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Original

Closed 1/2-elasticae in the hyperbolic plane / Musso, Emilio; Pámpano, Álvaro. - In: JOURNAL OF MATHEMATICAL ANALYSIS AND APPLICATIONS. - ISSN 0022-247X. - ELETTRONICO. - 527:1(2023), pp. 1-35.
[10.1016/j.jmaa.2023.127388]

Availability:

This version is available at: 11583/2979220 since: 2023-06-08T07:34:51Z

Publisher:

Elsevier

Published

DOI:10.1016/j.jmaa.2023.127388

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<http://dx.doi.org/10.1016/j.jmaa.2023.127388>

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CLOSED 1/2-ELASTICAE IN THE HYPERBOLIC PLANE

EMILIO MUSSO AND ÁLVARO PÁMPANO

ABSTRACT. We study critical trajectories in the hyperbolic plane for the 1/2-Bernoulli's bending energy with length constraint. Critical trajectories with periodic curvature are classified into three different types according to the causal character of their momentum. We prove that closed trajectories arise only when the momentum is a time-like vector. Indeed, for suitable values of the Lagrange multiplier encoding the conservation of the length during the variation, we show the existence of countably many closed trajectories with time-like momentum, which depend on a pair of relatively prime natural numbers.

Keywords: Bernoulli's Functionals, Closed Trajectories, p -Elastic Curves.

1. INTRODUCTION

The present paper is aimed to study the existence and the global properties of closed critical points of the functionals

$$(1.1) \quad \mathcal{B}_\lambda : \gamma \mapsto \int_\gamma (\sqrt{|\kappa|} + \lambda),$$

defined on convex curves γ of the hyperbolic plane \mathcal{H}^2 . The constant λ is a Lagrange multiplier encoding the conservation of the length during the variation and κ is the geodesic curvature of the curve. This is the natural continuation of a previous work [34], devoted to the analogous problem for curves in the plane \mathbb{R}^2 and in the sphere \mathbb{S}^2 . In turn, [34] extended the results obtained in [2, 3, 4, 5, 29] from the unconstrained ($\lambda = 0$) to the constrained case ($\lambda \in \mathbb{R}$).

The functional (1.1) belongs to the family of Bernoulli's functionals

$$\mathcal{B}_{p,\lambda} : \gamma \mapsto \int_\gamma (|\kappa|^p + \lambda),$$

whose critical curves are known as *p-elasticae*. These functionals appeared for the first time in a letter that D. Bernoulli sent to L. Euler in 1738 (see [43], p. 172).

The case $p = 2$ has been extensively studied since then. In addition to the original motivations connected with the theory of elastic rods, 2-elasticae have found several interesting applications in other areas, such as, in surface theory (Willmore surfaces [30, 37, 45], constrained Willmore surfaces [9, 22, 41], and surfaces with spherical lines of curvature [15], among others) and in the Canham-Hefrich-Evans modeling

Date: May 3, 2023.

2010 *Mathematics Subject Classification.* 53C50; 53C42; 53A04; 53A10.

Authors partially supported by PRIN 2014-2017 "Varietà reali e complesse: geometria, topologia e analisi armonica" and by the GNSAGA of INDAM. The second author has been partially supported by the AMS-Simons Travel Grants Program 2021-2022. The authors would like to thank the referee for their valuable comments.

[10, 16, 21] of bilipid membranes [12, 26, 44]. The existence and the geometric properties of closed 2-elasticae have been treated in several works published since the 1980s (see for instance [22, 30, 46]).

In a recent paper [35] Miura-Yoshizawa obtained a complete classification of p -elasticae in the plane \mathbb{R}^2 , for every real number $p > 1$. For $p \in (0, 1)$, since the Lagrangian is merely continuous at the origin, the Bernoulli's functionals are defined for convex curves. Although these cases have been less studied, some particular cases are well known. The unconstrained (ie. $\lambda = 0$) cases in \mathbb{R}^2 with $p = 1/2$, and $p = 1/3$, were considered by W. Blaschke ([5], Vol I, 1921, and Vol II, 1923, respectively) who showed that the critical curves are catenaries ($p = 1/2$) or parabolas ($p = 1/3$). The case $p = 1/3$ and $\lambda = 0$ corresponds with the equi-affine length for convex curves. After the seminal paper [14], equi-affine geometry of convex curves has been consistently used in recent studies on human curvilinear 2-dimensional drawing movements and recognition for non-rigid planar shapes (see for instance [17, 40], respectively, and the literature therein).

For natural values of $p > 2$, unconstrained p -elasticae were previously studied in [2]. They have been used to construct Willmore-Chen submanifolds in spaces with Riemannian and pseudo-Riemannian warped product metrics [1, 8] and have been applied to analyze conformal tensions in string theories [7]. In the case of smooth spherical curves, the only closed critical trajectories are geodesics. Surprisingly, smooth closed spherical unconstrained p -elasticae other than geodesics are 2-elasticae or else $p \in (0, 1)$ [20]. In [2, 4, 20, 32, 33], for $0 < p < 1$, the existence of infinitely many closed unconstrained p -elasticae in \mathbb{S}^2 was shown. When $p = (n - 2)/(n + 1)$, $n \in \mathbb{N}$, and $n > 2$, unconstrained p -elasticae in Riemannian 2-space forms arise in the theory of biconservative hypersurfaces as the generating curves of rotational ones [32, 33]. In particular, unconstrained 1/2-elasticae have also been characterized as the generating curves of invariant minimal surfaces in Riemannian and Lorentzian 3-space forms [3].

The case $p = 1/2$ of the Bernoulli's functionals $\mathcal{B}_{p,\lambda}$ is also special for the following reason: after a suitable contact transformation, the invariant signatures [13, 23, 27, 31] of the critical curves are the connected components of the smooth strata of singular elliptic curves. For this reason, $p = 1/2$ can be considered to play the role of the classical case $p = 2$ among the possible values of $p \in (0, 1)$. As in the case $p = 2$, their study can be made by resorting to elliptic functions and integrals. However, the appearance of a singularity in the elliptic curves containing the signatures does not allow one to explicitly express the curvature in terms of elliptic functions as is the case when $p = 2$ [22, 30].

In the plane \mathbb{R}^2 there are no closed 1/2-elasticae [29, 34], while all closed 1/2-elasticae in \mathbb{S}^2 were recently found in [34] (constrained case) and previously in [2, 4] for the unconstrained case. Motivated by these results of Arroyo, Garay, Mencía, Musso and Pámpano about the existence of closed 1/2-elasticae in \mathbb{S}^2 , this paper aims to investigate constrained 1/2-elasticae in the hyperbolic plane \mathcal{H}^2 . Despite obvious formal analogies, the hyperbolic and spherical cases present substantial differences due to the different topologies of their isometry groups, $O_+^\uparrow(1, 2)$ and $SO(3)$ respectively, and to the different properties of the adjoint representations. Another substantial difference is the following: for every fixed λ , the critical curves of \mathcal{B}_λ are the flow lines of a vector field \vec{X}_λ of the half-plane $\mathbb{H} = \{(x, y) \in \mathbb{R}^2 / x > 0\}$. In the spherical case \vec{X}_λ possesses a unique stable equilibrium point (a center), while

in the hyperbolic case \vec{X}_λ may have, for suitable values of λ , a stable equilibrium point (a center) and an unstable equilibrium point (a saddle point). This causes difficulties in the numerical evaluations of those critical curves whose signatures are near the unstable critical point.

This paper is organized as follows: after recalling the basic features of the hyperbolic plane \mathcal{H}^2 and of the immersed curves, in Section 2 we introduce the variational problem associated with 1/2-elasticae and compute the explicit expression of their momentum. To this end, we employ standard arguments of the calculus of variations and the construction of the Griffith's phase space. The momentum leads to a conservation law whose solutions are analyzed understanding the orbit types of its phase portrait. Section 3 is devoted to the study of periodic solutions to the conservation law, whose corresponding curves are called B-curves. Depending on the causal character of the momentum, we distinguish between three possible types of B-curves: BL-curves, BS-curves and BT-curves. Their explicit parameterizations by quadratures as well as several representations can be found in Subsections 3.1, 3.2 and 3.3, respectively. In particular, in each subsection, the closure conditions are shown. It turns out that closed B-curves (B-strings, for simplicity) exist only among BT-curves. This together with all the necessary concepts is stated in Section 4 (the proof of the existence of BT-strings is postponed to the Appendix, for the sake of clarity).

2. 1/2-ELASTICAE

Let $\mathbb{R}^{1,2}$ be the Minkowski 3-space with the inner product

$$\vec{x} \cdot \vec{y} = (x^1, x^2, x^3) \cdot (y^1, y^2, y^3) = -x^1 y^1 + x^2 y^2 + x^3 y^3,$$

oriented by the volume form $dx^1 \wedge dx^2 \wedge dx^3$, time-oriented by the causal cone $\mathcal{N}^+ = \{\vec{x} \in \mathbb{R}^{1,2} / \vec{x} \cdot \vec{x} \leq 0, x^1 > 0\}$, and equipped with the vector cross-product \times defined by $(\vec{x} \times \vec{y}) \cdot \vec{w} = \det(\vec{x}, \vec{y}, \vec{w})$ where \det stands for the determinant.

The *hyperbolic plane* is the space-like surface

$$\mathcal{H}^2 = \{\vec{x} \in \mathcal{N}^+ / \vec{x} \cdot \vec{x} = -1\},$$

with the induced Riemannian metric $g_{\mathcal{H}^2} = (d\vec{x} \cdot d\vec{x})|_{\mathcal{H}^2}$ of constant sectional curvature -1 . We identify \mathcal{H}^2 and the unit disk $D^2 \subset \mathbb{R}^2$ with the Poincaré metric by means of the isometry

$$\phi : \vec{x} = (x^1, x^2, x^3) \in \mathcal{H}^2 \mapsto \frac{1}{1+x^1}(x^2, x^3) \in D^2.$$

Remark 2.1. Throughout this paper we will use the two models of the hyperbolic plane. In particular, for visualization purposes, the Poincaré disk will be used.

Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathcal{H}^2$ be a smooth immersed curve where $I \subseteq \mathbb{R}$ is its maximal interval of definition. The *hyperbolic Frenet frame* along γ is defined by

$$\mathcal{F} = (\gamma, \dot{\gamma}, \gamma \times \dot{\gamma}) : I \subseteq \mathbb{R} \mapsto \mathcal{O}_+^\uparrow(1, 2),$$

where $\mathcal{O}_+^\uparrow(1, 2)$ is the restricted Lorentz group of $\mathbb{R}^{1,2}$ and the upper dot represents the derivative with respect to the hyperbolic line element ds (ie. $d\gamma = \dot{\gamma}ds$). The hyperbolic Frenet frame satisfies the linear system

$$(2.1) \quad \mathcal{F}^{-1} \cdot d\mathcal{F} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & -\kappa \\ 0 & \kappa & 0 \end{pmatrix} ds,$$

where κ is the *geodesic curvature* of γ . If $\kappa(t_o) = 0$ for some value $t_o \in I \subseteq \mathbb{R}$, we say that $\gamma(t_o)$ is a *hyperbolic inflection point*. Curves with no inflection points have a preferred orientation such that $\kappa > 0$ everywhere. If $\kappa(t_o) = 0$ for some $t_o \in I \subseteq \mathbb{R}$, we say that $\gamma(t_o)$ is a *hyperbolic vertex*.

Remark 2.2. We will distinguish between the curve $\gamma : I \subseteq \mathbb{R} \rightarrow \mathcal{H}^2$ and its image, denoted by $||[\gamma]|| \subset \mathcal{H}^2$, which will be referred to as the *trajectory* of γ .

Let γ be a curve such that its curvature κ is non-constant and periodic. The *wavelength* of γ is the least period $\omega > 0$ of κ . The *monodromy* of the curve is defined by $\mathbf{m}_\gamma = \mathcal{F}|_\omega \cdot \mathcal{F}|_0^{-1}$, and it belongs to the stabilizer of the trajectory $||[\gamma]||$. The curve γ is closed (ie. periodic) if and only if \mathbf{m}_γ has finite order $\mathbf{n}_\gamma \in \mathbb{N}$. We call \mathbf{n}_γ the *wave number*.

Remark 2.3. From the geometric point of view, the wave number is the order of the symmetry group of γ .

If γ is closed, then $I = \mathbb{R}$ and $\omega_\gamma = \mathbf{n}_\gamma \omega$ is the *least period* of γ . A closed curve γ induces an immersion $\boldsymbol{\gamma} : \mathbb{S}_{\omega_\gamma}^1 = \mathbb{R}/\omega_\gamma \mathbb{Z} \rightarrow \mathcal{H}^2$. If $\boldsymbol{\gamma}$ is injective, we say that γ is a *simple closed curve*.

For later use we recall here the hyperbolic analogue of the classical Four Vertex Theorem [28], proved by S. B. Jackson in [24] (see [42] for an alternative proof in the convex case):

Theorem 2.4. *A simple closed smooth curve in \mathcal{H}^2 possesses at least four hyperbolic vertices.*

Remark 2.5. The geometric fact underlying the hyperbolic Four Vertex Theorem is that the notion of a vertex of a curve in a 2-space form is invariant with respect to the action of the pseudo-group of Moebius transformations. Therefore, if we take a curve in the unit disk, its Euclidean and hyperbolic vertices coincide.

We now introduce the variational problem and the class of critical curves under consideration.

Definition 2.6. A *1/2-elastica* with multiplier $\lambda \in \mathbb{R}$ is a convex curve in \mathcal{H}^2 of class \mathcal{C}^4 which is a critical point of the functional

$$\mathcal{B}_\lambda : \gamma \mapsto \int_\gamma \left(\sqrt{|\kappa|} + \lambda \right),$$

with respect to compactly supported variations through convex curves.

Remark 2.7. The regularity condition requested on the space of admissible curves is necessary to apply the classical methods of the calculus of variations giving rise to the standard formula for the variational derivative of functionals depending on the curvature [2, 3, 30, 36]. Although less regularity may as well be imposed (for instance, as in the case treated in [35]), this will not be considered in this paper.

As suggested by this definition, from now on we will only work with convex curves, for which we define the following geometric invariant.

Definition 2.8. The *Blaschke invariant* of a convex curve γ is

$$\mu = \sqrt{\kappa},$$

ie. the positive square root of the geodesic curvature of γ .

In the following proposition we characterize 1/2-elasticae with multiplier $\lambda \in \mathbb{R}$ in terms of a vector of $\mathbb{R}^{1,2}$, namely the momentum.

Proposition 1. *Let γ be a convex curve parameterized by the arc length. Then, γ is a 1/2-elastica with multiplier λ if and only if there exists a non-zero vector $\vec{\xi} \in \mathbb{R}^{1,2}$, called the momentum, such that*

$$(2.2) \quad \frac{1}{2\mu}\gamma + \frac{\dot{\mu}}{2\mu^2}\dot{\gamma} - \left(\lambda + \frac{\mu}{2}\right)\gamma \times \dot{\gamma} = \vec{\xi},$$

where $\mu = \sqrt{\kappa}$ is the Blaschke invariant of γ .

Proof. Using a standard formula for the variational derivative of functionals depending on κ [2, 3, 30, 36], a convex curve is critical for \mathcal{B}_λ if and only if $\mu = \sqrt{\kappa}$ is a solution of the Euler-Lagrange equation

$$(2.3) \quad \frac{\ddot{\mu}}{2\mu^2} = \frac{\dot{\mu}^2}{\mu^3} - \frac{1}{2\mu} - \lambda\mu^2 - \frac{\mu^3}{2}.$$

On the other hand, (2.1) implies

$$\frac{d}{ds} \left(\frac{1}{2\mu}\gamma + \frac{\dot{\mu}}{2\mu^2}\dot{\gamma} - \left[\lambda + \frac{\mu}{2}\right]\gamma \times \dot{\gamma} \right) = \left(\frac{\ddot{\mu}}{2\mu^2} - \frac{\dot{\mu}^2}{\mu^3} + \frac{1}{2\mu} + \lambda\mu^2 + \frac{\mu^3}{2} \right) \dot{\gamma},$$

which proves the result \square

Remark 2.9. The explicit expression of the momentum is found via a more conceptual approach, which is based on the construction of the Griffith's phase space and the analysis of the moment map for the Hamiltonian action of $\mathbb{O}_+^\uparrow(1, 2)$ on the phase space [18, 19, 25, 34, 38].

From (2.2) we obtain the conservation law

$$(2.4) \quad \dot{\mu}^2 = -\mu^2 (\mu^4 + 4\lambda\mu^3 + 4[\lambda^2 - c]\mu^2 - 1),$$

where $c = \vec{\xi} \cdot \vec{\xi}$. Note that the constant c may have any real value.

In order to understand the solutions of (2.3) and (2.4) we will analyze the orbit types of its phase portrait.

2.1. The Modified Invariant Signatures. We begin by defining the invariant and modified invariant signatures of an hyperbolic curve. Let $\gamma : I \subseteq \mathbb{R} \rightarrow \mathcal{H}^2$ be a smooth immersed curve with curvature κ .

Definition 2.10. The (*hyperbolic*) *invariant signature* of γ is the set $\mathfrak{S}_\gamma \subset \mathbb{R}^2$ parameterized by $(\kappa, \dot{\kappa})$. The *modified invariant signature* of a convex curve γ is the set $\widehat{\mathfrak{S}}_\gamma \subset \mathbb{R}^2$ parameterized by $(\mu, \dot{\mu})$, where $\mu = \sqrt{\kappa}$ is the Blaschke invariant.

Remark 2.11. Our definition of the invariant signature is the hyperbolic analogue of the corresponding one for plane curves in Euclidean, affine or projective geometries [13, 23, 27, 31]. We note that the signature of a convex curve is the image of the modified signature by the contact diffeomorphism $\mathbf{f} : (x, y) \in \mathbb{H} \rightarrow (x^2, 2xy) \in \mathbb{H}$ of the positive half-plane $\mathbb{H} = \{(x, y) \in \mathbb{R}^2 / x > 0\}$. If γ is a closed convex curve with non-constant curvature and wave number \mathbf{n}_γ , the point $(\mu(s), \dot{\mu}(s))$, $s \in [0, \omega_\gamma]$ runs through the signature \mathbf{n}_γ -times. Hence, the wave number is the degree of the branched covering $\gamma(s) \in |\gamma| \rightarrow (\kappa(s), \dot{\kappa}(s)) \in \mathfrak{S}_\gamma$ or, in the convex case, the degree of $\gamma(s) \in |\gamma| \rightarrow (\mu(s), \dot{\mu}(s)) \in \widehat{\mathfrak{S}}_\gamma$.

