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Experimental Demonstration of Beam Scanning of Dual-Metasurface Antenna

Lucia Teodorani ^{1,*}, Francesco Vernì ^{1,†}, Giorgio Giordanengo ², Rossella Gaffoglio ² and Giuseppe Vecchi ¹

- ¹ Antenna and EMC Lab (LACE), Department of Electronics and Telecommunication (DET), Politecnico di Torino, 10129 Torino, Italy
- ² Advanced Computing, Photonics and Electromagnetics Area, Fondazione LINKS, 10138 Torino, Italy
- * Correspondence: lucia.teodorani@polito.it
- + Current address: Huawei, Milan Research Center, 20054 Segrate, Italy.

Abstract: Beam-scanning antennas are employed in a wide range of applications, such as in satellite communications and 5G networks. Current commercial solutions rely mostly on electronically reconfigurable phased arrays, which require complex feeding networks and are affected by high losses, high costs, and are often power-hungry. In this paper, a novel beam scanning architecture employing a pair of planar metasurfaces, for use in thin reconfigurable antennas, is presented and experimentally demonstrated. The structure consisted of a radiative passive (non-reconfigurable) modulated metasurface, and a second metasurface that controls beam pointing, operating as a variable-impedance ground plane. Unlike other existing approaches, surface impedance variation was obtained by on-plane varactor diodes, no vias and a single voltage bias. This paper presents a design procedure based on an approximate theoretical model and simulation verification; a prototype of the designed antenna was fabricated for operation in X band, and a good agreement between measured results and simulations was observed. In the presented simple embodiment of the concept, the angular scanning range was limited to 10°; this limitation is discussed in view of future applications.

Keywords: beam steering; leaky-wave antenna; reconfigurable metasurface; varactors

1. Introduction

In recent years, reconfigurable antennas have been the subject of constantly growing interest, since beam steering is required in a wide range of present, emerging, and future applications, as in satellite communications, radars, 5G, and beyond-5G networks [1–3].

Commercial solutions, current and under development, rely mostly on electronically reconfigurable phased arrays, but the inherent complex feeding networks and high losses make these antennas less than optimal [4]; this has prompted research into alternative architectures. Among these, solutions are favored in which the radiating part and the power distribution structure coexist; the interplay between wave guiding (spatial power distribution) and radiation is well-captured by the leaky-wave paradigm [5–7], which allows for approximate designs. Beam steering at a fixed frequency has been achieved using materials with tunable electric properties [8–11], performed electromechanically [12] or by employing a multitude of (lumped) active components such as varactors [4,13–18].

In [18], varactors were used to individually load the grooves of a corrugated microstrip line, with operation below 6 GHz; the resulting antenna was thin and simple but the use of (TEM) microstrip guiding likely affected operation at higher frequencies because of the intrinsic losses. In [14], varactors were employed as tuning elements for a high-impedance surface in a 1D Fabry–Perot leaky-waveguide; the inherent transverse resonance mechanism required a thickness of about 3/4 wavelength. In [4], varactors were inserted into tunableimpedance phase-shifting side walls in a waveguide antenna (a modified WR90) derived from a standard waveguide slot array (in leaky-wave operation mode).



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Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). One of the most recent uses of metasurfaces is as refracting or reflective intelligent surfaces [19–21], also beamformers [22] for satellite-terrestrial networks have been revamped.

In this paper, a novel fixed-frequency beam scanning mechanism is introduced and demonstrated. The main goal of the present study was to investigate the potential of beam steering via distributed varactor diodes with a *single* DC control, i.e., on-plane varactors and no vias: this can be realized with existing standard low-cost technologies (e.g., pick-and-place). Using the metasurface paradigm, varactors can act as variable (reactive) loads in a suitably designed texture, yielding a variable impedance surface, with a surface impedance value controlled by the DC bias.

