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Guidelines for Implementing Control Flow Checking into Automotive Embedded Applications Developed with C Language

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Abstract—Embedded systems, such as automotive applications, are increasingly used in safety-critical systems. The correct and reliable implementation of such systems depends on many factors, including the design of the system hardware, software, fault-tolerance mechanisms, and the choice of programming language, followed by the test, verification, and validation techniques employed. Even well-designed systems are not exempt from having defects that stem from their physical properties, and these imperfections can cause unforeseen and dangerous actions in safety critical systems. This paper focuses on isolating or mitigating the effects of Random Hardware Failures (RHF). Hardening strategies are employed to mitigate RHF in embedded systems, either by adding specialized hardware or using Software-Implemented Hardware Fault Tolerance (SIHFT) methods. SIHFT methods are applied to various applications to harden them against Control Flow Errors (CFEs). This paper presents a guideline for applying a subset of SIHFT methods called Control Flow Checking (CFC) methods to application code written in C language. The motivation is that in the literature few guidelines can be found that provide insight on implementing CFC methods with high-level programming languages. Most proposals implement CFC methods in low-level languages such as assembly. The rationale behind developing high-level language implementations lies in the pursuit of architecture independence as well as the inadequacy of a certified compiler for the target platform that can conveniently incorporate Certified Functionally Correct into the compiled assembly/machine language code.

Index Terms—control flow checking, automotive applications, software reliability

I. INTRODUCTION

Embedded systems are becoming increasingly common in a variety of industries. These systems must be reliable and safe. These characteristics of the system depend on both system hardware and software. Several techniques can be applied to improve reliability and safety, including hardware and software redundancy to harden systems. Hardening the system generally means adding redundancy. It can be implemented in two ways: (i) adding extra hardware components or (ii) adding software instructions in the application code. Hardware redundancy requires replicated hardware modules or custom hardware with fault detection mechanisms. Software redundancy, on the other hand, executes additional instructions without modifying any

hardware components and allows tracking the proper execution of the application. In addition, software redundancy techniques are much more adaptable and economical solutions for error detection.

Software-Implemented Hardware Fault Tolerance (SIHFT) methods are more flexible and cost-effective as they do not require adding any special hardware components, because they exploit what is already available in common Commercial Off The Shelf (COTS) products. They add extra code to the application to monitor its correct execution.

Among various SIHFT methods, this paper focuses on Control Flow Checking (CFC) methods [3-12]. CFC methods check the application's control flow to ensure it is executing correctly.

Implementing CFC methods can be challenging, and their effectiveness needs to be assessed. The literature on CFC methods provides most examples written in Assembly language. This is usually considered the most suitable strategy since compilers can automatically add the hardening method instructions to the application. However, for some embedded applications, using Assembly language is not the preferred development flow, since functional safety standards (part 6 of ISO 26262 Standard [1]) mandate the use of high-level programming languages such as C whenever possible as well as, use of certified compilers. Moreover, the automotive industry production chains are typically complex because different companies develop software components that are then integrated into the system, especially within the AUTOSAR framework. This leads to the need to guarantee a minimum acceptable hardening level regardless of the platform chosen to run the integrated products.

This paper presents a set of guidelines for implementing CFC methods using C programming language. We evaluate the effectiveness of the proposed approach in two case studies. Our results show that our approach regarding the implementation of the CFC in C language is maintaining the effectiveness of the CFC method in detecting RHF in the embedded systems. Hence, our approach is a viable alternative to implementing traditional hardening techniques.

This work is organized as follows: Section II discusses the significance of C in the automotive industry as well as provides

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Graphic representation	Explanation
	Statement/statements to be added to perform a test/set operation needed by the CFC technique. (Regardless of the color).
	A basic block of the algorithm to be hardened. (Regardless of the color).
	A legal transition between two basic blocks.
	Function call. (Regardless of the color).
	A body of statements inside a basic block to indicate if the statement of CFC algorithm has to be put before or after it.
	Horizontal bars indicate borders between basic blocks (regardless of the color).