Let \mathbb{H} be the half-plane $\{(x, y) \in \mathbb{R}^2 / x > 0\}$ and $\vec{X}_\lambda \in \mathfrak{X}(\mathbb{H})$ be the vector field (see Figure 1, left)

$$(2.5) \quad \vec{X}_\lambda|_{(x,y)} = y \partial_x + 2 \left(\frac{y^2}{x} - \frac{x}{2} - \lambda x^4 - \frac{x^5}{2} \right) \partial_y.$$

The integral curves of \vec{X}_λ are the modified signatures of 1/2-elasticae with multiplier $\lambda \in \mathbb{R}$. Hence, they are parameterized by

$$\mathbf{m} : s \in I \subseteq \mathbb{R} \mapsto (\mu(s), \dot{\mu}(s)),$$

where μ is a positive solution of (2.3) and I is its maximal interval of definition. From (2.4) it follows that the modified signature of a 1/2-elastica with momentum $\bar{\xi}$ is a smooth stratum of $\mathcal{C}_{\lambda,c}^* = \mathcal{C}_{\lambda,c} \cap \mathbb{H}$, where $\mathcal{C}_{\lambda,c} \subset \mathbb{R}^2$ is the singular elliptic curve $y^2 + x^2 Q_{\lambda,c}(x) = 0$ and $Q_{\lambda,c}(x)$ is the quartic polynomial

$$(2.6) \quad Q_{\lambda,c}(x) = x^4 + 4\lambda x^3 + 4(\lambda^2 - c)x^2 - 1.$$

Non-constant periodic solutions of (2.3) correspond to the smooth compact connected components of $\mathcal{C}_{\lambda,c}$ contained in \mathbb{H} . If $\lambda \geq -2/\sqrt[4]{27}$ there are no smooth compact 1-dimensional phase curves of \vec{X}_λ . Thus, there are no critical curves with non-constant periodic curvature and, a fortiori, closed 1/2-elasticae. Since our ultimate goal is to investigate closed 1/2-elasticae, we discard this case. Thus, from now on we assume that $\lambda < -2/\sqrt[4]{27}$ holds. Then, the equilibrium points of \vec{X}_λ are $\mathbf{m}_\pm(\lambda) = (\eta_\pm(\lambda), 0)$, where $0 < \eta_-(\lambda) < \eta_+(\lambda)$ are the two real roots of the quartic polynomial

$$(2.7) \quad P_\lambda(x) = x^4 + 2\lambda x^3 + 1.$$

The equilibrium point $\mathbf{m}_-(\lambda)$ is unstable (a saddle point) while $\mathbf{m}_+(\lambda)$ is a stable elliptic equilibrium point (a center).

Remark 2.12. The functions

$$(2.8) \quad \eta_\pm : (-\infty, -2/\sqrt[4]{27}) \mapsto \eta_\pm(\lambda) \in \mathbb{R}^+$$

are continuous and real-analytic on $(-\infty, -2/\sqrt[4]{27})$. The function η_- is strictly increasing, $\eta_-(\lambda) > 1$ for every $\lambda \in (-1, -2/\sqrt[4]{27})$, and $\eta_-(\lambda) \leq 1$ for every $\lambda \leq -1$. The function η_+ is strictly decreasing. Using Ferrari's formula one can obtain the explicit expressions of the functions η_\pm . These expressions are rather complicated and, hence, we avoid writing them here, although they will be used in some computations later on.

We now describe the orbit types of the phase portrait of the vector field \vec{X}_λ (see Figure 1, right):

- The unstable equilibrium point $\mathbf{m}_-(\lambda)$ and the stable equilibrium point $\mathbf{m}_+(\lambda)$. They correspond to the constant solutions $\mu = \eta_-(\lambda)$ and $\mu = \eta_+(\lambda)$ of (2.3) (the purple and black points, respectively, in Figure 1).
- Closed trajectories (see the red curve depicted on Figure 1). They correspond to the solutions of (2.3) with initial conditions $\mu(0) \in (\eta_-(\lambda), \eta_+(\lambda))$ and $\dot{\mu}(0) = 0$.
- Non-closed phase curves of the first kind (see the blue curve depicted on Figure 1). They correspond to the solutions of (2.3) with initial conditions $\mu(0) \in (m_\lambda^*, +\infty)$ and $\dot{\mu}(0) = 0$ (the point $(m_\lambda^*, 0)$ is represented in blue in Figure 1). The origin is the limit point of these integral curves.

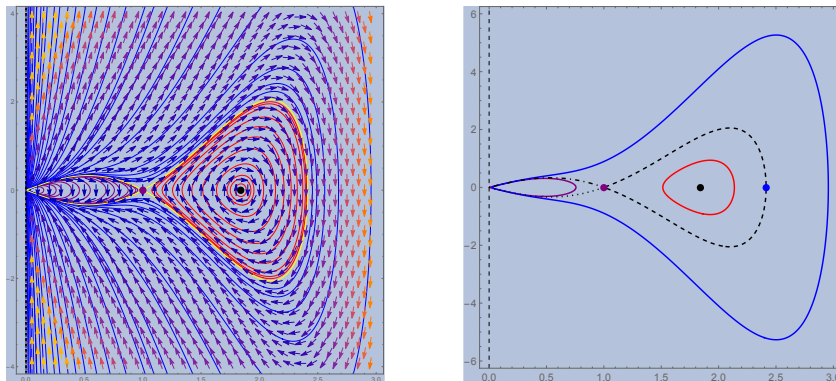


FIGURE 1. Left: The plot of the vector field \vec{X}_{-1} and its phase portrait. Right: The orbit types of \vec{X}_{-1} .

- Non-closed phase curves of the second kind (see the purple curve depicted on Figure 1). They correspond to the solutions of (2.3) with initial conditions $\mu(0) \in (0, \eta_-(\lambda))$ and $\dot{\mu}(0) = 0$. The origin is the limit point of these integral curves.
- The exceptional (non-closed) phase curve of the first kind (the dashed-black curve reproduced in Figure 1). It corresponds to the solution of (2.3) with initial conditions $\mu(0) = m_\lambda^*$ and $\dot{\mu}(0) = 0$. The unstable equilibrium is the limit point of this phase curve.
- The two exceptional (non-closed) phase curves of the second kind (the dotted and dash-dotted black curves reproduced in Figure 1). They correspond to the solutions of (2.3) with initial conditions

$$\mu(0) = \frac{\eta_-(\lambda)}{2}, \quad \dot{\mu}(0) = \pm \frac{\eta_-(\lambda)}{2} \sqrt{-Q_{\lambda, c_+(\lambda)}\left(\frac{\eta_-(\lambda)}{2}\right)}.$$

They have two limit points: the origin and the unstable equilibrium point.

In the hyperbolic plane \mathcal{H}^2 there are three types of curves of positive constant curvature κ , depending on whether $\kappa > 1$ (elliptic type), $\kappa = 1$ (parabolic type) or $\kappa < 1$ (hyperbolic type). The only closed ones, namely circles, are those of elliptic type (ie. $\kappa > 1$). We then have the following result.

Proposition 2. *For closed 1/2-elasticae with multiplier λ and $\kappa > 0$ constant, the following conclusions hold:*

- If $\lambda > -2/\sqrt[4]{27}$ there are no 1/2-elasticae with positive constant curvature and multiplier λ .
- If $\lambda = -2/\sqrt[4]{27}$ there is one equivalence class of closed 1/2-elasticae with positive constant curvature and multiplier λ . In this case $\kappa = \sqrt{3}$.
- If $-1 < \lambda < -2/\sqrt[4]{27}$ there are two distinct equivalence classes of closed 1/2-elasticae with positive constant curvature and multiplier λ . Their curvatures are $\eta_-(\lambda)^2$ and $\eta_+(\lambda)^2$, respectively.
- If $\lambda \leq -1$ there is one equivalence class of closed 1/2-elasticae with positive constant curvature $\eta_+(\lambda)^2$ and multiplier λ .

Proof. Consider the vector field $\vec{X}_\lambda \in \mathfrak{X}(\mathbb{H})$ given in (2.5). Constant solutions of (2.3) correspond to the equilibrium points of \vec{X}_λ . Hence, 1/2-elasticae with multiplier λ and $\kappa > 0$ constant are related to the equilibria of \vec{X}_λ . Therefore, from the previous discussion (more precisely, see the first item of the previous list about the orbit types) we have the following cases. If $\lambda > -2/\sqrt[4]{27}$ the vector field \vec{X}_λ has no equilibrium points. This implies that (2.3) does not possess constant solutions. This proves the first assertion. If $\lambda = -2/\sqrt[4]{27}$, the vector field \vec{X}_λ possesses a unique equilibrium point, namely $\mathbf{m}_+(\lambda) = \mathbf{m}_-(\lambda) = (\sqrt[4]{3}, 0)$. Recall that in the hyperbolic plane \mathcal{H}^2 a curve of positive constant curvature is closed if $\kappa = \mu^2 > 1$. Since $\sqrt[4]{3} > 1$, this implies the second assertion. Suppose now that $\lambda < -2/\sqrt[4]{27}$. The two critical curves of \mathcal{B}_λ with constant curvature correspond to the two equilibrium points of the vector field \vec{X}_λ . Thus, their curvatures are $\eta_+(\lambda)^2$ and $\eta_-(\lambda)^2$, respectively. Since $\eta_+(\lambda) > 1$ for every λ , any curve with modified signature $\mathbf{m}_+(\lambda)$ is a closed circle. Instead, $\eta_-(\lambda) > 1$ if and only if $\lambda \in (-1, -2/\sqrt[4]{27})$. This proves the third and the last assertions. \square

Remark 2.13. If $-1 < \lambda < -2/\sqrt[4]{27}$, the unstable equilibrium point of \vec{X}_λ is the modified signature of a curve with constant curvature of elliptic type (a closed circle). If $\lambda = -1$, the unstable equilibrium point is the modified signature of a curve with constant curvature of parabolic type (in the Poincaré disk, a circle minus an “ideal” point). If $\lambda < -1$ the unstable equilibrium point is the modified signature of a curve with constant curvature of hyperbolic type (a circular arc with two “ideal” points).

The study of closed 1/2-elasticae with non-constant curvature can be subdivided into two parts: the analysis of the curves with non-constant periodic curvature and the investigation of the closure conditions for these curves.

3. B-CURVES

In this section we study 1/2-elasticae with non-constant periodic curvature. For convenience, we introduce the following terminology.

Definition 3.1. Convex curves whose Blaschke invariant μ is a non-constant periodic solution of (2.4) are called *B-curves*. A closed B-curve is a *B-string*.

Remark 3.2. Note that periodic solutions of (2.4) do exist if and only if the quartic polynomial $Q_{\lambda,c}$ has four distinct real roots, three positive and one negative, denoted by $e_1 > e_2 > e_3 > 0 > e_4$, respectively. The equations (2.3), (2.4), the multiplier λ , the constant c and the roots $e_1 > e_2 > e_3 > 0 > e_4$ of $Q_{\lambda,c}$ depend only on the equivalence class of the B-curve (see the definition below).

Definition 3.3. Two immersed curves γ and $\tilde{\gamma}$ are *equivalent to each other* if there exist $A \in \mathcal{O}_+^\uparrow(1, 2)$ and a smooth strictly increasing function $\psi : I \subseteq \mathbb{R} \rightarrow \mathbb{R}$ such that $\tilde{\gamma}(t) = A\gamma \circ \psi$, for all $t \in I \subseteq \mathbb{R}$. The *equivalence class* of γ is denoted by $\langle \gamma \rangle$. The *moduli space* is the set of the equivalence classes.

Remark 3.4. If γ and $\tilde{\gamma}$ are equivalent to each other and parameterized by arc length the change of parameter ψ is a translation of the independent variable (ie. $\psi(s) = s + s_o$, where s_o is a constant).

It turns out that the moduli space of B-curves can be described in terms of the multiplier λ and the root e_2 of $Q_{\lambda,c}$.

Proposition 3. *Let γ be a B-curve. The map $\langle \gamma \rangle \rightarrow (\lambda(\langle \gamma \rangle), e_2(\langle \gamma \rangle)) \in \mathbb{R}^2$ is a bijection onto the open domain $\mathfrak{P} = \{(\lambda, e_2) \in \mathbb{R}^2 / e_2 > 0, e_2^4 + 2\lambda e_2^3 + 1 < 0\}$ of \mathbb{R}^2 .*

Proof. Assume that γ is a B-curve. From the definition, its Blaschke invariant μ is a non-constant periodic solution of (2.4). As noticed in Remark 3.2, since $Q_{\lambda,c}(0) = -1$ and $\lim_{\mu \rightarrow \pm\infty} Q_{\lambda,c}(\mu) = +\infty$, periodic solutions of (2.4) exist if and only if the quartic polynomial $Q_{\lambda,c}$ has four distinct real roots $e_1 > e_2 > e_3 > 0 > e_4$. It then follows that $Q_{\lambda,c}$ has roots $e_1 > e_2 > e_3 > 0 > e_4$ if and only if

$$(3.1) \quad \begin{cases} (i) & 0 < e_2 < e_1, \\ (ii) & 0 < e_1^2 e_2^3 - 2e_1 - e_2, \\ (iii) & e_3 = \frac{e_1 + e_2 + \sqrt{4e_1^3 e_2^3 + (e_1 + e_2)^2}}{2e_1^2 e_2^2}, \\ (iv) & e_4 = \frac{-2e_1 e_2}{e_1 + e_2 + \sqrt{4e_1^3 e_2^3 + (e_1 + e_2)^2}}, \\ (v) & \lambda = -\frac{e_1^3 e_2^2 + e_1^2 e_2^3 + e_1 + e_2}{4e_1^2 e_2^2}, \\ (vi) & c = \frac{-2e_1^5 e_2^5 + e_1^6 e_2^4 + e_1^4 e_2^6 - 2(e_1^4 e_2^2 + e_1^2 e_2^4) + (e_1 + e_2)^2}{16e_1^4 e_2^4}. \end{cases}$$

Case (i) above is direct, (ii) is a consequence of requesting $e_2 > e_3$, while cases (iii)-(vi) arise by solving the Cardano-Vieta's relations in terms of e_1 and e_2 . From (i), (ii) and (v) it follows that $1 + e_2^4 + 2\lambda e_2^3 < 0$ and $e_2 > 0$. This implies that $(\lambda(\langle \gamma \rangle), e_2(\langle \gamma \rangle))$ belongs to \mathfrak{P} , for every equivalence class $\langle \gamma \rangle$ of B-curves. Conversely, let (λ, e_2) be a point of \mathfrak{P} . The inequalities $e_2 > 0$ and $1 + e_2^4 + 2\lambda e_2^3 < 0$ imply that the cubic polynomial

$$(3.2) \quad e_2^2 x^3 + (e_2^3 + 4e_2^2 \lambda) x^2 + x + e_2$$

has a unique real root e_1 strictly bigger than e_2 . Define e_3, e_4 and c as in (3.1). Then, e_1 and e_2 satisfy (ii) of (3.1) and $e_1 > e_2 > e_3 > 0 > e_4$ are the four roots of $Q_{\lambda,c}$. Let μ be the (periodic) solution of (2.4) such that $\mu(0) = e_2$ and γ be a B-curve with $\kappa = \mu^2$. Then, $\langle \gamma \rangle \in \mathfrak{P}$ is the unique equivalence class of B-curves such that $\lambda(\langle \gamma \rangle) = \lambda$ and $e_2(\langle \gamma \rangle) = e_2$. \square

Remark 3.5. *From the Cardano's formula¹, we have*

$$(3.3) \quad e_1 = \frac{1}{3e_2} \left[(e_2 + 4\lambda)e_2 + \Re \left(\sqrt[3]{-8 \left[\mathbf{a} + 3\sqrt{3\mathbf{b}} \right]} \right) \right]$$

where

$$\mathbf{a} = \mathbf{a}(\lambda, e_2) = e_2^6 + 12\lambda e_2^5 + 48\lambda^2 e_2^4 + 64\lambda^3 e_2^3 + 9e_2^2 - 18\lambda e_2,$$

$$\mathbf{b} = \mathbf{b}(\lambda, e_2) = e_2^8 + 12\lambda e_2^7 + 48\lambda^2 e_2^6 + 64\lambda^3 e_2^5 + 2e_2^4 - 20\lambda e_2^3 + 4\lambda^2 e_2^2 + 1.$$

Using (3.3) and (iii), (iv), (vi) of (3.1), the roots e_3, e_4 and the constant c can be expressed as real-analytic functions of λ and e_2 . As a rule, this dependence is implied. If necessary, it will be explicitly indicated.

From now on the moduli space of B-curves is identified with \mathfrak{P} . For each $\mathbf{p} = (\lambda, e_2) \in \mathfrak{P}$, the polynomial $Q_{\lambda,c}$, $c = c(\lambda, e_2)$, is denoted by $Q_{\mathbf{p}}$. Similarly, $\mu_{\mathbf{p}}$ stands for the solution of (2.3) with initial conditions $\mu_{\mathbf{p}}(0) = e_2$, $\dot{\mu}_{\mathbf{p}}(0) = 0$. By construction, $\mu_{\mathbf{p}}$ satisfies $\dot{\mu}_{\mathbf{p}}^2 + Q_{\mathbf{p}}(\mu_{\mathbf{p}}) = 0$.

¹ $\sqrt[n]{\zeta}$ is the determination of the n-th root of $\zeta \in \mathbb{C}$, with a branch cut discontinuity along the negative real axis such that $\Im(\sqrt[n]{\zeta}) > 0$, if ζ belongs to the negative real axis.

We will next discuss an approach to obtain the Blaschke invariant $\mu_{\mathbf{p}}$ and its associated B-curve $\gamma_{\mathbf{p}}$. Let $\mathbf{p} = (\lambda, e_2) \in \mathfrak{P}$, e_1, e_3, e_4 be the other three roots of $Q_{\mathbf{p}}$ and $\omega_{\mathbf{p}}$ be the least period of $\mu_{\mathbf{p}}$. We call $\omega : \mathbf{p} \in \mathfrak{P} \rightarrow \omega_{\mathbf{p}} \in \mathbb{R}$ the *wavelength function*. From 256.12 and 340.04 of [6] we obtain

$$(3.4) \quad \omega_{\mathbf{p}} = 2 \int_{e_2}^{e_1} \frac{dx}{x\sqrt{-Q_{\mathbf{p}}(x)}} = \frac{2\mathbf{g}}{e_1} \left(\frac{\mathbf{a}}{\mathbf{n}} \mathbf{K}(\mathbf{m}) - \frac{\mathbf{a} - \mathbf{n}}{\mathbf{n}} \mathbf{\Pi}(\mathbf{n}, \mathbf{m}) \right),$$

where \mathbf{K} and $\mathbf{\Pi}$ are the complete elliptic integrals of the first and third kind respectively, and

$$(3.5) \quad \mathbf{a} = \frac{e_2 - e_1}{e_2 - e_4}, \quad \mathbf{m} = \frac{(e_1 - e_2)(e_3 - e_4)}{(e_1 - e_3)(e_2 - e_4)}, \quad \mathbf{n} = \frac{e_4 \mathbf{a}}{e_1}, \quad \mathbf{g} = \frac{2}{\sqrt{(e_1 - e_3)(e_2 - e_4)}}.$$

It then follows from (3.5) that the wavelength depends in a real-analytic fashion on \mathbf{p} . On the other hand, the function $\mu_{\mathbf{p}}$ is strictly increasing on $[0, \omega_{\mathbf{p}}/2]$. Let $h_{\mathbf{p}} : [e_2, e_1] \rightarrow [0, \omega_{\mathbf{p}}/2]$ be the inverse of $\mu_{\mathbf{p}}|_{[0, \omega_{\mathbf{p}}/2]}$. From $\dot{\mu}_{\mathbf{p}}^2 = -\mu_{\mathbf{p}}^2 Q_{\mathbf{p}}(\mu_{\mathbf{p}})$, we have

$$h_{\mathbf{p}}(\mu) = \frac{\omega_{\mathbf{p}}}{2} - \int_{\mu}^{e_1} \frac{dx}{x\sqrt{-Q_{\mathbf{p}}(x)}}, \quad \mu \in [e_2, e_1].$$

This integral can be solved in terms of incomplete elliptic integrals and Jacobi's functions ([6], 257.12 and 340.04). As a result we obtain

$$(3.6) \quad h_{\mathbf{p}}(\mu) = \frac{\omega_{\mathbf{p}}}{2} - \frac{\mathbf{g}}{e_1} \left(\frac{\mathbf{a}}{\mathbf{n}} \mathbf{u}(\mu) - \frac{\mathbf{a} - \mathbf{n}}{\mathbf{n}} \mathbf{\Pi}(\mathbf{n}, \mathbf{am}_{\mathbf{m}}(\mathbf{u}(\mu)), \mathbf{m}) \right),$$

where $\mathbf{\Pi}(\mathbf{n}, -, \mathbf{m})$ is the incomplete elliptic integral of the third kind with parameters \mathbf{n} and \mathbf{m} , $\mathbf{am}_{\mathbf{m}}$ is the Jacobi's amplitude with parameter \mathbf{m} , and

$$\mathbf{u}(\mu) = \operatorname{sn}^{-1} \left(\sqrt{\frac{(e_2 - e_4)(e_1 - \mu)}{(e_1 - e_2)(\mu - e_4)}}, \mathbf{m} \right).$$

Then, $\mu_{\mathbf{p}}|_{[0, \omega_{\mathbf{p}}/2]} = h_{\mathbf{p}}^{-1}$. Since $\mu_{\mathbf{p}}$ is even, this suffices to reconstruct $\mu_{\mathbf{p}}$ on the whole real axis. The B-curves with curvature $\kappa_{\mathbf{p}} = \mu_{\mathbf{p}}^2$ can be numerically evaluated solving the linear system (2.1), with appropriate initial conditions.