By combining a modulated upper metasurface (responsible for radiation) with a reconfigurable impedance plane (responsible for beam scanning), we effectively separated RF wave propagation from DC bias, while maintaining a very small form factor.

In this paper, Section 2 illustrates the adopted design techniques and describes the geometry of the designed antenna, while simulation results and experimental measurements of the fabricated prototype are reported in Section 3. In Section 4, these results are discussed and future work is outlined. Finally, conclusions are drawn in Section 5.

2. Materials and Methods

2.1. Principle of Operation

The beam scanning mechanism was conceived as a *dual* metasurface structure (see Figure 1a). Radiation is effected by a (static) transparent metasurface with metal texture on a dielectric (inspired by [23]); in a fixed-beam configuration, the radiating metasurface would be backed by a metal plane providing wave guiding. Here, the ground plane was replaced by a *tunable-impedance metasurface*. The principle of operation was based on the radiation of a guided wave, whose phase velocity was controlled by the variable-impedance surface.

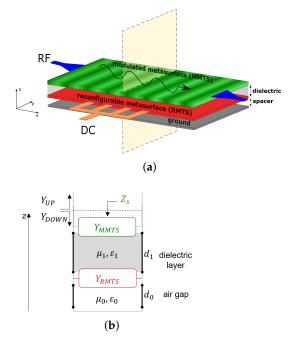


Figure 1. Structure of the proposed antenna. (a) Schematic architecture. (b) Transverse equivalent network: Y_{MMTS} is the admittance of the upper metasurface, Y_{RMTS} is the admittance of the lower (reconfigurable) metasurface, d_1 is the thickness of the dielectric layer, d_0 indicates the air gap, Y_{UP} and Y_{DOWN} are the admittances looking up and down from the interface between the antenna and free space, Z_s is the equivalent impenetrable surface impedance that approximates the whole multilayer structure.

The present study considered an antenna with scan in the vertical plane; the transverse size can range from small to multi-wavelength, depending on the type of feeding structure.

For the sake of simplicity, here the intermediate size of one wavelength was considered, which would allow for star-type 2D scanning [24].

Radiation of a guided mode is conveniently framed in the leaky-wave paradigm; hence, radiation happens via the spatially-modulated upper metasurface, exploiting both well-known results [5] and recent advances in metasurface antennas [23]. The operation principle, and thus the first-pass design, can be conveniently understood for the simplest modulation of the radiating metasurface, i.e., for the sinusoidal one [23]:

$$Z_{\rm s}(x) = j X_{\rm s,ave} \left[1 + M \cos\left(\frac{2\pi}{p}x\right) \right],\tag{1}$$

where Z_s is the equivalent impenetrable surface impedance that approximates the whole multilayer structure and takes into account the effects of both metasurfaces (Figure 1b), *x* is the coordinate along the direction of wave propagation, *M* is the modulation index, *p* is the modulation period, and $X_{s,ave}$ is the average surface reactance.

In this case, leaky-wave radiation happens for the n = -1 Floquet harmonic of the traveling wave [5,23]; for TM mode propagation, the radiation angle θ_{-1} is linked to the average surface reactance $X_{s,ave}$ by the approximate expression [18,23]:

$$\theta_{-1} = \arcsin\left(\sqrt{1 + \left(\frac{X_{\text{s,ave}}}{\eta_0}\right)^2} - \frac{2\pi}{k_0 p}\right),\tag{2}$$

where η_0 , k_0 are the free-space impedance and wavenumber, respectively.

2.2. Design Method

The design was carried out in terms of standard guided-mode analysis [25] via the Transverse-Resonance Equation (TRE). As depicted in Figure 1b, the total admittance from the antenna-free space boundary was controlled by the variable impedance layer, resulting in a controllable wavenumber of the guided wave.