Fig. 1: Instructions on how to read the Control Flow Graphs represented in this paper.

application. However, RACFED extends this functionality by inserting gradual signature updates after each instruction inside the Run Time Signature (RTS) variable. To understand this guideline, Figure 1 explains how to read Control Flow Graphs. The control graph is a visual representation of the control flow of a program. The nodes in the graph represent the statements in the program, and the edges represent the control flow between the statements.

A. Functions or macros needed in C language

The YACCA and RACFED algorithms use different methods for performing the TEST and SET operations, with algorithm 1 used for TEST in YACCA and algorithm 2 used for RACFED, and algorithm 3 used for SET in YACCA and algorithm 4 used for RACFED. In RACFED, the Run Time Signature (RTS) is updated after each basic block statement by summing a random number, and the total of these random numbers is subtracted before signature checking to allow for intra-block detection capabilities. The SET operation is conducted in two phases within the actual algorithm. To optimize YACCA, the predecessor's mask is retrieved from the last TEST call in the implementation, as TEST always occurs before SET. For more details on CFC methods, see [13], which provides implementation examples.

Algorithm 1 TEST operation (YACCA)

- 1: **TEST**(RTS, predecessors_mask)
- 2: **if** $RTS \wedge (\neg predecessors_mask)$ **then**
| **CFE detected**
 end
- 3: Continue normal execution

B. Switch-case construct

For a switch-case construct, Figure 2 shows the positions of the TEST and SET statements for the entry BB which is indicated with the `switch(...)` statement. Meanwhile, Figure 3 shows the positions of the TEST and SET statements for the exit BB which is indicated with a `}` character.

Algorithm 2 TEST operation (RACFED). bb represents the ID of the BB which is calling TEST(). RTS is an array containing the compile-time signature of every BB.

- 1: **TEST**(bb)
- 2: **if** $RTS \neq CTS[bb]$ **then**
| **CFE detected**
 end
- 3: Continue normal execution

Algorithm 3 Set operation (YACCA)

- 1: **SET**(RTS, predecessors_mask, BB_ID)
- 2: $RTS = RTS \wedge \neg predecessors_mask$
- 3: $RTS = RTS \vee (1 \ll BB_ID)$

It is important to note that in cases where there is no default case for the entry BB, its inclusion is necessary. We address this by adding a default case to the original algorithm used in implementing the CFC. Lastly, an optimized diagnostic coverage for exit BB can be achieved by testing the signature of its only legal predecessors for each switch case. This is due to the presence of diverse paths in this construct.

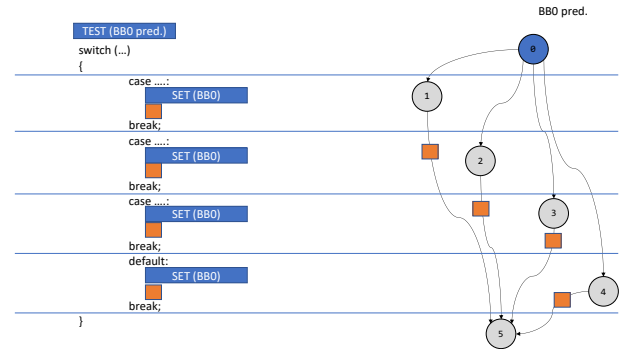


Fig. 2: Positions of the TEST and SET operations for inter-block CFE detection inside the `switch-case` constructs for the entry block (indicated as 0, in blue.)

C. If-else construct

For the `if-else` construct, Figure 4 illustrates the positions of the TEST and SET statements for the entry BB, which is indicated with the `if(...)` statement. While Figure 5

Algorithm 4 Set operation (RACFED). bb represents the current BB, while bb_{+1} its expected successor. `subRanPrevVal` and `CTS` are arrays (with lengths equal to the number of BBs) containing respectively the random number sums and the compile-time signature for every BB.