Remark 3.6. The algebraic curves $y^2 + x^2 Q_{\mathbf{p}}(x) = 0$ possess a singularity at the origin. This is the geometric reason behind the fact that the Blaschke invariant $\mu_{\mathbf{p}}$ cannot be expressed through elliptic functions as in the case of constrained and unconstrained elasticae of the hyperbolic plane [22, 30]. Therefore, a more practical procedure to build $\mu_{\mathbf{p}}$ is to solve numerically the second-order ordinary differential equation (2.3) with initial conditions $\mu_{\mathbf{p}}(0) = e_2$ and $\dot{\mu}_{\mathbf{p}}(0) = 0$.

There are three possible types of B-curves depending on the causal character of the momentum $\vec{\xi}$: either $\vec{\xi}$ is space-like or light-like or else time-like. Each of these cases carries different signs on the constant $c = \vec{\xi} \cdot \vec{\xi}$ of the conservation law (2.4) and the associated B-curves present essentially different behaviors. Thus, we will distinguish between them.

Definition 3.7. We say that a B-curve γ is a *BS-curve* (resp., *BL-* or *BT-curve*) if its momentum $\vec{\xi}$ is space-like (resp., light-like or time-like).

It is also convenient to split the moduli space \mathfrak{P} in three different subdomains depending on whether the B-curves associated with $\mathbf{p} = (\lambda, e_2)$ are BS-, BL-, or BT-curves (see Figure 2).

Definition 3.8. The open subdomains $\mathcal{S} = \{(\lambda, e_2) \in \mathfrak{P} / c(\lambda, e_2) > 0\}$, $\mathcal{T} = \{(\lambda, e_2) \in \mathfrak{P} / c(\lambda, e_2) < 0\}$ and the separating curve $\mathcal{L} = \{(\lambda, e_2) \in \mathfrak{P} / c(\lambda, e_2) = 0\}$ are the *moduli spaces of BS-, BT- and BL-curves*, respectively.

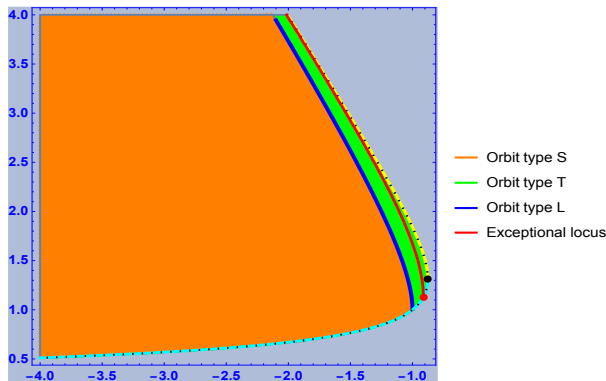


FIGURE 2. The moduli space \mathfrak{P} . The blue curve is \mathcal{L} , the orange region is \mathcal{S} and the green region is \mathcal{T} . The red curve is the exceptional locus \mathcal{E} .

Remark 3.9. The moduli spaces \mathcal{S} , \mathcal{L} and \mathcal{T} can be characterized as follows:

- $(\lambda, e_2) \in \mathcal{S} \iff (\lambda, e_2) \in \mathfrak{P}$ and $e_2^2 + 2\lambda e_2 + 1 < 0$,
- $(\lambda, e_2) \in \mathcal{L} \iff (\lambda, e_2) \in \mathfrak{P}$ and $e_2^2 + 2\lambda e_2 + 1 = 0$,
- $(\lambda, e_2) \in \mathcal{T} \iff (\lambda, e_2) \in \mathfrak{P}$ and $e_2^2 + 2\lambda e_2 + 1 > 0$.

The curve \mathcal{L} is also the graph of the function

$$(3.7) \quad b_0 : \lambda \in (-\infty, -1) \mapsto -\lambda + \sqrt{\lambda^2 - 1}.$$

The boundary $\partial\mathfrak{P}$ is the curve $1 + e_2^4 + 2e_2^3\lambda = 0$, $\lambda < -2/\sqrt[4]{27}$. This curve is the union of the graphs $\partial_{\pm}\mathfrak{P}$ of the functions η_{\pm} defined in (2.8) (the dotted curves colored in blue and yellow in Figure 2).

We now study each type of B-curves separately. For each case we will obtain explicit parameterizations by quadratures. The explicit expressions of the B-curves are found with a more conceptual approach based on the Marsden-Weinstein reduction method as applied to the Hamiltonian action of $O_+^{\uparrow}(1, 2)$ on the Griffith's phase space of the variational problem [18, 19, 25, 34, 38].

3.1. BL-Curves. Let $\mathfrak{p} \in \mathcal{L}$. Then \mathfrak{p} is of the form $\mathfrak{p} = (\lambda, e_2(\lambda))$, where $e_2(\lambda) = -\lambda + \sqrt{\lambda^2 - 1}$ and $\lambda < -1$. The B-curves associated with $\mathfrak{p} \in \mathcal{L}$ have constant $c = 0$ in the conservation law (2.4). In other words, their momenta are light-like vectors.

Theorem 3.10. Let $\mathfrak{p} = (\lambda, e_2) \in \mathcal{L}$ and $\mu_{\mathfrak{p}}$ be the solution of (2.4) with initial condition $\mu_{\mathfrak{p}}(0) = e_2$ where $c = 0$. Define $\Theta_{\mathfrak{p}}$ by

$$\Theta_{\mathfrak{p}}(s) = - \int_0^s \mu_{\mathfrak{p}}^2 (\mu_{\mathfrak{p}} + 2\lambda) ds.$$

Then,

$$(3.8) \quad \gamma_{\mathfrak{p}} = \frac{1}{2\sqrt{2}\mu_{\mathfrak{p}}} \left(2\Theta_{\mathfrak{p}}^2 + 2\mu_{\mathfrak{p}}^2 + 1, 2\sqrt{2}\Theta_{\mathfrak{p}}, 2\Theta_{\mathfrak{p}}^2 + 2\mu_{\mathfrak{p}}^2 - 1 \right)$$

is a BL-curve with modulus \mathfrak{p} and momentum $\vec{\xi} = \frac{1}{\sqrt{2}}(1, 0, 1)$. There are no BL-strings.

Proof. For simplicity, we will omit the subscript \mathfrak{p} throughout this proof. From (3.8) it follows that $\gamma \cdot \dot{\gamma} = -1$ and furthermore we have that

$$\dot{\gamma} \cdot \dot{\gamma} = \frac{\dot{\mu}^2 + \mu^6 + 4\lambda\mu^5 + 4\lambda^2\mu^4}{\mu^2}.$$

Using (2.4) we obtain $\dot{\gamma} \cdot \dot{\gamma} = 1$. Then, γ is parameterized by arc length. Computing $\kappa = \ddot{\gamma} \cdot (\gamma \times \dot{\gamma})$ we find

$$\kappa = -(\mu + 2\lambda)\ddot{\mu} + 2(1 + \lambda\mu^{-1})\dot{\mu}^2 - \mu^6 - 6\lambda\mu^5 - 12\lambda^2\mu^4 - 8\lambda^3\mu^3.$$

Then, from (2.3) and (2.4) we obtain $\kappa = \mu^2$. This implies that γ is a B-curve with parameters $(\lambda, e_2(\lambda))$. In addition, we have

$$\begin{cases} \gamma|_0 = \frac{1}{2\sqrt{2}} (\sqrt{\lambda^2 - 1} - 3\lambda, 0, 3\sqrt{\lambda^2 - 1} - \lambda), \\ \dot{\gamma}|_0 = (0, 1, 0), \\ \gamma|_0 \times \dot{\gamma}|_0 = \frac{1}{2\sqrt{2}} (3\sqrt{\lambda^2 - 1} - \lambda, 0, \sqrt{\lambda^2 - 1} - 3\lambda). \end{cases}$$

Keeping in mind that $\mu(0) = e_2(\lambda)$ and $\dot{\mu}(0) = 0$, we obtain

$$\vec{\xi} = \frac{1}{e_2(\lambda)} \gamma|_0 - \left(\lambda + \frac{e_2(\lambda)}{2} \right) \gamma|_0 \times \dot{\gamma}|_0 = \frac{1}{\sqrt{2}}(1, 0, 1).$$

We now show that BL-strings do not exist. For γ to be periodic, it follows from (3.8) that $\Theta(\omega)$ needs to be zero where ω is the least period of κ , ie. the wavelength. In this case, the least period of γ is also ω . On $[0, \omega/2]$ we have from (2.4)

$$ds = \frac{d\mu}{-\mu\sqrt{-(\mu^4 + 4\lambda\mu^3 + 4\lambda^2\mu^2 - 1)}}.$$

Then,

$$(3.9) \quad \begin{aligned} \Theta(\omega) &= -\int_0^\omega \mu^2(\mu + 2\lambda) ds = -2 \int_0^{\omega/2} \mu^2(\mu + 2\lambda) ds \\ &= 2 \int_{e_2}^{e_1} \frac{\mu(\mu + 2\lambda)}{\sqrt{-(\mu^4 + 4\lambda\mu^3 + 4\lambda^2\mu^2 - 1)}} d\mu, \end{aligned}$$

where

$$e_1 = -\lambda + \sqrt{\lambda^2 + 1} > e_2 = -\lambda + \sqrt{\lambda^2 - 1}.$$

The right hand side of (3.9) is a standard elliptic integral that can be solved using 257.11, 336.01, 336.02 and 340.02 of [6]. As a result we obtain

$$\Theta(\omega) = 2 \frac{\sqrt{2} (2\lambda^4 + 2\lambda^2\sqrt{\lambda^2 - 1})}{(\lambda^2 + \sqrt{\lambda^4 - 1})^{3/2}} (E(\mathfrak{m}_\lambda) - K(\mathfrak{m}_\lambda)),$$

where E is the complete elliptic integral of the second kind and

$$\mathfrak{m}_\lambda = \frac{\lambda^2 - \sqrt{\lambda^4 - 1}}{\lambda^2 + \sqrt{\lambda^4 - 1}} \in (0, 1).$$

Since $E(m) < K(m)$ for every $m \in (0, 1)$, it follows that

$$\Theta(\omega) < 0,$$

and so there are no BL-strings. \square

Definition 3.11. The BL-curve $\gamma_{\mathbf{p}}$ given by (3.8) is referred to as the *standard BL-curve* with modulus $\mathbf{p} \in \mathcal{L}$.

Remark 3.12. Every BL-curve with modulus $\mathbf{p} \in \mathcal{L}$ is equivalent to $\gamma_{\mathbf{p}}$, (3.8). From now on we implicitly assume that the BL-curves in consideration are in their standard form.

Let $\mathbf{p} = (\lambda, -\lambda + \sqrt{\lambda^2 - 1}) \in \mathcal{L}$ and $\gamma_{\mathbf{p}}$ be the standard BL-curve with modulus \mathbf{p} defined as in (3.8). Adopting the Poincaré model of the hyperbolic plane, the curve $\gamma_{\mathbf{p}}$ is parameterized by

$$\gamma_{\mathbf{p}} = \frac{1}{2\Theta_{\mathbf{p}}^2 + (1 + \sqrt{2}\mu_{\mathbf{p}})^2} \left(2\sqrt{2}\Theta_{\mathbf{p}}, 2\Theta_{\mathbf{p}}^2 + 2\mu_{\mathbf{p}}^2 - 1 \right).$$

The stabilizer of the momentum is the parabolic subgroup

$$P = \left\{ \text{HP}(t) = \begin{pmatrix} 1 + \frac{t^2}{2} & t & -\frac{t^2}{2} \\ t & 1 & -t \\ \frac{t^2}{2} & t & 1 - \frac{t^2}{2} \end{pmatrix} / t \in \mathbb{R} \right\}.$$

The monodromy \mathbf{m} is the non-trivial element $\text{HP}(\sqrt{2}\Theta_{\mathbf{p}}(\omega_{\mathbf{p}}))$ of P . Let $\Gamma = \gamma_{\mathbf{p}}([0, \omega_{\mathbf{p}}])$ be the fundamental arc, then $|\gamma_{\mathbf{p}}| = \cup_{n \in \mathbb{Z}} \mathbf{m}^n(\Gamma)$. Since the curvature is an even function, $|\gamma_{\mathbf{p}}|$ is invariant by the reflection with respect to the O_Y -axis. The segment $\{(0, v) / -1 < v < 1\}$ is a slice for the action of P on D^2 . The orbit \mathcal{O}_v through $(0, v)$ is the intersection of D^2 with the circle passing through $(0, v)$, $\mathbf{p} = (0, 1)$ and tangent to ∂D^2 at \mathbf{p} . Denote by \mathcal{O}^- and by \mathcal{O}^+ the orbits of P through $\gamma_{\mathbf{p}}(0)$ and $\gamma_{\mathbf{p}}(\omega_{\mathbf{p}}/2)$ respectively, referred to as the *lower and upper osculating circles* of $\gamma_{\mathbf{p}}$. The trajectory $|\gamma_{\mathbf{p}}|$ is contained in the lunular region of D^2 bounded by \mathcal{O}^+ and \mathcal{O}^- ; is tangent to \mathcal{O}^- at $\gamma_{\mathbf{p}}(n\omega_{\mathbf{p}})$, $n \in \mathbb{Z}$, and to \mathcal{O}^+ at $\gamma_{\mathbf{p}}(\omega_{\mathbf{p}}/2 + n\omega_{\mathbf{p}})$, $n \in \mathbb{Z}$, with limit point

$$\lim_{s \rightarrow +\infty} \gamma_{\mathbf{p}}(s) = \lim_{s \rightarrow -\infty} \gamma_{\mathbf{p}}(s) = \mathbf{p}.$$

When $\lambda \rightarrow -1^-$, \mathcal{O}^- and $|\gamma_{\mathbf{p}}|$ tend to $\mathcal{O}_{2-\sqrt{2}}$. When λ decreases, $|\gamma_{\mathbf{p}}|$ and \mathcal{O}^- inflect (ie. their radii shrink) and, when $\lambda \rightarrow -\infty$, tend to \mathbf{p} . Figure 3 reproduces the trajectories of BL-curves with $\lambda = -1.01, -1.17, -1.3$ and -2 , respectively (all numerical values are rounded up to a maximum of two decimals).

3.2. BS-Curves. Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{S}$. The corresponding B-curves have space-like momentum and $c > 0$ holds in the conservation law (2.4).

Theorem 3.13. Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{S}$ and $\mu_{\mathbf{p}}$ be the solution of (2.4) with initial condition $\mu_{\mathbf{p}}(0) = e_2$, where $c > 0$ is as in (vi) of (3.1). Define $\Theta_{\mathbf{p}}$ by

$$\Theta_{\mathbf{p}}(s) = 2\sqrt{c} \int_0^s \frac{\mu_{\mathbf{p}}^2(\mu_{\mathbf{p}} + 2\lambda)}{1 + 4c\mu_{\mathbf{p}}^2} ds.$$

Then,

$$(3.10) \quad \gamma_{\mathbf{p}} = \frac{1}{2\sqrt{c}\mu_{\mathbf{p}}} \left(\sqrt{1 + 4c\mu_{\mathbf{p}}^2} \cosh(\Theta_{\mathbf{p}}), \sqrt{1 + 4c\mu_{\mathbf{p}}^2} \sinh(\Theta_{\mathbf{p}}), 1 \right)$$

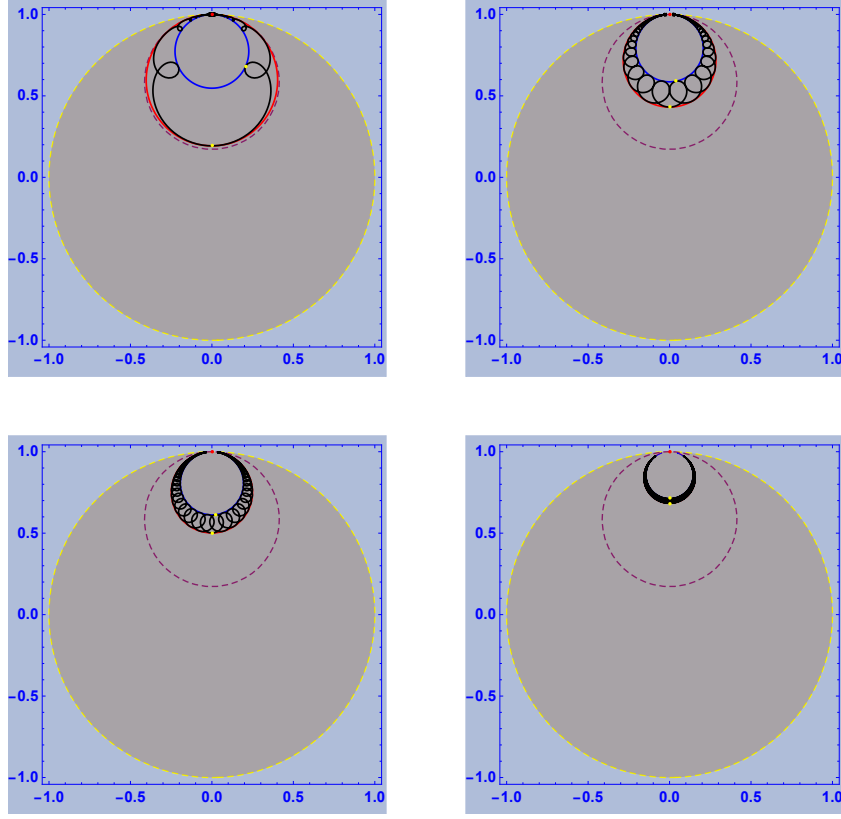


FIGURE 3. Trajectories of BL-curves with decreasing multiplier λ . The red and blue curves are the osculating circles. The dashed purple curve is the limit circle $\mathcal{O}_{2-\sqrt{2}}$.

is a BS-curve with modulus \mathfrak{p} and momentum $\vec{\xi} = (0, 0, -\sqrt{c})$. There are no BS-strings.