The use of the usual "adiabatic" approximation for slow variations of the top impedance allowed us to approximate the antenna with a transverse equivalent network (TEN) (see Figure 1b) at any given sample point of the modulated structure. From this transmissionline representation of the structure, the *local* value of the surface impedance $Z_s(x)$ can be retrieved by solving the corresponding TRE:

$$Y_{\rm UP}(x) + Y_{\rm DOWN}(x) = 0, \tag{3}$$

where Y_{UP} and Y_{DOWN} are the admittances looking up and down from a reference plane located at the interface between the antenna and free space. Indicating with d_1 the thickness of the dielectric layer between the two metasurfaces and with d_0 the air gap between reconfigurable metasurface and ground plane, standard transmission-line theory yields [26]:

$$Y_{\rm UP} = Y_0^{\rm TM} \tag{4}$$

$$Y_{\text{DOWN}} = Y_{\text{MMTS}} + Y_1^{\text{TM}} \frac{Y_{\text{EGP}} + jY_1^{\text{TM}} \tan(k_{z1}d_1)}{Y_1^{\text{TM}} + jY_{\text{EGP}} \tan(k_{z1}d_1)}$$
(5)

$$Y_{\text{EGP}} = Y_{\text{RMTS}} - jY_0^{\text{TM}} \cot(k_{z0}d_0), \tag{6}$$

where Y_{MMTS} is the admittance of the upper metasurface, Y_{RMTS} is the admittance of the lower (reconfigurable) metasurface, and Y_{EGP} is the admittance of the equivalent ground

plane looking down from just above the tunable impedance plane (Figure 1b). In (4)–(6), Y_0^{TM} and Y_1^{TM} are the TM wave admittances in free space and dielectric substrate:

$$Y_0^{\rm TM} = \frac{\omega \varepsilon_0}{k_{z0}} \tag{7}$$

$$f_1^{\rm TM} = \frac{\omega \varepsilon_1}{k_{z1}},\tag{8}$$

where k_{z0} and k_{z1} are the wavenumbers in the transverse direction:

1

$$k_{z0} = \sqrt{k_0^2 - k_x^2} \tag{9}$$

$$k_{z1} = \sqrt{k_1^2 - k_{x'}^2} \tag{10}$$

and k_x is the longitudinal wavenumber. From (5) and (6), it can be seen that the solution of the TRE depends on the sheet admittances of both metasurfaces (Y_{MMTS} and Y_{RMTS}). Since all quantities in (4)–(6) can be expressed as a function of k_x , it is possible to solve (3) for k_x and then obtain the (local) surface impedance as:

$$Z_{\rm s} = jX_{\rm s} = \frac{1}{\gamma_{\rm DOWN}}.$$
(11)

It is worth noting that the longitudinal wavenumber k_x considered above is used only to compute the local surface impedance based on the adiabatic approximation, and does not correspond to the actual wavenumber of the leaky wave that arises from the modulation of such impedance.

The average value of X_s is linked to the radiation angle through (2). This means that tuning Y_{RMTS} directly affects the beam direction, thus validating the concept of this architecture. Once a desired radiation angle for the n = -1 harmonic is chosen, the modulation period p is retrieved from (2) after selecting a proper value of $X_{s,ave}$ among those physically attainable with the considered structure.

The design process now requires the choice of the geometry of both metasurfaces and the computation of their sheet admittances Y_{MMTS} and Y_{RMTS} , in order to solve (3). For the upper layer, a unit cell was chosen such that its admittance can be easily modulated by varying only one geometric feature, e.g., the gap width between two adjacent metal strips, as in [23]. For the implementation of the tunable metasurface, the unit cell shown in Figure 2 was used. This shape was inspired by the geometry described in [27]. Each unit cell contained two MAVR-011020-1411 varactors that were approximated as RC series elements for simulation purposes; the values of resistance and voltage-dependent capacitance were taken from the manufacturer's datasheet [28]. Varying the bias voltage changes the varactors' capacitance, which in turn affects the sheet admittance of this layer.