- 1: **SET**(bb, bb_{+1})
- 2: $RTS = RTS - subRanPrevVal[bb]$
- 3: $adjVal = (CTS[bb] + subRanPrevVal[bb]) + (CTS[bb_{+1}] + subRanPrevVal[bb_{+1}])$
- 4: $RTS = RTS + adjVal$

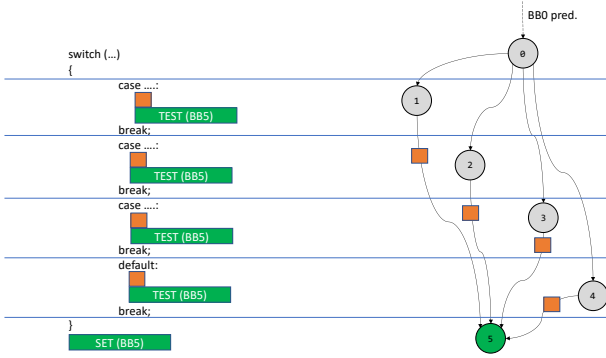


Fig. 3: Positions of the TEST and SET operations for inter-block CFE detection inside the `switch-case` constructs for the exit block (indicated as 5, in green.)

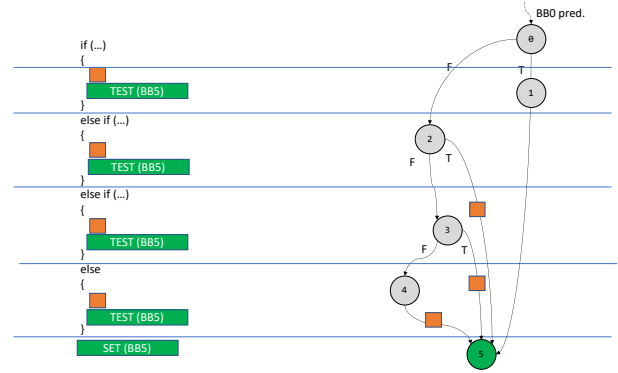


Fig. 5: Positions of the TEST and SET operations for inter-block CFE detection inside the `if-else` constructs for the exit block (indicated as 5, in green.)

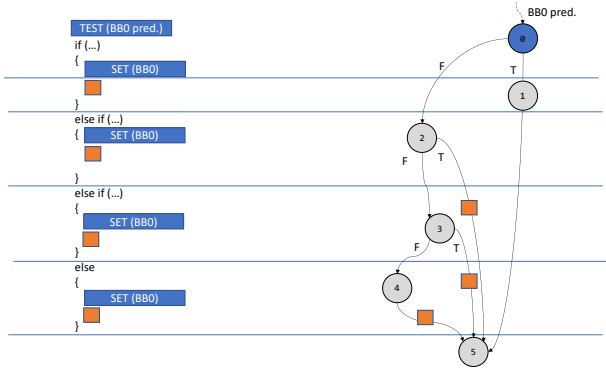


Fig. 4: Positions of the TEST and SET operations for inter-block CFE detection inside the `if-else` constructs for the entry block (indicated as 0, in blue.)

displays the positions of the TEST and SET statements for the exit block which is indicated with a `}` character.

If there is no `else` statement, an `else` statement should be included. In this situation, it is strongly recommended to add a comment clarifying that the `else` statement was inserted to the initial algorithm to facilitate the implementation of the CFC.

D. Function calls

Figure 6 illustrates that a function call is considered a basic block (BB) since the call and return statements act as jumps. Each function has its own return to subroutine Run Time Signature (RTS) so its TEST and SET functions operate on two different signatures: one for the caller and another for the called function. The blue operations refer to operations on the caller's Run Time Signature (RTS), while the yellow operations refer to operations on the function's Run Time Signature (RTS). The BBs are also color-coded. Within a function call, there are generally three BBs, including:

- the previous BB of the caller (p_c),
- the function call (f),
- and the BB following the function call (f_c).

Meanwhile, in a called function, we can define at least two BBs, including the (i) initial BB (i_f) and (ii) final BB (f_f). The two BBs may be merged if the called function has only one BB or if its source code is unavailable.