Proof. The first part of the proof is analogous to the first part of Theorem 3.10. For the sake of brevity, we omit it here.

We prove that there are no BS-strings. As customary in our proofs, we avoid explicitly writing the dependence upon \mathfrak{p} . By contradiction suppose that γ is periodic. From (3.10) it follows that $\Theta(\omega) = 0$ and that ω is the least period of the curvature κ , ie. the wavelength. In this case, this implies that ω is also the least period of γ . Since

$$f(s) = \frac{\mu^2(\mu + 2\lambda)}{1 + 4c\mu^2}$$

is even and periodic with period ω , the function Θ is odd, periodic with period ω , and such that

$$\Theta(\omega) = 2\sqrt{c} \int_0^\omega f(s) ds = 2\sqrt{c} \int_{-\omega/2}^{\omega/2} f(s) ds = 4\sqrt{c} \int_0^{\omega/2} f(s) ds = 2\Theta(\omega/2).$$

Then, $\Theta(\omega/2) = 0$. The function μ is strictly increasing on $(0, \omega/2)$ and strictly decreasing on $(\omega/2, \omega)$. Then, $\Gamma_1 = \gamma([0, \omega/2])$ and $\Gamma_2 = \gamma([\omega/2, \omega])$ are simple closed arcs with distinct boundary points

$$\begin{aligned}\vec{p}_0 = \gamma(0) &= \frac{1}{2\sqrt{2}e_2} \left(\sqrt{1 + 4ce_2^2}, 0, 1 \right), \\ \vec{p}_2 = \gamma(\omega/2) &= \frac{1}{2\sqrt{2}e_1} \left(\sqrt{1 + 4ce_1^2}, 0, 1 \right),\end{aligned}$$

such that $\gamma(\mathbb{R}) = \Gamma_1 \cup \Gamma_2$. Taking into account that $\mu(0) = e_2 < -2\lambda < e_1 = \mu(\omega/2)$ and recalling that μ is strictly increasing on $(0, \omega/2)$ and strictly decreasing on $(\omega/2, \omega)$, the equation $\mu + 2\lambda = 0$ possesses exactly one solution s' in the interval $(0, \omega/2)$ and exactly one solution s'' in the interval $(\omega/2, \omega)$. Thus,

$$\begin{cases} \mu(s) + 2\lambda < 0, & s \in [0, s'), \\ \mu(s) + 2\lambda > 0, & s \in (s', s''), \\ \mu(s) + 2\lambda < 0, & s \in (s'', \omega]. \end{cases}$$

This implies that Θ is strictly decreasing on $(0, s')$, strictly increasing on (s', s'') and strictly decreasing on (s'', ω) . Since $\Theta(0) = \Theta(\omega/2) = \Theta(\omega) = 0$, we have

$$\Theta(s) < 0, \quad \forall s \in (0, \omega/2), \quad \Theta(s) > 0, \quad \forall s \in (\omega/2, \omega).$$

Therefore,

$$\Gamma_1 \setminus \{\vec{p}_1, \vec{p}_2\} \subset \{\vec{x} \in \mathbb{R}^{1,2} / x^2 < 0\}, \quad \Gamma_2 \setminus \{\vec{p}_1, \vec{p}_2\} \subset \{\vec{x} \in \mathbb{R}^{1,2} / x^2 > 0\}.$$

Hence γ is a simple closed curve with two vertices, namely, $\gamma(0)$ and $\gamma(\omega/2)$. This conclusion contradicts the Four Vertex Theorem (Theorem 2.4). Consequently, γ cannot be closed. \square

Definition 3.14. The BS-curve $\gamma_{\mathbf{p}}$ given by (3.10) is referred to as the *standard BS-curve* with modulus $\mathbf{p} \in \mathcal{S}$.

Remark 3.15. Every BS-curve with modulus $\mathbf{p} \in \mathcal{S}$ is equivalent to $\gamma_{\mathbf{p}}$, (3.10). From now on we implicitly assume that the BS-curves in consideration are in their standard form.

Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{S}$ and $\gamma_{\mathbf{p}}$ be the standard BS-curve with modulus \mathbf{p} . Resorting to the Poincaré model, the parameterization of $\gamma_{\mathbf{p}}$ is

$$\gamma_{\mathbf{p}} = \frac{1}{2\sqrt{c}\mu_{\mathbf{p}} + \sqrt{1 + 4c\mu_{\mathbf{p}}^2} \cosh(\Theta_{\mathbf{p}})} \left(\sqrt{1 + 4c\mu_{\mathbf{p}}^2} \sinh(\Theta_{\mathbf{p}}), 1 \right).$$

The stabilizer of the momentum is the subgroup

$$\mathcal{O}_+^\uparrow(1, 1) = \left\{ \text{HR}(t) = \begin{pmatrix} \cosh(t) & \sinh(t) & 0 \\ \sinh(t) & \cosh(t) & 0 \\ 0 & 0 & 1 \end{pmatrix} / t \in \mathbb{R} \right\}.$$

The monodromy \mathbf{m} is the non-trivial element $\text{HR}(\Theta_{\mathbf{p}}(\omega_{\mathbf{p}}))$ of $\mathcal{O}_+^\uparrow(1, 1)$. Let $\Gamma = \gamma_{\mathbf{p}}([0, \omega_{\mathbf{p}}])$ be the fundamental arc, then $|\gamma_{\mathbf{p}}| = \cup_{n \in \mathbb{Z}} \mathbf{m}^n(\Gamma)$. Since the curvature is an even function, $|\gamma_{\mathbf{p}}|$ and Γ are invariant by the reflection with respect to the Oy-axis. The segment $\{(0, v) / -1 < v < 1\}$ is a slice for the action of $\mathcal{O}_+^\uparrow(1, 1)$ on \mathbb{D}^2 . The orbit \mathcal{O}_v through $(0, v)$ is the intersection of \mathbb{D}^2 with the circle passing through $(0, v)$, $\mathbf{p}_+ = (1, 0)$ and $\mathbf{p}_- = (-1, 0)$. Denote by \mathcal{O}^- and by \mathcal{O}^+ the orbits

of $O_+^\dagger(1, 1)$ through $\gamma_p(0)$ and $\gamma_p(\omega_p/2)$ respectively, referred to as the *lower and upper osculating circular arcs* of γ_p . The trajectory $||[\gamma_p]||$ is contained in the lunular region of D^2 bounded by \mathcal{O}^+ and \mathcal{O}^- ; is tangent to \mathcal{O}^+ at $\gamma_p(n\omega_p)$, $n \in \mathbb{Z}$, and to \mathcal{O}^- at $\gamma_p(\omega_p/2 + n\omega_p)$, $n \in \mathbb{Z}$, with limit points

$$\lim_{s \rightarrow +\infty} \gamma_p(s) = p_+, \quad \lim_{s \rightarrow -\infty} \gamma_p(s) = p_-.$$

Choose $\lambda \in (-\infty, -1)$. Put $L_\lambda = (\eta_-(\lambda), b_0(\lambda))$ and consider the 1-parameter family $\{\gamma_p\}_{e_2 \in L_\lambda}$ of BS-curves with multiplier λ . Recall that the graph of the function η_- (2.8) is the lower boundary of the moduli space \mathcal{S} , while the graph of b_0 (3.7) is the upper boundary. The function

$$v_\lambda^+ : e_2 \in L_\lambda \mapsto \frac{1}{2\sqrt{c}e_2 + \sqrt{1 + 4ce_2^2}} \in \mathbb{R},$$

where $c = c(\lambda, e_2) > 0$ is as in (vi) of (3.1), is convex, attains the minimum at $e_2 = -\lambda$, and satisfies

$$\lim_{e_2 \rightarrow \eta_-(\lambda)^+} v_\lambda(e_2) = v_\lambda^*, \quad \lim_{e_2 \rightarrow b_0(\lambda)^+} v_\lambda(e_2) = 1,$$

where

$$v_\lambda^* = \frac{1}{2\sqrt{c(\lambda, \eta_-(\lambda))\eta_-(\lambda) + \sqrt{1 + 4c(\lambda, \eta_-(\lambda))\eta_-(\lambda)^2}} < 1.$$

Let $e_2^*(\lambda)$ be the unique element of L_λ such that $v_\lambda^+(e_2^*(\lambda)) = v_\lambda^*$.

We are now in a position to describe the main features of the kinematics of the 1-parameter family $\{\gamma_p\}_{e_2 \in L_\lambda}$. When e_2 varies in the interval L_λ the curves of the family tend to two asymptotic positions and evolve in five intermediate stages with contracting and expanding phases:

- When $e_2 \rightarrow \eta_-(\lambda)^+$, the osculating arc \mathcal{O}^+ and $||[\gamma_p]||$ tend to the asymptotic position $\mathcal{O}_{v_\lambda^*}$.
- When $e_2 \in (\eta_-(\lambda), -\lambda)$, the radius of circular arc \mathcal{O}^+ increases (ie. \mathcal{O}^+ and $||[\gamma_p]||$ deflect). The evolution of the curve is in a contracting phase.
- When $e_2 = -\lambda$ the radius of the osculating circular arc \mathcal{O}^+ assume its maximum value.
- When $e_2 \in (-\lambda, e_2^*(\lambda))$, the radius of \mathcal{O}^+ decreases (ie. \mathcal{O}^+ and $||[\gamma_p]||$ inflect). The evolution of the curve is in an expanding phase.
- When $e_2 = e_2^*(\lambda)$, the osculating arc \mathcal{O}^+ returns to the limit position $\mathcal{O}_{v_\lambda^*}$.
- When $e_2 \in (e_2^*(\lambda), \eta_-(\lambda))$, the radius of \mathcal{O}^+ decreases (ie. \mathcal{O}^+ and $||[\gamma_p]||$ inflect). The evolution of the curve is in an expanding phase.
- When $e_2 \rightarrow b_0(\lambda)^-$, $||[\gamma_p]||$ and its osculating arc \mathcal{O}^+ tend to the upper hemisphere $\partial D^2 \cap \{(u, v) \in \mathbb{R}^2 / v > 0\}$ of the ideal boundary.

Figure 4 represents all stages of the evolution of the BS-curves of the family $\{\gamma_p\}_{e_2 \in L_\lambda}$, for the multiplier $\lambda = -1.1$. The trajectory of the BS-curves are colored in black, the upper osculating arcs \mathcal{O}^+ in red and the lower ones \mathcal{O}^- in blue. The asymptotic limit position $\mathcal{O}_{v_\lambda^*}$ is the purple dashed circular arc and the asymptotic limit position as $e_2 \rightarrow b_0(\lambda)^-$ is the dashed dark-red upper hemisphere of the ideal boundary. In the first two images ($e_2 = 0.92$ and $e_2 = 1$, respectively) two BS-curves in their contracting phases are reproduced. In the third image we show the BS-curve when it reaches its maximally contracted position and the radius of the upper osculating arc \mathcal{O}^+ reaches its maximum ($e_2 = -\lambda = 1.1$). A subsequent BS-curve in its expanding phase is shown in the fourth image ($e_2 = 1.2$). The first

image of the second row ($e_2 = e_2^*(\lambda) \approx 1.28$) reproduces the BS-curve when the upper osculating arc \mathcal{O}^+ returns to the asymptotic position $\mathcal{O}_{v_\lambda^*}$. The last three images ($e_2 = 1.54, 1.55$ and 1.56) depict BS-curves in their expanding phases evolving toward the maximally expanded asymptotic limit (the upper semicircle of the ideal boundary).

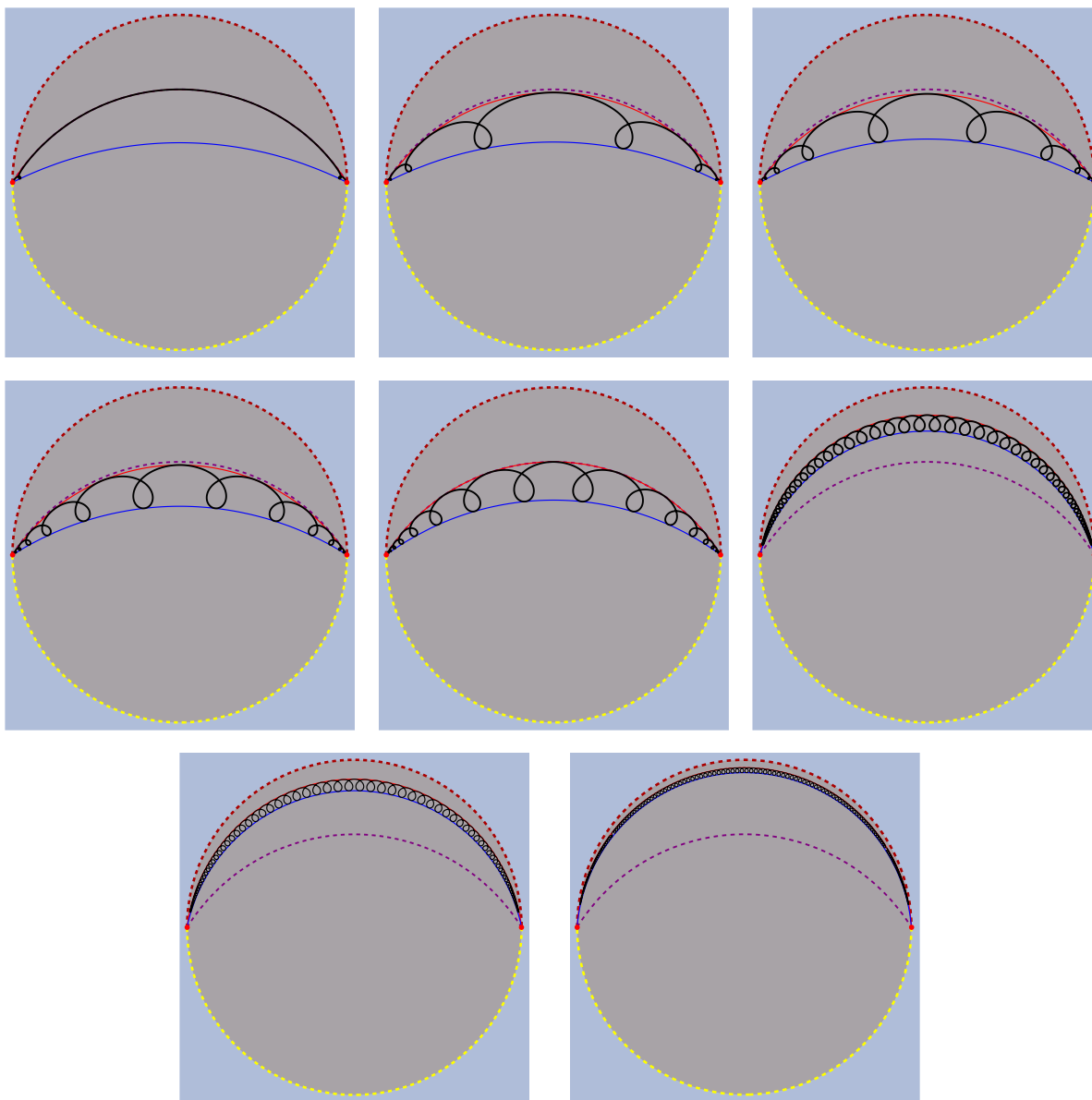


FIGURE 4. Trajectories of BS-curves with multiplier $\lambda = -1.1$ and increasing values of $e_2 \in L_\lambda$.

3.3. BT-Curves. Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$. The B-curves associated with $\mathbf{p} \in \mathcal{T}$ have time-like momentum. Their Blaschke invariant $\mu_{\mathbf{p}}$ is the solution of (2.4) with $c < 0$ and $\mu_{\mathbf{p}}(0) = e_2$. This case is analogous to the spherical one. Thus, we proceed as in [34] by introducing the exceptional locus and by defining the radial and angular functions, whose behavior will be essential in the description of the BT-curves.

Definition 3.16. The curve $\mathcal{E} = \{(\lambda, e_2) \in \mathfrak{P} / 1 + 4ce_1^2 = 0\}$ contained in the moduli space \mathfrak{P} is the *exceptional locus*.

Remark 3.17. The exceptional locus \mathcal{E} is characterized by each one of the following equations:

$$(3.11) \quad \begin{cases} (i) & e_1 + 2\lambda = 0, \\ (ii) & 1 + 16c\lambda^2 = 0, \\ (iii) & e_1^2 e_2^3 - e_1^3 e_2^2 + e_1 + e_2 = 0, \end{cases}$$

or as the graph of the function $c : (-\infty, -\sqrt[4]{\varphi^5}/2) \rightarrow (\sqrt[4]{\varphi}, +\infty)$ defined by

$$(3.12) \quad c(\lambda) = -\frac{2}{3}\lambda + \frac{1}{3\lambda^2} \mathfrak{R} \left(\sqrt[3]{-69\lambda^9 + 72\lambda^5 - 3i\lambda^3 \sqrt{768\lambda^8 + 528\lambda^4 + 3}} \right),$$

where $\varphi = (1 + \sqrt{5})/2$ is the golden ratio. See Figures 2 and 5.

Let η_{\pm} and c be as in (2.8) and (3.12), respectively. Define $a : (-\infty, -2/\sqrt[4]{27}) \rightarrow \mathbb{R}$ by

$$a(\lambda) = \begin{cases} \sqrt{\lambda^2 - 1} - \lambda, & \lambda \leq -1, \\ \eta_-(\lambda), & -1 < \lambda < -2/\sqrt[4]{27}. \end{cases}$$

Then, $a(\lambda) < \eta_+(\lambda)$, for all $\lambda < -2/\sqrt[4]{27}$, and $a(\lambda) < c(\lambda) < \eta_+(\lambda)$, for all $\lambda < -\sqrt[4]{\varphi^5}/2$. We decompose \mathcal{T} as the disjoint union $\mathcal{T} = \mathcal{T}_- \cup \mathcal{E} \cup \mathcal{T}_+$ of the exceptional locus \mathcal{E} with a lower domain (the green region of Figure 5),

$$\mathcal{T}_- = \{(\lambda, e_2) \in \mathcal{T} / \lambda < -\sqrt[4]{\varphi^5}/2, a(\lambda) < e_2 < c(\lambda)\},$$

and an upper domain (the brown domain of Figure 5),

$$\begin{aligned} \mathcal{T}_+ = & \{(\lambda, e_2) \in \mathcal{T} / \lambda < -\sqrt[4]{\varphi^5}/2, c(\lambda) \leq e_2 < \eta_+(\lambda)\} \cup \\ & \{(\lambda, e_2) \in \mathcal{T} / -\sqrt[4]{\varphi^5}/2 \leq \lambda < -2/\sqrt[4]{27}, a(\lambda) < e_2 < \eta_+(\lambda)\}. \end{aligned}$$

Definition 3.18. Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$ and $\mu_{\mathbf{p}}$ be the solution of (2.4) with initial condition $\mu_{\mathbf{p}}(0) = e_2$ where $c < 0$ is as in (vi) of (3.1). The *radial function* $\varrho_{\mathbf{p}}$ is defined by:

- If $\mathbf{p} \notin \mathcal{E}$,

$$\varrho_{\mathbf{p}} = \frac{\sqrt{1 + 4c\mu_{\mathbf{p}}^2}}{2\sqrt{|c|}\mu_{\mathbf{p}}}.$$

- If $\mathbf{p} \in \mathcal{E}$,

$$\varrho_{\mathbf{p}} = \begin{cases} \frac{\sqrt{1 + 4c\mu_{\mathbf{p}}^2}}{2\sqrt{|c|}\mu_{\mathbf{p}}}, & \text{on } [-\frac{\omega_{\mathbf{p}}}{2}, \frac{\omega_{\mathbf{p}}}{2}], \\ -\frac{\sqrt{1 + 4c\mu_{\mathbf{p}}^2}}{2\sqrt{|c|}\mu_{\mathbf{p}}}, & \text{on } [\frac{\omega_{\mathbf{p}}}{2}, \frac{3\omega_{\mathbf{p}}}{2}]. \end{cases}$$

We now describe the main features of the radial functions (see Figure 6):

- The radial function $\varrho_{\mathbf{p}}$ is real-analytic, even and periodic, for every $\mathbf{p} \in \mathcal{T}$.

