  
528 parameters governing the bolt-rock interaction: the shear interaction parameter  $\beta_c$  at  
529 the bolt-rock interface and the normal interaction parameter  $k$  at the same interface.
- 530 • The interaction parameters are difficult to determine through specific in situ tests.
- 531 • For this reason, an accurate analysis through numerical modeling is necessary. Two  
532 different highly detailed numerical models have been developed, one for the study of  
533 the shear interaction and the other for the normal interaction between the bolt and  
534 the rock.
- 535 • Numerous cases were considered, varying the diameter of the steel bar, the  
536 thickness of the binder annulus, the mechanical characteristics of the rock and of the  
537 binder material.
- 538 • The parametric analysis was developed considering fields of variability of each  
539 geometric and mechanical parameter, typical of the real cases that can be  
540 encountered.
- 541 • From the study it was possible to identify the interaction parameters for all the cases  
542 analyzed and also to define equations that are able to estimate them when the main  
543 geometric and mechanical parameters that characterize the functioning of fully  
544 grouted passive bolts vary.

- 545       • Thanks to the knowledge of these parameters, it has been possible to directly  
546       evaluate the stabilization forces of the single bolt and develop diagrams that allow  
547       their determination as the diameter of the steel bars, the thickness of the binder  
548       annulus, the mechanical characteristics of the rock and the binder vary material  
549       (either cementitious grout or resin).
- 550       • These diagrams are a useful tool to allow an accurate design of such interventions in  
551       the stabilization of potentially unstable blocks of rock.

## 552 **Conflict of interests**

553 Authors declare they have no conflict of interest.

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