The following implementation steps are taken:

- 1) Before the function call, we insert the SET operation for the caller BB (p_c) signature.
- 2) Then, the function call BB starts. As usual, the signature of the predecessor BB is tested with the TEST operation for the caller BB (p_c) signature.
- 3) Now, the SET operation is called for the signature of the i_f BB. If the function has been already called in other points of the program, the signature remains set to the signature of the f_f BB, generating a false CFE. The signature of the i_f BB is the signature of the function wrapper, while the signature of the f_f BB is the signature expected at the end of the function call. Hence, the signatures of the i_f and f_f BBs are different if the function is hardened, equal otherwise.
- 4) The function is executed (with possible hardening) and terminates. The signature of the f_f BB is tested with the TEST operation.
- 5) The wrapper sets the signature to the signature of the f BB. (since it is a normal BB of the function call) as its last instruction.
- 6) The BB following the function call tests the signature against the signature of the caller BB (f).

If the compiler decides to inline the function, the proposed strategy behaves correctly (since the TESTs/SETs order is kept). If a function is impossible to harden (for example, using standard libraries or Application Programming Interfaces) or the function contains only a single BB, it is treated as a normal statement.

If a function is called from different locations within the code, separate wrappers must be utilized, each with the appropriate TEST and SET operations. Finally, if the application is multi-threaded, it is critical to avoid having the Run Time Signature (RTS) and predecessor masks of the function

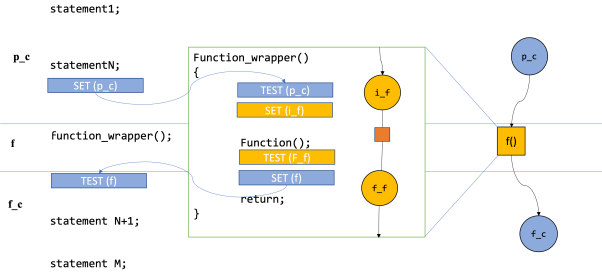


Fig. 6: Positions of the TEST and SET operations for inter-block CFE detection for a function call.

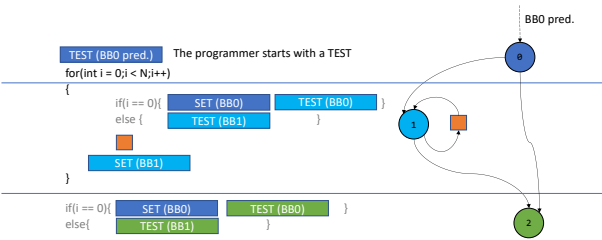


Fig. 7: Positions of TEST and SET operations to detect inter-block CFEs for a for loop.

as static variables to avoid conflicts. Local variables are used in this case.

E. For loops

To implement a hardened for loop, the structure depicted in Figure 7 must be employed, along with the if...else structures shown in gray. It should be noted that these structures are not separate basic blocks (BBs), as they are not present in the original algorithm but are necessary to properly call the TEST/SET functions in the correct order. If the body of the for loop statement (denoted by the orange square in the figure) contains more than one BB, they should be hardened as usual, ensuring that the last BB places the same tested signature in the else statements (identified as BB1 in the figure). For handling a break statement within a for loop, as demonstrated in Figure 8, it is impossible to know if the break has been executed. Therefore, the only way is to refrain from performing the TEST and SET operations on BB2 (which is disregarded in the implementation). The reason is that the break is the sole means of reaching BB5 without executing BB4; hence, BB1 is a legal predecessor of BB5.

IV. TESTING AND VALIDATION APPROACH

This section compares implementations of two established CFC methods in C language, YACCA and RACFED. We have implemented both methods in C and run them on two benchmarks: (i) Timeline Scheduler (TS) and (ii) Tank Level

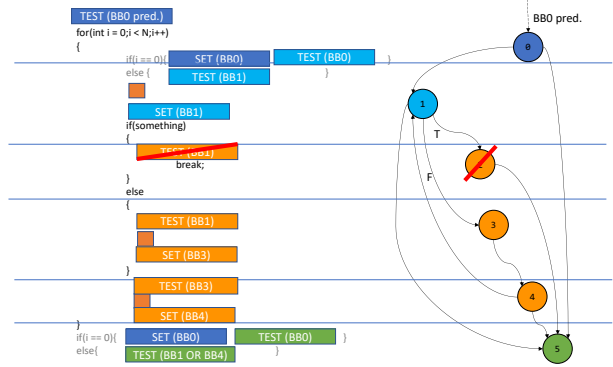


Fig. 8: Positions of TEST and SET operations to detect inter-block CFEs for a for loop containing a break instruction inside it.