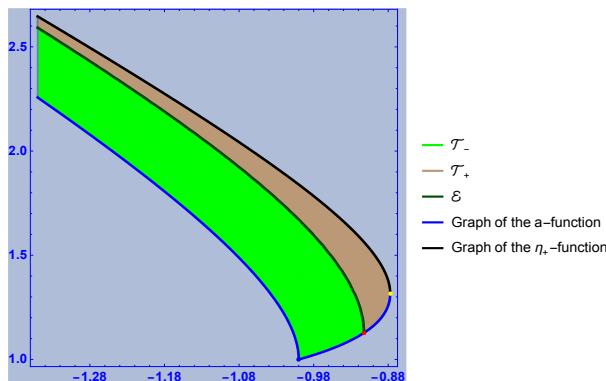


FIGURE 5. The decomposition of the moduli space \mathcal{T} as $\mathcal{T} = \mathcal{T}_- \cup \mathcal{E} \cup \mathcal{T}_+$.

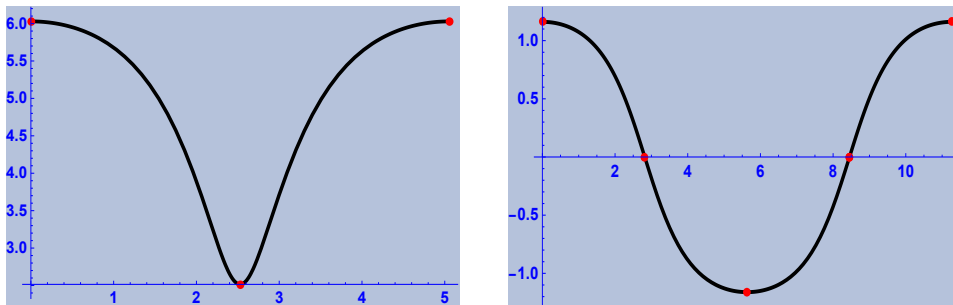


FIGURE 6. The graphs of the radial functions $\varrho_{\mathbf{p}}$ with $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$. Left: Non-exceptional case $\lambda = -0.99$ and $e_2 = 1.05$ represented from 0 to the least period $\omega_{\mathbf{p}}$. Right: Exceptional case $\lambda = -0.91$ and $e_2 = 1.19$ represented from 0 to the least period $2\omega_{\mathbf{p}}$.

- If $\mathbf{p} \notin \mathcal{E}$, $\varrho_{\mathbf{p}} > 0$ with least period $\omega_{\mathbf{p}}$. It attains the maximum at $h\omega_{\mathbf{p}}$ and the minimum at $\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}$, $h \in \mathbb{Z}$. It is strictly decreasing on $[h\omega_{\mathbf{p}}, \omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}]$ and strictly increasing on $[\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}, (h+1)\omega_{\mathbf{p}}]$, $h \in \mathbb{Z}$.
- If $\mathbf{p} \in \mathcal{E}$, $\varrho_{\mathbf{p}}$ is periodic, with least period $2\omega_{\mathbf{p}}$. It is strictly positive on $(\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}, \omega_{\mathbf{p}}/2 + (h+1)\omega_{\mathbf{p}})$, $h \in \mathbb{Z}$ and $\text{mod}(h, 2) = 1$, and strictly negative on $(\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}, \omega_{\mathbf{p}}/2 + (h+1)\omega_{\mathbf{p}})$, $h \in \mathbb{Z}$ and $\text{mod}(h, 2) = 0$. It is strictly decreasing on $[h\omega_{\mathbf{p}}, (h+1)\omega_{\mathbf{p}}]$, $\text{mod}(h, 2) = 0$, and strictly increasing on $[h\omega_{\mathbf{p}}, (h+1)\omega_{\mathbf{p}}]$, $\text{mod}(h, 2) = 1$.

Definition 3.19. Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$ and $\mu_{\mathbf{p}}$ be the solution of (2.4) with initial condition $\mu_{\mathbf{p}}(0) = e_2$ where $c < 0$ is as in (vi) of (3.1). The *angular function* $\Theta_{\mathbf{p}}$ is defined by:

- If $\mathbf{p} \notin \mathcal{E}$,

$$\Theta_{\mathbf{p}}(s) = 2\sqrt{|c|} \int_0^s \frac{\mu_{\mathbf{p}}^2(\mu_{\mathbf{p}} + 2\lambda)}{1 + 4c\mu_{\mathbf{p}}^2} ds.$$

- If $\mathbf{p} \in \mathcal{E}$,

$$\Theta_{\mathbf{p}}(s) = -8\sqrt{|c|}\lambda^2 \int_0^s \frac{\mu_{\mathbf{p}}^2}{\mu_{\mathbf{p}} - 2\lambda} ds.$$

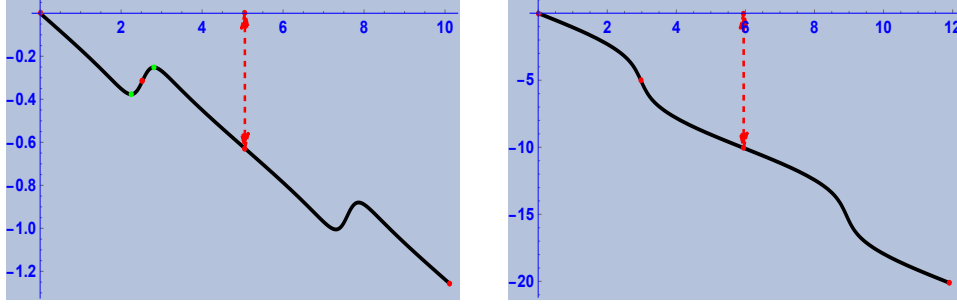


FIGURE 7. The graphs of the angular functions $\Theta_{\mathbf{p}}$ with $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$, represented from 0 to two least periods $2\omega_{\mathbf{p}}$. Left: Case $\mathbf{p} \in \mathcal{T}_-$ where $\lambda = -0.99$ and $e_2 = 1.05$. Right: Case $\mathbf{p} \in \mathcal{T}_+$ where $\lambda = -0.9$ and $e_2 = 1.24$. The dashed arrow represents the value $\Theta_{\mathbf{p}}(\omega_{\mathbf{p}})$. If the length of this arrow is a rational multiple of 2π , the BT-curve $\gamma_{\mathbf{p}}$ will be closed (see Section 4).

We now describe the main features of the angular functions (see Figure 7):

- The angular function $\Theta_{\mathbf{p}}$ is an odd quasi-periodic function with least quasi-period $\omega_{\mathbf{p}}$.
- The function $\Theta_{\mathbf{p}}$ tends to $-\infty$ when $s \rightarrow +\infty$ and to $+\infty$ when $s \rightarrow -\infty$.
- If $\mathbf{p} \in \mathcal{E} \cup \mathcal{T}_+$, $\Theta_{\mathbf{p}}$ is strictly decreasing, with ascending inflection points at $\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}$, $h \in \mathbb{Z}$ and descending inflection points at $\omega_{\mathbf{p}} + h\omega_{\mathbf{p}}$, $h \in \mathbb{Z}$.
- If $\mathbf{p} \in \mathcal{T}_-$, $\Theta_{\mathbf{p}}$ has a relative minimum at $s_{\mathbf{p}}^* \in (0, \omega_{\mathbf{p}}/2)$ and a relative maximum at $s_{\mathbf{p}}^{**} = \omega_{\mathbf{p}} - s_{\mathbf{p}}^*$. There are no other critical points in the interval $[0, \omega_{\mathbf{p}}]$. $\Theta_{\mathbf{p}}$ has descending inflection points at $\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}}$, $h \in \mathbb{Z}$ and ascending inflection points at $\omega_{\mathbf{p}} + h\omega_{\mathbf{p}}$, $h \in \mathbb{Z}$.

Once the radial and angular functions have been introduced and their behavior described, we can proceed with the parameterization of BT-curves.

Theorem 3.20. *Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$ and $\mu_{\mathbf{p}}$ be the solution of (2.4) with initial condition $\mu_{\mathbf{p}}(0) = e_2$ where $c < 0$ is as in (vi) of (3.1). Let $\varrho_{\mathbf{p}}$ and $\Theta_{\mathbf{p}}$ be the radial and angular functions defined above, respectively. Then,*

$$(3.13) \quad \gamma_{\mathbf{p}} = \left(\frac{1}{2\sqrt{|c|}\mu_{\mathbf{p}}}, -\varrho_{\mathbf{p}} \cos(\Theta_{\mathbf{p}}), \varrho_{\mathbf{p}} \sin(\Theta_{\mathbf{p}}) \right)$$

is a BT-curve with modulus \mathbf{p} and momentum $\vec{\xi} = (\sqrt{|c|}, 0, 0)$.

Proof. The proof of this theorem is analogous to the previous cases (see Theorem 3.10). \square

Definition 3.21. The BT-curve $\gamma_{\mathbf{p}}$ given by (3.13) is referred to as the *standard BT-curve* with modulus $\mathbf{p} \in \mathcal{T}$.

Remark 3.22. Every BT-curve with modulus $\mathbf{p} \in \mathcal{T}$ is equivalent to $\gamma_{\mathbf{p}}$, (3.13). From now on we implicitly assume that the BT-curves in consideration are in their standard form.

Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{T}$ and $\gamma_{\mathbf{p}}$ be the standard BT-curve with modulus \mathbf{p} . In the Poincaré model, $\gamma_{\mathbf{p}}$ can be written as

$$(3.14) \quad \gamma_{\mathbf{p}} = \frac{2\sqrt{|c|} \varrho_{\mathbf{p}} \mu_{\mathbf{p}}}{1 + 2\sqrt{|c|} \mu_{\mathbf{p}}} (-\cos(\Theta_{\mathbf{p}}), \sin(\Theta_{\mathbf{p}})).$$

Thus, $||[\gamma_{\mathbf{p}}]||$ is contained in the region

$$D_{\mathbf{p}}^2 = \{\zeta \in D^2 / r'_{\mathbf{p}} \leq |\zeta| \leq r''_{\mathbf{p}}\},$$

where

$$\begin{cases} r'_{\mathbf{p}} = \min \left| \frac{2\sqrt{|c|} \varrho_{\mathbf{p}} \mu_{\mathbf{p}}}{1 + 2\sqrt{|c|} \mu_{\mathbf{p}}} \right| = \frac{\sqrt{1 + 4ce_1^2}}{1 + 2\sqrt{|c|} e_1}, \\ r''_{\mathbf{p}} = \max \left| \frac{2\sqrt{|c|} \varrho_{\mathbf{p}} \mu_{\mathbf{p}}}{1 + 2\sqrt{|c|} \mu_{\mathbf{p}}} \right| = \frac{\sqrt{1 + 4ce_2^2}}{1 + 2\sqrt{|c|} e_2}. \end{cases}$$

From this we see that $r'_{\mathbf{p}} = 0$ if and only if $1 + 4ce_1^2 = 0$, or in other words using the definition of the exceptional locus, if and only if $\mathbf{p} \in \mathcal{E}$. Consequently, the trajectory $||[\gamma_{\mathbf{p}}]||$ passes through the origin if and only if $\mathbf{p} \in \mathcal{E}$. In this case $D_{\mathbf{p}}^2$ is a disk. Otherwise $D_{\mathbf{p}}^2$ is an annulus and the outer and inner circles bounding $D_{\mathbf{p}}^2$, denoted by \mathcal{O}^{\pm} are said the *outer and inner osculating circles*. The trajectory $||[\gamma_{\mathbf{p}}]||$ is tangent to \mathcal{O}^+ at $\gamma_{\mathbf{p}}(h\omega_{\mathbf{p}})$, $h \in \mathbb{Z}$ and is tangent to \mathcal{O}^- at $\gamma_{\mathbf{p}}(\omega_{\mathbf{p}}/2 + h\omega_{\mathbf{p}})$, $h \in \mathbb{Z}$. From (3.13) it follows that $\gamma_{\mathbf{p}}$ is closed if and only if $\Theta_{\mathbf{p}}(\omega_{\mathbf{p}})/2\pi \in \mathbb{Q}$. Otherwise $||[\gamma_{\mathbf{p}}]||$ is a dense subset of $D_{\mathbf{p}}^2$. Several closed examples will be illustrated in Figures 11 and 12.

4. BT-STRINGS

In this section we will study the existence of BT-strings and the kinematics of their corresponding isomonodromic family. As mentioned above a BT-curve $\gamma_{\mathbf{p}}$ will be closed if and only if its angular function $\Theta_{\mathbf{p}}$ evaluated at the wavelength $\omega_{\mathbf{p}}$ is a rational multiple of 2π (the quantity $\Theta_{\mathbf{p}}(\omega_{\mathbf{p}})$ is represented in Figure 7 by the dashed arrow). In order to analyze this closure condition we will define a couple of functions which will appear in an essential way.

Definition 4.1. Let $\mathbf{p} \in \mathcal{T}$ and $\gamma_{\mathbf{p}}$ be the BT-curve with modulus \mathbf{p} . The *period map* $\mathcal{P} : \mathcal{T} \rightarrow \mathbb{R}$ is defined by

$$\mathcal{P}(\mathbf{p}) = \begin{cases} -\frac{1}{2\pi} \Theta_{\mathbf{p}}(\omega_{\mathbf{p}}) + 1, & \text{if } \mathbf{p} \in \mathcal{T}_-, \\ -\frac{1}{2\pi} \Theta_{\mathbf{p}}(\omega_{\mathbf{p}}) + \frac{1}{2}, & \text{if } \mathbf{p} \in \mathcal{E}, \\ -\frac{1}{2\pi} \Theta_{\mathbf{p}}(\omega_{\mathbf{p}}), & \text{if } \mathbf{p} \in \mathcal{T}_+, \end{cases}$$

where $\Theta_{\mathbf{p}}$ is the angular function and $\omega_{\mathbf{p}}$ is the wavelength, ie. the least period of the Blaschke invariant of $\gamma_{\mathbf{p}}$.

Remark 4.2. Since $\mathcal{P}(\mathbf{p}) \cong -\Theta_{\mathbf{p}}(\omega_{\mathbf{p}})/2\pi \pmod{\mathbb{Q}}$ we conclude that $\gamma_{\mathbf{p}}$ is closed (ie. a BT-string) if and only if $\mathcal{P}(\mathbf{p}) \in \mathbb{Q}$. Hence, in order to prove the existence of BT-strings, it suffices to check that, for fixed multiplier λ , the image of $\mathcal{P} \equiv \mathcal{P}_{\lambda}$ is not constant, ie. $\mathcal{P}_{\lambda}(e_2)$ attains different values as e_2 varies in $I_{\lambda} = (a(\lambda), \eta_+(\lambda))$. Recall that the graph of the function a is the lower boundary of the moduli space \mathcal{T} , while the graph of η_+ is the upper boundary.

Definition 4.3. Let $\mathfrak{p} \in \mathcal{T}$ and $\gamma_{\mathfrak{p}}$ be the BT-curve with modulus \mathfrak{p} . The function $\chi : (-\infty, -2/\sqrt[4]{27}) \rightarrow \mathbb{R}$ is defined by

$$\chi(\lambda) = \frac{\eta_+(\lambda)^4 - 1}{\sqrt{\eta_+(\lambda)^8 - 4\eta_+(\lambda)^4 + 3}} \in \mathbb{R},$$

where $\eta_+(\lambda)$ is the function defined in (2.8).

Remark 4.4. The function χ is strictly increasing and tends to 1 when $\lambda \rightarrow -\infty$ and to $+\infty$ when $\lambda \rightarrow -2/\sqrt[4]{27}^-$.

We denote by J_λ the open interval

$$J_\lambda = \begin{cases} (1, \chi(\lambda)), & \lambda \leq -1, \\ (\chi(\lambda), +\infty), & -1 < \lambda < -2/\sqrt[4]{27}. \end{cases}$$

The following result shows the existence of infinitely many BT-strings for every multiplier $\lambda < -2/\sqrt[4]{27}$.

Theorem 4.5. For every $\lambda < -2/\sqrt[4]{27}$ and every $q = m/n \in J_\lambda \cap \mathbb{Q}$ there exist $\mathfrak{p} = (\lambda, e_2) \in \mathcal{T}$ such that $\gamma_{\mathfrak{p}}$ is a BT-string with $\mathcal{P}(\mathfrak{p}) = q$.

Proof. The proof of this result is a direct consequence of the following claim involving the limits of the period map:

Claim. Let $I_\lambda = (a(\lambda), \eta_+(\lambda))$. The period map $\mathcal{P}_\lambda : I_\lambda \rightarrow \mathbb{R}$ defined by $\mathcal{P}_\lambda(e_2) = \mathcal{P}(\lambda, e_2)$ is continuous. Moreover:

- If $\lambda \leq -1$,

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = 1, \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathcal{P}_\lambda(e_2) = \chi(\lambda).$$

- If $-1 < \lambda < -2/\sqrt[4]{27}$,

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = +\infty, \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathcal{P}_\lambda(e_2) = \chi(\lambda).$$

For the sake of clarity, the proof of this claim will be postponed to the appendix. \square

We anticipate some properties of the functions $\mathcal{P}_\lambda : e_2 \rightarrow \mathcal{P}(\lambda, e_2)$ that will be proved in the appendix as part of the proof of the existence of BT-strings. The purpose is to highlight the interrelationships between the behavior of the functions \mathcal{P}_λ and the geometry of the modified invariant signatures of critical curves with multiplier λ . Denote by $\hat{\mathfrak{S}}_{\lambda, e_2}$ the modified invariant signature of a B-curve with modulus $\mathfrak{p} = (\lambda, e_2) \in \mathfrak{P}$. There are three cases to be considered:

- (1) Case $\lambda < -1$. Then $(\lambda, a(\lambda)) \in \mathcal{L}$ is the modulus of a BL-curve whose modified invariant signature $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$ is closed. The modified invariant signatures $\hat{\mathfrak{S}}_{\lambda, e_2}$, $e_2 \in I_\lambda$ are contained in the internal region bounded by $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$. When $e_2 \rightarrow a(\lambda)^+$ the signature $\hat{\mathfrak{S}}_{\lambda, e_2}$ tends to $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$ and when $e_2 \rightarrow \eta_+(\lambda)^-$, $\hat{\mathfrak{S}}_{\lambda, e_2}$ contracts, tending to the stable equilibrium point $(\eta_+(\lambda), 0)$ (see the picture on the left of Figure 8). The function \mathcal{P}_λ is strictly increasing (this assertion is only supported by the experimental evidence). When $e_2 \rightarrow a(\lambda)^+$, \mathcal{P}_λ tends to 1 and when $e_2 \rightarrow \eta_+(\lambda)^-$, \mathcal{P}_λ tends to $\chi(\lambda)$.

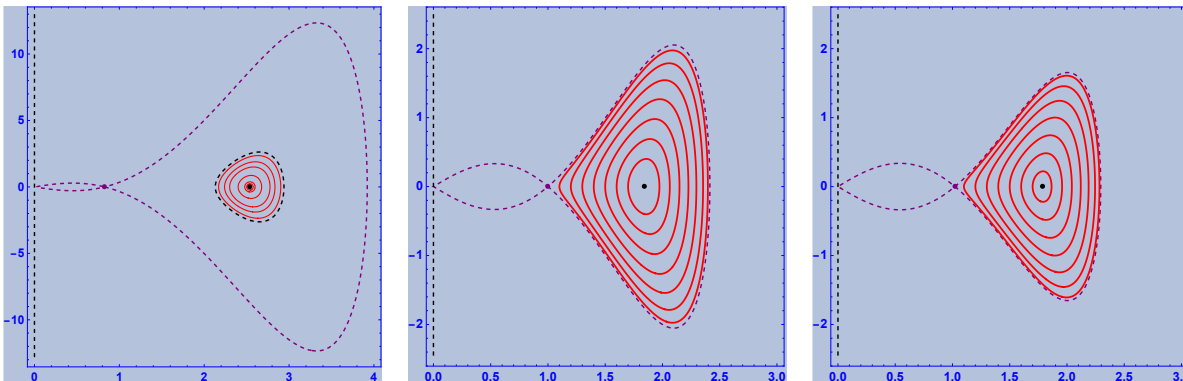


FIGURE 8. Left: The modified invariant signatures $\hat{\mathfrak{S}}_{\lambda, e_2}$, $e_2 \in (a(\lambda), \eta_+(\lambda))$ (red) and the signature $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$ (dashed-black), for $\lambda = -1.3$. Center: The modified invariant signatures $\hat{\mathfrak{S}}_{-1, e_2}$, $e_2 \in (1, \eta_+(\lambda))$ (red) and the signature $\hat{\mathfrak{S}}_{-1, 1}$ (dashed-black). Right: The modified invariant signatures $\hat{\mathfrak{S}}_{\lambda, e_2}$, $e_2 \in (a(\lambda), \eta_+(\lambda))$ (red) and the signature $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$ (dashed-black), for $\lambda = -0.98$.

- (2) Case $\lambda = -1$. Then $a(-1) = 1$ and the signature $\hat{\mathfrak{S}}_{-1, 1}$ is the unstable equilibrium point $(1, 0)$. Let $\hat{\mathfrak{S}}_{-1}^*$ be the exceptional modified invariant signature of the first kind. Then $\hat{\mathfrak{S}}_{-1}^* \cup \{(1, 0)\}$ is a simple (singular) closed curve. The region bounded by $\hat{\mathfrak{S}}_{-1}^* \cup \{(1, 0)\}$ contains the stable equilibrium point $(\eta_+(-1), 0)$. The signatures $\hat{\mathfrak{S}}_{-1, e_2}$, $e_2 \in I_{-1}$ are contained in the internal region bounded by $\hat{\mathfrak{S}}_{-1}^* \cup \{(1, 0)\}$. When $e_2 \rightarrow 1^+$, $\hat{\mathfrak{S}}_{\lambda, e_2}$ tends to $\hat{\mathfrak{S}}_{-1}^* \cup \{(1, 0)\}$ and, when $e_2 \rightarrow \eta_+(\lambda)^-$, $\hat{\mathfrak{S}}_{\lambda, e_2}$ contracts to the stable equilibrium point (see the picture on the center of Figure 8). The function \mathcal{P}_λ is strictly increasing (again, this fact follows from experimental evidence). When $e_2 \rightarrow 1^+$, \mathcal{P}_λ tends to 1 and when $e_2 \rightarrow \eta_+(-1)^-$, \mathcal{P}_λ tends to $\chi(-1)$.
- (3) Case $-1 < \lambda < -2/\sqrt[4]{27}$. Then $a(\lambda) > 1$ and the signature $\hat{\mathfrak{S}}_{\lambda, a(\lambda)}$ is the unstable equilibrium point $(a(\lambda), 0)$. Let $\hat{\mathfrak{S}}_\lambda^*$ be the exceptional modified invariant signature of the first kind. Then $\hat{\mathfrak{S}}_\lambda^* \cup \{(a(\lambda), 0)\}$ is a simple (singular) closed curve. As in the previous case, the region bounded by $\hat{\mathfrak{S}}_\lambda^* \cup \{(a(\lambda), 0)\}$ contains the stable equilibrium point and the signatures $\hat{\mathfrak{S}}_{\lambda, e_2}$, $e_2 \in I_\lambda$. When $e_2 \rightarrow a(\lambda)^+$, $\hat{\mathfrak{S}}_{\lambda, e_2}$ tends to $\hat{\mathfrak{S}}_\lambda^* \cup \{(1, 0)\}$ and, when $e_2 \rightarrow \eta_+(\lambda)^-$, $\hat{\mathfrak{S}}_{\lambda, e_2}$ contracts, to the stable equilibrium point (see the picture on the right of Figure 8). When $e_2 \rightarrow \eta_+(\lambda)^-$, \mathcal{P}_λ tends to $\chi(\lambda)$ and $\mathcal{P}_\lambda = O\left(\log(4/\sqrt{e_2 - a(\lambda)})\right)$ as $e_2 \rightarrow a(\lambda)^+$.

Remark 4.6. Unlike in the other cases, if $\lambda > -1$, the function \mathcal{P}_λ is not necessarily monotonous. Experimental evidence suggests the existence of a value of λ ($\lambda_* \approx -0.98147772$) such that \mathcal{P}_λ has a unique minimum point in the interval $(a(\lambda), \eta_+(\lambda))$, for every $\lambda \in (-1, \lambda_*)$ and is strictly decreasing, for every $\lambda \in$

$[\lambda_*, -2/\sqrt[4]{27}]$ (see Figure 9). This is a huge difference with the spherical case, for which experiments suggest that \mathcal{P}_λ is always monotonous [34].

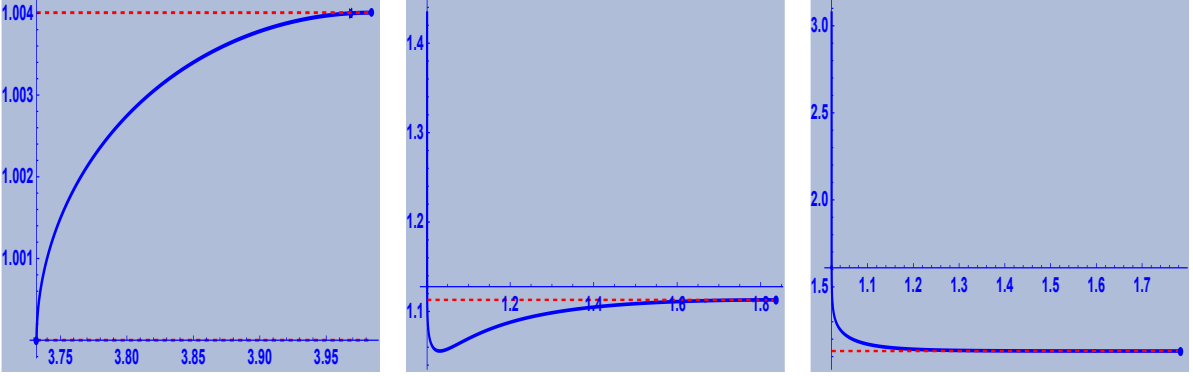


FIGURE 9. The graph of the functions \mathcal{P}_λ . From left to right: $\lambda = -1.3$, -0.999 , and -0.98 .

4.1. The Fibers of the Period Map. Consider the vector field $\vec{P} : \mathfrak{p} = (\lambda, e_2) \in \mathcal{T} \rightarrow (\partial_{e_2} \mathcal{P}, -\partial_\lambda \mathcal{P})$, where \mathcal{P} is the period map (for a plot see the picture on the left of Figure 10). Based on experimental evidence, this vector field never vanishes and its second component is negative, ie. the period map \mathcal{P} increases with λ . However, as highlighted in the previous remark, \mathcal{P} may not be monotonous with respect to e_2 . One can then deduce the following consequences:

- The fibers of the map $\mathcal{P} : \mathcal{T} \rightarrow \mathbb{R}$ are the integral curves of \vec{P} .
- For every $q > 1$ the fiber $\mathcal{T}_q = \mathcal{P}^{-1}(q)$ is a simple open arc with boundary points $\mathfrak{p}_0 = (-1, 1)$ and $\mathfrak{p}_q = (\lambda_q^*, e_{q,2}^*)$, where

$$\lambda_q^* = -\frac{1 + (e_{q,2}^*)^4}{2(e_{q,2}^*)^3}, \quad \frac{(e_{q,2}^*)^4 - 1}{\sqrt{(e_{q,2}^*)^8 - 4(e_{q,2}^*)^4 + 3}} = q.$$

More precisely, there exists a smooth function $\lambda_q : \tilde{\mathcal{J}}_q \rightarrow \mathbb{R}$, defined on the open interval $\tilde{\mathcal{J}}_q = (1, e_{q,2}^*)$ such that $\mathfrak{p}_q : e_2 \in \tilde{\mathcal{J}}_q \rightarrow (\lambda_q(e_2), e_2)$ is a parameterization of \mathcal{T}_q . Moreover, $\lambda_q(1) = -1$ and $\lambda_q(e_{q,2}^*) = -\lambda_q^*$ (see Figure 10).

- The fiber \mathcal{T}_q intersects transversely the exceptional locus at a unique point $\hat{\mathfrak{p}}_q = (\hat{\lambda}_2, \hat{e}_{q,2})$ (see Figure 10, right).
- When $q \rightarrow 1^+$, the fiber \mathcal{T}_q tends to \mathcal{L} . If $q \rightarrow +\infty$, the fiber \mathcal{T}_q tends to the arc $\eta_-[(-1, -2/\sqrt[4]{27})]$ (the green arc depicted on the right of Figure 10).

Remark 4.7. The integral curves of the vector field \vec{P} are the fibers of the period map \mathcal{P} . Each fiber $\mathcal{T}_q = \mathcal{P}^{-1}(q)$, $q > 1$, is a simple arc joining \mathfrak{p}_0 with \mathfrak{p}_q and intersecting the exceptional locus \mathcal{E} exactly once at $\hat{\mathfrak{p}}_q$. The fiber \mathcal{T}_q is related to a 1-parameter family of BT-curves $\mathcal{G}_q = \{\gamma_{\mathfrak{p}}\}_{\mathfrak{p} \in \mathcal{T}_q}$.

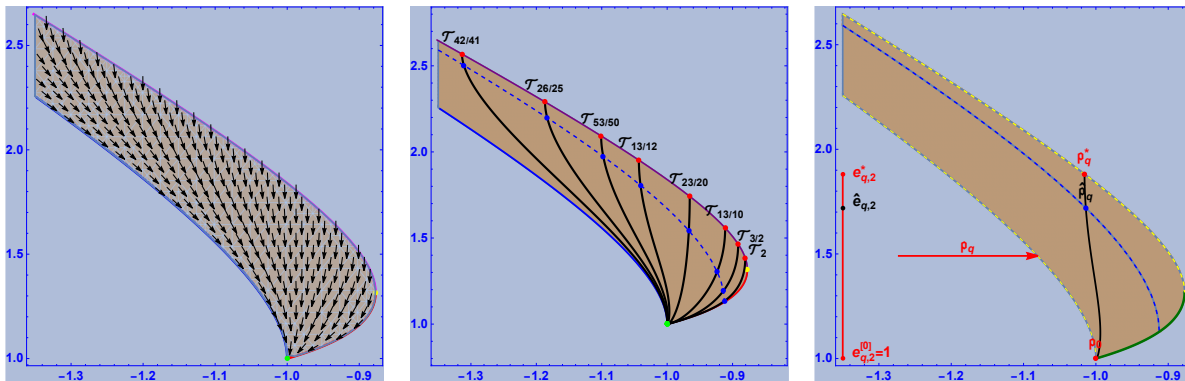


FIGURE 10. Left: The plot of the vector field $\vec{P} = (\partial_{e_2} \mathcal{P}, -\partial_\lambda \mathcal{P})$. Center: The fibers \mathcal{T}_q , for several values of q . Right: The fiber $\mathcal{T}_{11/10}$.

4.2. Isomonodromic Families. Let $q = m/n$ be a rational number. Then, $\mathcal{G}_q = \{\gamma_p\}_{p \in \mathcal{T}_q}$ is a 1-parameter family of BT-strings, the *isomonodromic family* with characteristic number q . We list some salient geometric properties of the isomonodromic families:

- (1) If $e_2 \rightarrow 1^+$, $|\gamma_{p_q(e_2)}|$ tends to the ideal boundary of \mathbb{D}^2 (see the first image of Figure 11).
- (2) If $e_2 \rightarrow e_{q,2}^*$, $|\gamma_{p_q(e_2)}|$ tends to the circle \mathcal{C}_q , centered at the origin, with radius

$$r_q = \frac{1}{e_{q,2}^* + \sqrt{(e_{q,2}^*)^4 - 1}}.$$

(See the last image of Figure 11.)

- (3) The trajectory $|\gamma_{p_q(e_2)}|$ passes through the origin if and only if $e_2 = \hat{e}_{q,2}$ (see the curve depicted on the fourth image of Figure 11).
- (4) The BT-strings are never simple, however their multiple points are admissible in the sense that the tangent vectors at those points are not equal (for details see Figure 12).
- (5) The BT-strings of the isomonodromic family \mathcal{G}_q have the same stabilizer, namely, the group R_n of order n generated by the rotation of an angle $2\pi m/n$ around the origin. Since κ is even, the strings are also invariant by the reflection with respect to the horizontal axis. If $n = 1$, the reflection is the unique residual symmetry. In particular, n is the wave number of the string of the isomonodromic family.
- (6) The number m is the hyperbolic turning number of the strings belonging to \mathcal{G}_q . In other words, m is the homotopy class of the Frenet frame in $O_+^\uparrow(1, 2)$, identified as $\mathbb{D}^2 \times \mathbb{S}^1$ [11, 39]. If $e_2 \in (1, \hat{e}_{q,2})$, $m - n$ is the homotopy class of $\gamma_{p_q(e_2)}$ in the punctured disk $\dot{\mathbb{D}}^2 = \mathbb{D}^2 \setminus \{(0, 0)\}$ (with the obvious identification $\pi_1(\dot{\mathbb{D}}^2) \cong \mathbb{Z}$). If $e_2 \in (\hat{e}_{q,2}, e_{q,2}^*)$, m is the homotopy class of $\gamma_{p_q(e_2)}$ in $\dot{\mathbb{D}}^2$.

(7) The function $\omega_q : e_2 \in \tilde{\mathbb{J}}_q \rightarrow \omega_{\gamma_{\mathfrak{p}_q(e_2)}} \in \mathbb{R}$ is strictly decreasing and satisfies

$$\lim_{e_2 \rightarrow 1^+} \omega_q(e_2) = +\infty, \quad \lim_{e_2 \rightarrow e_{q,2}^*} \omega_q(e_2) = \frac{4q\pi r_q}{1 - r_q^2}.$$

Remark 4.8. From (5), (6) and (7) it follows that BT-strings are characterized by three global geometric invariants: the wave number (ie. the order of the symmetry group), the hyperbolic turning number and the length.

Remark 4.9. If $q = m/n$ is a rational number, the 1-parameter family $\mathcal{G}_q = \{\gamma_{\mathfrak{p}}\}_{\mathfrak{p} \in \mathcal{T}_q}$ is composed by BT-strings. Moving on the fiber \mathcal{T}_q can be seen as the evolution of these BT-strings. As e_2 increases from 1 to $e_{q,2}^*$, the curves evolve from the ideal boundary of \mathbb{D}^2 to the circle \mathcal{C}_q . This evolution passes through the origin of \mathbb{D}^2 exactly once at $e_2 = \hat{e}_{q,2}$. The characteristic number $q = m/n$ determines the wave number n and the hyperbolic turning number m of the BT-strings of the isomonodromic family \mathcal{G}_q .

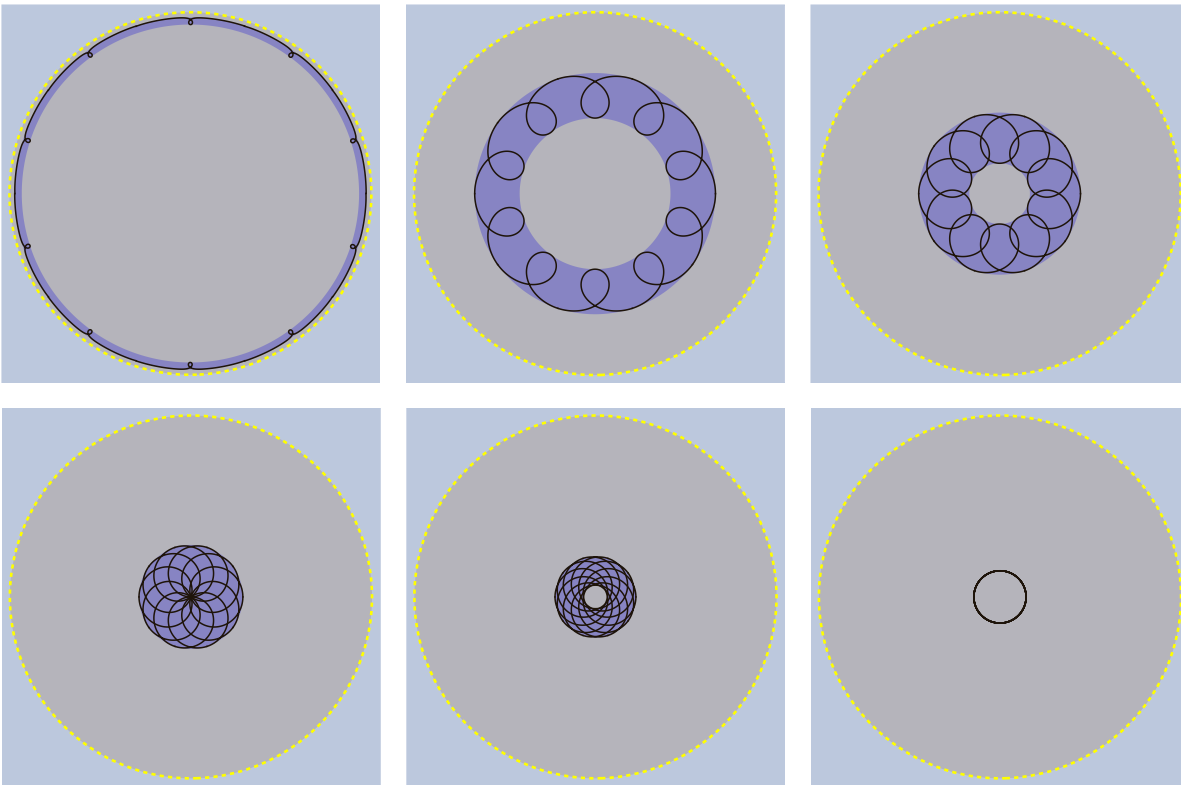


FIGURE 11. Trajectories of the BT-strings $|\{\gamma_{\mathfrak{p}_q(e_2)}\}|$ with $q = 11/10$ and e_2 increasing in $\tilde{\mathbb{J}}_{11/10}$.