Controller (T). The benchmarks were compiled using the GNU RISC-V toolchain and simulated at the instruction set level using QEMU. We used the fault injection system presented in [15] to inject permanent faults affecting the program counter. We chose this register because it directly affects the instruction flow. Two classes of detected faults were considered: (i) safe and (ii) just detected. Safe faults cannot lead to safety violations, while just detected faults are those that are detected but could potentially lead to a safety violation. The experimental results comply with ISO 26262 automotive functional safety standards [14]. Table I shows the diagnostic coverage (DC) of each CFC method for the two benchmarks. DC is defined as the ratio of the total number of faults detected to the total number of faults injected. The results reveal that RACFED outperforms YACCA in terms of DC for both benchmarks. This is attributed to the fact that RACFED can detect intra-block faults, while YACCA can only detect inter-block faults. Additionally, Table II presents the overhead of each method. In this work, two types of overheads are taken into account: (i) the increasing Text Segment Size (TSS), a measure of the amount of program memory that has been occupied as a result of the CFC instructions that were added to the program's instructions after the hardened program was compiled. As a result, the embedded system's flash memory needs to be larger. (ii) Execution time overhead, calculated as the additional number of machine instructions (# exec. instr.) required to run the hardened program given the ISA-level simulation used to run the campaigns. The overhead has been calculated, comparing the parameters measured for the hardened versions to those measured for the non-hardened versions. Although the RACFED overheads are slightly higher than YACCA's, both methods show low overhead levels suitable for real-time applications. In summary, our results show that RACFED is a more effective CFC method than YACCA. RACFED has higher DC and lower overheads, making it a better choice for safety-critical systems.

TABLE I: ISO 26262-compliant classification of the cumulative results obtained from the fault injection campaigns on the benchmarks. [14].

CFC method	Benchmark	Detected		Undetected		False Pos.
		Safe	Detected	Latent	Residual	
YACCA	TS	0.00%	67.49%	11.59%	20.92%	0.00%
YACCA	T	4.00%	2.80%	88.30%	4.90%	0.00%
RACFED	TS	0.00%	56.80%	7.67%	35.53%	0.00%
RACFED	T	5.2%	0.3%	94.50%	0.00%	0.00%

TABLE II: Data regarding memory occupation and executed instruction. T = Tank Level, TS = Timeline Scheduler, and TSS = Text Segment Size. Vanilla refers to the application that is not hardened from its original form. [14].

CFC method	Benchmark	Compiler Optimization	TSS Overhead	# exec. instr. Overhead
Vanilla	T	00	9012	42593
YACCA	T	00	10512 (+16.6%)	44668 (+4.9%)
RACFED	T	00	10966 (+21.7%)	43864 (+3.0%)
Vanilla	TS	00	1736	3991
YACCA	TS	00	2496 (+43.8%)	16689 (+318.17%)
RACFED	TS	00	6271 (+261.23%)	5770 (+44.58%)

V. CONCLUSIONS

This paper presents a comprehensive set of guidelines to assist in the development of safe and reliable embedded systems written in C while employing CFC hardening methods.

Following the proposed guideline is not mandatory, but it is designed to offer a practical approach to developing critical safety embedded systems. The effectiveness of this guideline has been demonstrated through a series of case studies, where reliable embedded systems were developed and deployed in safety-critical situations. The experimental results emphasize the applicability of the guidelines in automotive industry contexts due to their successful employment in this automotive industry scenario.

In conclusion, it would be valuable to investigate the applicability of this method to C++ compilers, especially given the current prevalence of embedded systems using C++ code. This could be a potential avenue for future research in the field of embedded systems.

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