Figure 11 reproduces the trajectories of BT-strings with characteristic number $q = 11/10$. The parameter e_2 varies in the interval $\tilde{\mathbb{J}}_{11/10} = (1, e_{11/10,2}^*)$, where $e_{11/10,2}^* \approx 1.8812$. The exceptional value $\hat{e}_{11/10,2}$ is approximately 1.71966. The curves of Figure 11 correspond to $e_2 \approx 1$, $e_2 = 1.26$, $e_2 = 1.53$, $e_2 = \hat{e}_{11/10,2}$,

$e_2 = 1.79$, respectively, while the last one is the circle $\mathcal{C}_{11/10}$. The BT-strings of the family have a tenth-fold rotational symmetry. If $e_2 < \hat{e}_{11/10,2}$ the homotopy class in the punctured disk is 1 while, if $e_2 > \hat{e}_{11/10,2}$ the homotopy class is 11.

Remark 4.10. As e_2 increases in the interval $\tilde{\mathcal{J}}_q$, the curves in the isomonodromic family \mathcal{G}_q pass through different isotopy classes. More precisely, let $j[q]$, $q = m/n$, be defined by

$$j[q] = (n + \text{mod}(n, 2))/2 - \delta_{1,n},$$

where $\delta_{1,n}$ is the Kronecker delta. There are $2j[q] + 1$ distinct isotopy classes of BT-strings in the isomonodromic family \mathcal{G}_q .

The curves depicted in Figure 12 are the representatives of the seven isotopy classes of strings in the isomonodromic family $\mathcal{G}_{7/5}$. In the same figure, the multiple points of the BT-strings are also illustrated.

5. APPENDIX. PROOF OF THEOREM 4.5

In this appendix, we will prove Theorem 4.5. As mentioned in Section 4, the proof follows from the claim with respect to the limits of the period map \mathcal{P}_λ . In turn, the claim follows from five lemmas:

Lemma 5.1. *If $\lambda \in [-\sqrt[4]{\varphi^5}/2, -2/\sqrt[4]{27}]$ where $\varphi = (1 + \sqrt{5})/2$ is the golden ratio, the period map \mathcal{P}_λ is real-analytic.*

Proof. Let \mathfrak{g} and \mathfrak{m} be as in (3.5). Put

$$(5.1) \quad \begin{cases} (i) & \mathbf{n}_1 = \frac{(1-2\sqrt{|c|}e_4)(e_2-e_1)}{(1-2\sqrt{|c|}e_1)(e_2-e_4)}, \\ (ii) & \mathbf{n}_2 = \frac{(1+2\sqrt{|c|}e_4)(e_2-e_1)}{(1+2\sqrt{|c|}e_1)(e_2-e_4)}, \\ (iii) & \mathbf{A} = -\frac{\mathfrak{g}e_4(e_4+2\lambda)}{1+4ce_4^2}, \\ (iv) & \mathbf{B} = -\frac{\mathfrak{g}(1+4\sqrt{|c|}\lambda)(e_1-e_4)}{4\sqrt{|c|}(1-2\sqrt{|c|}e_4)(1-2\sqrt{|c|}e_1)}, \\ (v) & \mathbf{C} = \frac{\mathfrak{g}(1-4\sqrt{|c|}\lambda)(e_1-e_4)}{4\sqrt{|c|}(1+2\sqrt{|c|}e_4)(1+2\sqrt{|c|}e_1)}. \end{cases}$$

If we fix λ , these are functions of $e_2 \in \mathcal{I}_\lambda = (a(\lambda), \eta_+(\lambda))$ (see Remark 4.2), denoted by \mathfrak{g}_λ , \mathfrak{m}_λ , $\mathbf{n}_{1,\lambda}$, $\mathbf{n}_{2,\lambda}$, \mathbf{A}_λ , \mathbf{B}_λ and \mathbf{C}_λ , respectively. In view of (3.11), \mathbf{B}_λ and $\mathbf{n}_{1,\lambda}$ are defined on $\mathcal{T} \setminus \mathcal{E}$. The functions \mathfrak{g}_λ , \mathfrak{m}_λ , $\mathbf{n}_{2,\lambda}$, \mathbf{A}_λ and \mathbf{C}_λ are real-analytic. If $\lambda \in [-\sqrt[4]{\varphi^5}/2, -2/\sqrt[4]{27}]$ also $\mathbf{n}_{1,\lambda}$ and \mathbf{B}_λ are real-analytic. Instead, if $\lambda < -\sqrt[4]{\varphi^5}/2$, $\mathbf{n}_{1,\lambda}$ and \mathbf{B}_λ are real-analytic on $\mathcal{I}_\lambda \setminus \{c(\lambda)\}$ and

$$\lim_{e_2 \rightarrow c(\lambda)^\pm} \mathbf{n}_{1,\lambda}(e_2) = -\infty, \quad \lim_{e_2 \rightarrow c(\lambda)^\pm} \mathbf{B}_\lambda(e_2) = \pm\infty.$$

Recall that $c(\lambda)$ is defined in (3.12) and its graph represents the exceptional locus \mathcal{E} .

If $\mathfrak{p} = (\lambda, e_2) \notin \mathcal{E}$, then

$$\begin{aligned} -\frac{1}{2\pi} \Theta_{\mathfrak{p}}(\omega_{\mathfrak{p}}) &= -\frac{\sqrt{|c|}}{\pi} \int_0^{\omega_{\mathfrak{p}}} \frac{\mu_{\mathfrak{p}}^2(\mu_{\mathfrak{p}} + 2\lambda)}{1 + 4c\mu_{\mathfrak{p}}^2} ds = \\ &= -\frac{2\sqrt{|c|}}{\pi} \int_{e_2}^{e_1} \frac{\mu(\mu + 2\lambda)}{(1 + 4c\mu^2)\sqrt{-(\mu - e_1)(\mu - e_2)(\mu - e_3)(\mu - e_4)}} d\mu. \end{aligned}$$

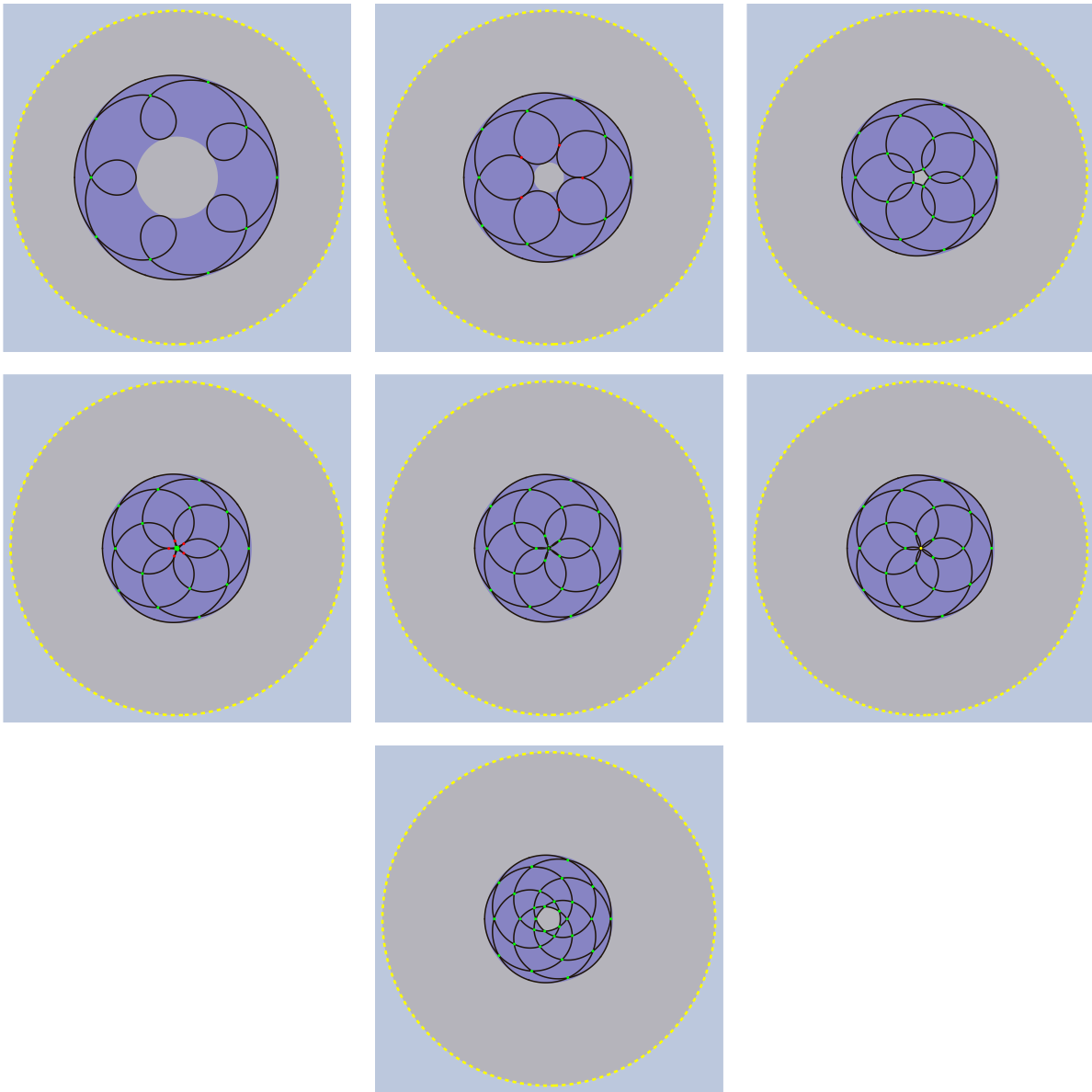


FIGURE 12. Trajectories of the BT-strings $[[\gamma_{p_q(e_2)}]]$ with $q = 7/5$ and e_2 increasing in $\tilde{\mathcal{J}}_{7/5}$. Ordinary double points are represented by the green dots, tangential admissible double points are the red dots and the multiple point of multiplicity bigger than two is shown in yellow.

The last integral, denoted by \mathcal{J}_p , can be written as

$$(5.2) \quad \mathcal{J}_p = \frac{2\sqrt{|c|}}{\pi} (\text{AK}(\mathbf{m}) + \text{BII}(\mathbf{n}_1, \mathbf{m}) + \text{CII}(\mathbf{n}_2, \mathbf{m})).$$

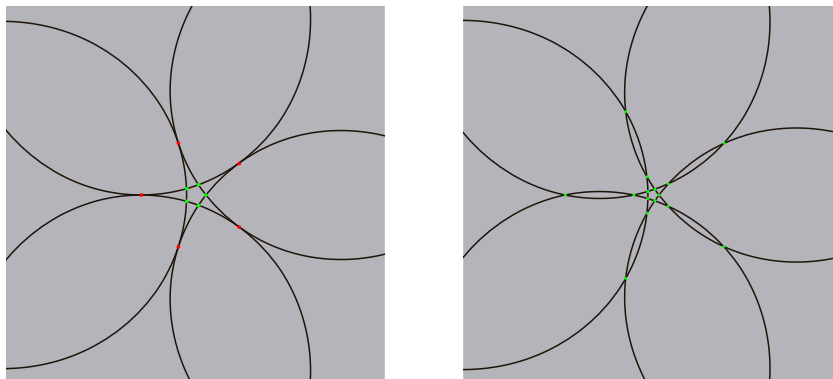


FIGURE 13. Amplifications of the fourth and fifth images of Figure 12, respectively.

The map $\mathfrak{J} : \mathbf{p} = (\lambda, e_2) \in \mathcal{T} \setminus \mathcal{E} \rightarrow \mathfrak{J}_{\mathbf{p}}$ is real-analytic.

Let $\mathbf{p} = (\lambda, e_2) \in \mathcal{E}$ (ie. $e_2 = c(\lambda)$), then

$$\begin{aligned} -\frac{1}{2\pi} \Theta_{\mathbf{p}}(\omega_{\mathbf{p}}) &= \frac{4\sqrt{|c|}\lambda^2}{\pi} \int_0^{\omega_{\mathbf{p}}} \frac{\mu_{\mathbf{p}}^2}{\mu_{\mathbf{p}} - 2\lambda} ds = \\ &= \frac{8\sqrt{|c|}\lambda^2}{\pi} \int_{e_2}^{e_1} \frac{\mu}{(\mu - 2\lambda)\sqrt{-(\mu - e_1)(\mu - e_2)(\mu - e_3)(\mu - e_4)}} d\mu. \end{aligned}$$

This last integral, denoted by $\widehat{\mathfrak{J}}_{\mathbf{p}}$ can be written as

$$(5.3) \quad \widehat{\mathfrak{J}}_{\mathbf{p}} = \frac{2\sqrt{|c|}}{\pi} (\mathbf{AK}(\mathbf{m}) + \mathbf{C}\Pi(\mathbf{n}_2, \mathbf{m})).$$

If $\lambda \in [-\sqrt[4]{\varphi^5}/2, -2/\sqrt[4]{27})$, then $\mathbf{I}_{\lambda} \cap \mathcal{E} = \emptyset$ and $\mathcal{P}_{\lambda} = \mathfrak{J}_{\mathbf{p}} + 1$. This proves that \mathcal{P}_{λ} is real-analytic, for every $\lambda \in [-\sqrt[4]{\varphi^5}/2, -2/\sqrt[4]{27})$. \square

Lemma 5.2. *If $\lambda < -\sqrt[4]{\varphi^5}/2$, the period map \mathcal{P}_{λ} is continuous on $\mathbf{I}_{\lambda} = (a(\lambda), \eta_+(\lambda))$ and real-analytic on $\mathbf{I}_{\lambda} \setminus \{c(\lambda)\}$.*

Proof. Following with the notation of the previous lemma, for every $\lambda < -\sqrt[4]{\varphi^5}/2$ we have $\mathbf{I}_{\lambda} \cap \mathcal{E} = \{(\lambda, c(\lambda))\}$ and

$$\begin{cases} \mathcal{P}_{\lambda}(e_2) = \mathfrak{J}_{\mathbf{p}} + 1, & e_2 \in (a(\lambda), c(\lambda)) \\ \mathcal{P}_{\lambda}(e_2) = \mathfrak{J}_{\mathbf{p}}, & e_2 \in (c(\lambda), \eta_+(\lambda)) \end{cases}.$$

Then, \mathcal{P}_{λ} is real-analytic on $\mathbf{I}_{\lambda} \setminus \{c(\lambda)\}$. The continuity part of the lemma follows from the limits

$$(5.4) \quad \lim_{e_2 \rightarrow c(\lambda)^-} \mathfrak{J}_{\mathbf{p}} = \widehat{\mathfrak{J}}_{\mathbf{p}} - 1/2, \quad \lim_{e_2 \rightarrow c(\lambda)^+} \mathfrak{J}_{\mathbf{p}} = \widehat{\mathfrak{J}}_{\mathbf{p}} + 1/2.$$

Or, equivalently, from

$$(5.5) \quad \lim_{e_2 \rightarrow c(\lambda)^{\pm}} \frac{2\sqrt{|c|}}{\pi} \mathbf{B}_{\lambda} \Pi(\mathbf{n}_1, \lambda, \mathbf{m}_{\lambda}) = \pm \frac{1}{2}.$$

The proof of (5.5) is organized into two steps:

Step I. In the first step we show that

$$(5.6) \quad \lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{1 + 4\lambda\sqrt{|c|}}{\sqrt{1 - 2e_{\lambda,1}\sqrt{|c|}}} = \mp \frac{\sqrt{2}}{e_{\lambda,1}(c(\lambda))^2},$$

where $e_{\lambda,j}(e_2) = e_j(\lambda, e_2)$, $j = 1, 3, 4$. Using (v) and (vi) of (3.1) we have

$$\frac{1 + 4\lambda\sqrt{|c|}}{\sqrt{1 - 2e_{\lambda,1}\sqrt{|c|}}} = \frac{2e_{\lambda,1}^3 e_2^2 - \mathbf{q}_\lambda(e_2)\sqrt{1 - \mathbf{p}_\lambda(e_2)^2}}{2e_{\lambda,1}^3 e_2^2 \sqrt{1 - \sqrt{1 - \mathbf{p}_\lambda(e_2)^2}}},$$

where

$$\mathbf{p}_\lambda(e_2) = \frac{e_{\lambda,1}^2 e_2^3 - e_{\lambda,1}^3 e_2^2 + e_{\lambda,1} + e_2}{2e_{\lambda,1} e_2^2}, \quad \mathbf{q}_\lambda(e_2) = (e_{\lambda,1} + e_2)(1 + e_{\lambda,1}^2 e_2^2).$$

By (iii) of Remark 3.17, $\mathbf{p}_\lambda(e_2)$ tends to 0 when $e_2 \rightarrow c(\lambda)$, it is negative if $e_2 < c(\lambda)$ and positive if $e_2 > c(\lambda)$. Then,

$$\begin{aligned} \lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{1 + 4\lambda\sqrt{|c|}}{\sqrt{1 - 2e_{\lambda,1}\sqrt{|c|}}} &= \lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{2e_{\lambda,1}^3 e_2^2 - \mathbf{q}_\lambda(e_2)\sqrt{1 - \mathbf{p}_\lambda(e_2)^2}}{2e_{\lambda,1}^3 e_2^2 \sqrt{1 - \sqrt{1 - \mathbf{p}_\lambda(e_2)^2}}} = \\ &= \lim_{e_2 \rightarrow c(\lambda)^\pm} - \frac{\mathbf{p}_\lambda(e_2)}{e_{\lambda,1}^2 \sqrt{1 - \sqrt{1 - \mathbf{p}_\lambda(e_2)^2}}} = \mp \frac{\sqrt{2}}{e_{\lambda,1}(c(\lambda))^2}. \end{aligned}$$

Step II. We will now prove (5.5). For this purpose, recall the standard limit (see [6], 906.00, p. 302)

$$\Pi(n, m) \sim \frac{\pi}{2\sqrt{1-n}}, \quad \text{as } n \rightarrow -\infty, \quad \forall m \in (0, 1).$$

Since

$$\lim_{e_2 \rightarrow c(\lambda)^\pm} \mathbf{n}_{1,\lambda}(e_2) = -\infty, \quad 0 < \mathbf{m}_\lambda(e_2) < 1, \quad \forall \lambda < -\sqrt[4]{\varphi^5}/2,$$

we have

$$\lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{2\sqrt{|c|}}{\pi} \mathbf{B}_\lambda \Pi(\mathbf{n}_{1,\lambda}, \mathbf{m}_\lambda) = \lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{\sqrt{|c|} \mathbf{B}_\lambda}{\sqrt{1 - \mathbf{n}_{1,\lambda}}}.$$

Using (5.1) we obtain

$$\frac{\sqrt{|c|} \mathbf{B}_\lambda}{\sqrt{1 - \mathbf{n}_{1,\lambda}}} = \frac{\widehat{\mathbf{p}}_\lambda}{\widehat{\mathbf{q}}_\lambda},$$

where $\widehat{\mathbf{p}}_\lambda$ is given by

$$\widehat{\mathbf{p}}_\lambda = -\frac{1}{4} \mathbf{g}_\lambda (1 + 4\sqrt{|c|} \lambda) (e_{\lambda,1} - e_{\lambda,4}) \sqrt{e_2 - e_{\lambda,4}} (1 - 2\sqrt{|c|} e_{\lambda,4})^{-1}$$

and $\widehat{\mathbf{q}}_\lambda$ is the square root of

$$\widehat{\mathbf{q}}_\lambda^2 = (1 - 2\sqrt{|c|} e_{\lambda,1}) \left((1 - 2\sqrt{|c|} e_{\lambda,4}) (e_{\lambda,1} - e_2) + (e_2 - e_{\lambda,4}) (1 - 2\sqrt{|c|} e_{\lambda,1}) \right).$$

Using (5.6) we obtain

$$\lim_{e_2 \rightarrow c(\lambda)^\pm} \frac{\sqrt{|c|} \mathbf{B}_\lambda}{\sqrt{1 - \mathbf{n}_{1,\lambda}}} = \pm \mathbf{h}_\lambda(c(\lambda)),$$

where

$$\mathfrak{h}_\lambda(e_2) = \frac{\mathfrak{g}_\lambda(e_{\lambda,1} - e_{\lambda,4})\sqrt{e_2 - e_{\lambda,4}}(1 - 2\sqrt{|c|}e_{\lambda,4})^{-1}}{2\sqrt{2}e_{\lambda,1}^2\sqrt{(e_{\lambda,1} - e_2)(1 - 2\sqrt{|c|}e_{\lambda,4}) + (e_2 - e_{\lambda,4})(1 - 2\sqrt{|c|}e_{\lambda,1})}}.$$

From (3.5), using (iv), (vi) of (3.1) and (iii) of (3.11), it follows that $\mathfrak{h}_\lambda(c(\lambda)) = 1/2$, which proves the result. \square

Before proceeding further, we list eight properties that will be used to prove the remaining lemmas:

- (1) For every $\lambda < -2/\sqrt[4]{27}$, $0 < \mathfrak{m}_\lambda < 1$, and

$$\begin{aligned} \lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{m}_\lambda(e_2) &= 1, & \forall \lambda \in [-1, -2/\sqrt[4]{27}), \\ \lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{m}_\lambda(e_2) &< 1, & \forall \lambda \in (-\infty, -1). \end{aligned}$$

Recall that \mathfrak{m}_λ is the notation of \mathfrak{m} (3.5) for fixed λ .

- (2) The functions $\mathfrak{n}_{j,\lambda}(e_2)$ are negative when $e_2 \rightarrow a(\lambda)^+$ and $\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{n}_{2,\lambda}(e_2)$ is finite, for every $\lambda < -2/\sqrt[4]{27}$. The limit $\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{n}_{1,\lambda}(e_2)$ is finite, for every $\lambda < -2/\sqrt[4]{27}$, $\lambda \neq -\sqrt[4]{\varphi^5}/2$ and is $-\infty$ if $\lambda = -\sqrt[4]{\varphi^5}/2$. In addition, if $\lambda \leq -1$

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{n}_{1,\lambda}(e_2) = \lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{n}_{2,\lambda}(e_2).$$

- (3) The limit $\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{B}_\lambda(e_2)$ is finite, for every $\lambda \in (-1, -2/\sqrt[4]{27})$ and $\lambda \neq -\sqrt[4]{\varphi^5}/2$, while it is $-\infty$ for every $\lambda \leq -1$.
(4) The limit $\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{C}_\lambda(e_2)$ is finite, for every $\lambda \in (-1, -2/\sqrt[4]{27})$, and it is $+\infty$ for every $\lambda \leq -1$.
(5) The limit $\lim_{e_2 \rightarrow a(\lambda)^+} c$ ($c = c(\lambda, e_2)$) is finite, for every $\lambda < -2/\sqrt[4]{27}$. It is negative if $\lambda > -1$ and zero if $\lambda \leq -1$.
(6) The limit $\lim_{e_2 \rightarrow a(\lambda)^+} c\mathfrak{C}_\lambda(e_2)$ is finite for every $\lambda < -2/\sqrt[4]{27}$. It is 0 if $\lambda \leq -1$ and it is negative if $\lambda > -1$.
(7) The limit $\lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{A}_\lambda(e_2)$ is finite for every $\lambda < -2/\sqrt[4]{27}$.
(8) Let \mathfrak{Q}_λ be defined by

$$(5.7) \quad \mathfrak{Q}_\lambda = \mathfrak{A}_\lambda + \frac{\mathfrak{B}_\lambda}{1 - \mathfrak{n}_{1,\lambda}} + \frac{\mathfrak{C}_\lambda}{1 - \mathfrak{n}_{2,\lambda}}.$$

Using (iii) – (vi) of (3.1) and taking into account (3.5) and (5.1) we have

$$\mathfrak{Q}_\lambda = -\frac{\mathfrak{g}_\lambda e_2(e_2 + 2\lambda)}{1 + 4ce_2^2}.$$

Hence, \mathfrak{Q}_λ is real-analytic, it is positive and tends to a finite limit when $e_2 \rightarrow a(\lambda)^+$ and when $e_2 \rightarrow \eta_+(\lambda)^-$ for every $\lambda < -2/\sqrt[4]{27}$.

We now continue with the proofs of the remaining lemmas, which will show the limits of the period map \mathcal{P}_λ .

Lemma 5.3. *Let $\lambda \in (-1, -2/\sqrt[4]{27})$. Then,*

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = +\infty.$$

Proof. We begin by recalling some asymptotic behavior of elliptic integrals. From 906.03 at p. 302 of [6] we have the asymptotic expansion

$$(5.8) \quad \Pi(n, m) \sim \frac{1}{1-n} \left(\log\left(\frac{4}{\sqrt{1-m}}\right) + \sqrt{-n} \arctan(\sqrt{-n}) \right), \quad \text{as } m \rightarrow 1^-,$$

while from 112.01 at p. 11 of [6] we have the standard asymptotic expansion

$$(5.9) \quad K(m) \sim \log\left(\frac{4}{\sqrt{1-m}}\right), \quad \text{as } m \rightarrow 1^-.$$

Then, from Property (1), (5.2), (5.8) and (5.9) we have

$$(5.10) \quad \mathfrak{J}_p \sim \frac{\sqrt{|c|}}{\pi} \left(\mathbb{R}_\lambda + \log\left(\frac{4}{\sqrt{1-\mathfrak{m}_\lambda}}\right) \mathbb{Q}_\lambda \right), \quad \text{as } e_2 \rightarrow a(\lambda)^+,$$

where

$$(5.11) \quad \mathbb{R}_\lambda = \frac{\sqrt{-\mathfrak{n}_{1,\lambda}} \arctan(\sqrt{-\mathfrak{n}_{1,\lambda}})}{1-\mathfrak{n}_{1,\lambda}} \mathbb{B}_\lambda + \frac{\sqrt{-\mathfrak{n}_{2,\lambda}} \arctan(\sqrt{-\mathfrak{n}_{2,\lambda}})}{1-\mathfrak{n}_{2,\lambda}} \mathbb{C}_\lambda.$$

Next, using the Properties (2)-(6), we conclude that the limits

$$\lim_{e_2 \rightarrow a(\lambda)^+} \sqrt{|c|} \mathbb{R}_\lambda(e_2), \quad \lim_{e_2 \rightarrow a(\lambda)^+} \sqrt{|c|} \mathbb{Q}_\lambda$$

are finite, for every $\lambda \in (-1, -2/\sqrt[4]{27})$ and $\lambda \neq -\sqrt[4]{\varphi^5}/2$. It then follows from Property (1) and (5.10) that

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = \lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{J}_p = +\infty,$$

for every $\lambda \in (-1, -2/\sqrt[4]{27})$ and $\lambda \neq -\sqrt[4]{\varphi^5}/2$.

Consider now $\lambda = -\sqrt[4]{\varphi^5}/2$. Then $a(\lambda) = \varphi^{1/4}$ and the limits

$$\lim_{e_2 \rightarrow a(\lambda)^+} \sqrt{|c|} \mathbb{Q}_\lambda, \quad \lim_{e_2 \rightarrow a(\lambda)^+} \frac{\sqrt{-\mathfrak{n}_{2,\lambda}} \arctan(\sqrt{-\mathfrak{n}_{2,\lambda}})}{1-\mathfrak{n}_{2,\lambda}} \mathbb{C}_\lambda$$

exist and are positive. The functions \mathbb{B}_λ and $\sqrt{-\mathfrak{n}_{1,\lambda}} \arctan(\sqrt{-\mathfrak{n}_{1,\lambda}})(1-\mathfrak{n}_{1,\lambda})^{-1}$ are positive on $(a(\lambda), a(\lambda) + \epsilon)$, for some $\epsilon > 0$. Consequently, $\sqrt{|c|} \mathbb{R}_\lambda$ is positive on $(a(\lambda), a(\lambda) + \epsilon)$. Thus, also in this case

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = \lim_{e_2 \rightarrow a(\lambda)^+} \mathfrak{J}_p = +\infty,$$

as claimed. \square

Lemma 5.4. *Let $\lambda \in (-\infty, -1]$. Then,*

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = 1.$$

Proof. From (v) and (vi) of (5.1) we have

$$(5.12) \quad \mathbb{B}_\lambda + \mathbb{C}_\lambda = \frac{\mathfrak{g}_\lambda(e_{\lambda,1} - e_{\lambda,4})(e_{\lambda,4}(8c\lambda e_{\lambda,1} - 1) - e_{\lambda,1} - 2\lambda)}{(1 + 4ce_{\lambda,1}^2)(1 + 4ce_{\lambda,4}^2)}.$$

Using (3.1) and the characterization of Remark 3.9 we deduce that

$$\lim_{e_2 \rightarrow a(\lambda)^+} e_{\lambda,4}(e_2) + e_{\lambda,1}(e_2) + 2\lambda = 0, \quad \forall \lambda \leq -1.$$

This implies

$$(5.13) \quad \lim_{e_2 \rightarrow a(\lambda)^+} (\mathbb{B}_\lambda(e_2) + \mathbb{C}_\lambda(e_2)) = 0, \quad \forall \lambda \leq -1.$$

Assume first $\lambda = -1$. From (5.13) we have

$$\mathbf{R}_\lambda \sim \left(\frac{\sqrt{-\mathbf{n}_{2,\lambda}} \arctan(\sqrt{-\mathbf{n}_{2,\lambda}})}{1 - \mathbf{n}_{2,\lambda}} - \frac{\sqrt{-\mathbf{n}_{1,\lambda}} \arctan(\sqrt{-\mathbf{n}_{1,\lambda}})}{1 - \mathbf{n}_{1,\lambda}} \right) \mathbf{C}_\lambda,$$

as $e_2 \rightarrow a(-1)^+$, $a(-1) = 1$. From (v) of (5.1) it follows that $\lim_{e_2 \rightarrow 1^+} \sqrt{|c|} \mathbf{C}_{-1}$ is finite. Property (2) implies

$$\lim_{e_2 \rightarrow a(\lambda)^+} \left(\frac{\sqrt{-\mathbf{n}_{2,\lambda}} \arctan(\sqrt{-\mathbf{n}_{2,\lambda}})}{1 - \mathbf{n}_{2,\lambda}} - \frac{\sqrt{-\mathbf{n}_{1,\lambda}} \arctan(\sqrt{-\mathbf{n}_{1,\lambda}})}{1 - \mathbf{n}_{1,\lambda}} \right) = 0,$$

for every $\lambda \leq -1$. Then,

$$(5.14) \quad \lim_{e_2 \rightarrow 1^+} \sqrt{|c|} \mathbf{R}_{-1} = 0.$$

On the other hand²

$$(5.15) \quad \lim_{e_2 \rightarrow 1^+} \frac{c}{1 - \mathbf{m}_{-1}(e_2)} = 0.$$

Combining (5.10), (5.14) and (5.15) we obtain

$$\lim_{e_2 \rightarrow 1^+} \mathcal{P}_{-1}(e_2) = \lim_{e_2 \rightarrow 1^+} \mathcal{J}_p + 1 = 1.$$

Consider now the case $\lambda < -1$. Using Property (2) we have

$$(5.16) \quad \lim_{e_2 \rightarrow a(\lambda)^+} \mathbf{n}_{1,\lambda}(e_2) = \lim_{e_2 \rightarrow a(\lambda)^+} \mathbf{n}_{2,\lambda}(e_2) < 0, \quad \lim_{e_2 \rightarrow a(\lambda)^+} \mathbf{m}_\lambda(e_2) \in (0, 1).$$

Then

$$\lim_{e_2 \rightarrow a(\lambda)^+} \Pi(\mathbf{n}_{1,\lambda}(e_2), \mathbf{m}_\lambda(e_2)) = \lim_{e_2 \rightarrow a(\lambda)^+} \Pi(\mathbf{n}_{2,\lambda}(e_2), \mathbf{m}_\lambda(e_2)).$$

Moreover, (5.16) implies that the limits

$$\lim_{e_2 \rightarrow a(\lambda)^+} \Pi(\mathbf{n}_{1,\lambda}(e_2), \mathbf{m}_\lambda(e_2)), \quad \lim_{e_2 \rightarrow a(\lambda)^+} \mathbf{K}(\mathbf{m}_\lambda(e_2))$$

are finite for every $\lambda < -1$. From (v) of (5.1) it follows that $\lim_{e_2 \rightarrow a(\lambda)^+} \sqrt{|c|} \mathbf{C}_\lambda$ is finite for every $\lambda < -1$. Properties (5) and (7) implies that $\lim_{e_2 \rightarrow a(\lambda)^+} \mathbf{A}_\lambda$ is also finite, and that $\lim_{e_2 \rightarrow a(\lambda)^+} \sqrt{|c|} = 0$ for every $\lambda < -1$. Then, using (5.13), we have

$$\begin{aligned} \mathcal{J}_p &= \frac{2\sqrt{|c|}}{\pi} (\mathbf{A}_\lambda \mathbf{K}(\mathbf{m}_\lambda) + \mathbf{B}_\lambda \Pi(\mathbf{n}_{1,\lambda}, \mathbf{m}_\lambda) + \mathbf{C}_\lambda \Pi(\mathbf{n}_{2,\lambda}, \mathbf{m}_\lambda)) \\ &\sim_{e_2 \rightarrow a(\lambda)^+} \frac{2\sqrt{|c|}}{\pi} (\Pi(\mathbf{n}_{2,\lambda}, \mathbf{m}_\lambda) - \Pi(\mathbf{n}_{1,\lambda}, \mathbf{m}_\lambda)) \mathbf{C}_\lambda, \end{aligned}$$

for every $\lambda < -1$. This implies

$$\lim_{e_2 \rightarrow a(\lambda)^+} \mathcal{P}_\lambda(e_2) = \lim_{e_2 \rightarrow 1^+} \mathcal{J}_p + 1 = 1, \quad \forall \lambda < -1,$$

concluding the proof. \square

Lemma 5.5. *Let $\lambda < -2/\sqrt[4]{27}$. Then,*

$$\lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathcal{P}_\lambda(e_2) = \chi(\lambda),$$

where $\chi(\lambda)$ is the function defined in Definition 4.3.

²This limit has been computed with the software Mathematica 13.1.

Proof. From

$$\lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathfrak{m}_\lambda(e_2) = \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathfrak{n}_{1,\lambda}(e_2) = \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathfrak{n}_{2,\lambda}(e_2) = 0,$$

it follows that

$$\begin{aligned} \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{K}(\mathfrak{m}_\lambda(e_2)) &= \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{\Pi}(\mathfrak{n}_{1,\lambda}(e_2), \mathfrak{m}_\lambda(e_2)) = \\ &= \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{\Pi}(\mathfrak{n}_{2,\lambda}(e_2), \mathfrak{m}_\lambda(e_2)) = \frac{\pi}{2}. \end{aligned}$$

Then,

$$(5.17) \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathcal{P}_\lambda = \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathfrak{J}_p = \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \sqrt{|c|} (\mathbf{A}_\lambda + \mathbf{B}_\lambda + \mathbf{C}_\lambda).$$

From (3.1) and (5.1) we obtain the following limits:

$$(i) \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} c = \frac{\eta_+(\lambda)^4 - 1}{\eta_+(\lambda)^6},$$

$$(ii) \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{A}_\lambda = \frac{2\eta_+(\lambda)^3(1 + \sqrt{1 + \eta_+(\lambda)^4}(1 - \eta_+(\lambda)^4))}{\sqrt{\eta_+(\lambda)^4 - 3(\eta_+(\lambda)^8 - \eta_+(\lambda)^4 - 1)}},$$

$$(iii) \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{B}_\lambda = \frac{\eta_+(\lambda)^3(\sqrt{\eta_+(\lambda)^4 - 1}(1 + \eta_+(\lambda)^4) - \eta_+(\lambda)^6)(2 + \sqrt{1 + \eta_+(\lambda)^4})}{\sqrt{3 + \eta_+(\lambda)^8 - 4\eta_+(\lambda)^4(1 + \eta_+(\lambda)^4)\sqrt{1 + \eta_+(\lambda)^4} - \eta_+(\lambda)^2\sqrt{\eta_+(\lambda)^8 - 1}}},$$

$$(iv) \quad \lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathbf{C}_\lambda = \frac{\eta_+(\lambda)^3(\sqrt{\eta_+(\lambda)^4 - 1}(1 + \eta_+(\lambda)^4) + \eta_+(\lambda)^6)(2 + \sqrt{1 + \eta_+(\lambda)^4})}{\sqrt{3 + \eta_+(\lambda)^8 - 4\eta_+(\lambda)^4(1 + \eta_+(\lambda)^4)\sqrt{1 + \eta_+(\lambda)^4} - \eta_+(\lambda)^2\sqrt{\eta_+(\lambda)^8 - 1}}}$$

Substituting (i)-(iv) in (5.17) we conclude

$$\lim_{e_2 \rightarrow \eta_+(\lambda)^-} \mathcal{P}_\lambda(e_2) = \chi(\lambda),$$

as stated. \square

Finally, the proof of Theorem 4.5 follows from the limits shown in previous lemmas in combination with the continuity of the period map \mathcal{P}_λ .

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(E. MUSSO) DIPARTIMENTO DI MATEMATICA, POLITECNICO DI TORINO, CORSO DUCA DEGLI ABRUZZI 24, I-10129 TORINO, ITALY

Email address: `emilio.musso@polito.it`

(A. PÁMPANO) DEPARTMENT OF MATHEMATICS AND STATISTICS, TEXAS TECHU UNIVERSITY, LUBBOCK, TX, 79409, USA

Email address: `alvaro.pampano@ttu.edu`