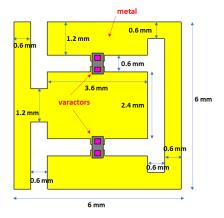


Figure 2. Unit cell of the reconfigurable metasurface.

The computation of Y_{MMTS} must be carried out for every possible value of the gap width in the constitutive unit cell, while Y_{RMTS} must be determined for every possible biasing state of the varactor diodes. This allowed us to obtain the equivalent impenetrable surface reactance X_s by solving the TRE for every combination of gap width in the upper metasurface and capacitance value in the reconfigurable plane. Moreover, at any given frequency, both admittances are also dependent on the longitudinal wavenumber k_x [14,29]: namely, $Y_{\text{MMTS}} = Y_{\text{MMTS}}(g, k_x)$ and $Y_{\text{RMTS}} = Y_{\text{RMTS}}(C, k_x)$, where g and C are the gap width and the varactors' capacitance, respectively. Therefore, to compute such admittances, the technique described in [14,30] was adopted, where the dependence on the longitudinal wavenumber was retrieved by performing scattering simulations of the constitutive unit cells for different angles of incidence. In particular, similarly to what was carried out in [30], the rational functions used to express Y_{MMTS} and Y_{RMTS} are:

$$Y_{\text{MMTS}}(g,k_x) = j \frac{[g - g_{z1}(k_x)][g - g_{z2}(k_x)]}{g[g - g_{p1}(k_x)][g - g_{p2}(k_x)]}$$
(12)

$$Y_{\text{RMTS}}(C,k_x) = j \frac{[C - C_{z1}(k_x)][C - C_{z2}(k_x)][C - C_{z3}(k_x)]}{C - C_p(k_x)}.$$
(13)

In (12) and (13), subscripts *z* and *p* indicate zeros and poles of the rational functions. These quantities are expressed as third degree polynomials of k_x . In the frequency range of interest ([10.55–10.75] GHz), for the considered geometries, Y_{MMTS} is capacitive and Y_{RMTS} is always inductive.

Figure 3 shows how the surface reactance of the whole antenna is affected by a change in the varactors' bias voltage. The curve relating X_s to the gap width is shifted when the bias voltage goes from 0 V to 8.2 V. This means that, for a fixed spatial modulation in the upper layer, the sinusoidal profile of the surface reactance (and its average value $X_{s,ave}$) seen by the traveling wave is dependent on the varactors' basing state. Since $X_{s,ave}$ is linked to the radiation angle through (2) and the period *p* is fixed by the upper metasurface, beam steering occurs.

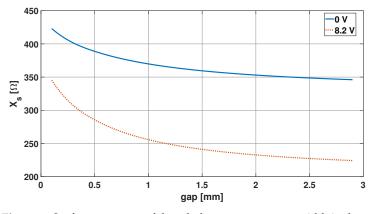


Figure 3. Surface reactance of the whole structure vs gap width in the array of strips, for two different values of the varactors' bias voltage.

2.3. Implementation

A center-band frequency of 10.65 GHz was considered. A Rogers RT5880 ($\varepsilon_r = 2.2$, tan $\delta = 0.0009$) 3.175 mm-thick substrate was placed between the upper radiating layer and the lower variable-impedance plane. The unit cell of the modulated metasurface was chosen to be about 1/10 of the wavelength, i.e., 3 mm. The air gap between the reconfigurable plane and the ground was set to 1.5 mm in order to allow enough space for the variators.

The modulation period *p* of the top impedance surface was computed from (2), setting a radiation angle of 20° for a 0 V bias voltage of the varactors, and this resulted in p = 27 mm. Since the unit cell of the modulated metasurface was 3 mm wide, the cosi-

nusoidal variation of the reactance in one period was sampled in nine points, i.e., with sufficient sampling. For the radiating part, eight modulation periods were chosen for a total length of 216 mm; this was a good compromise between beam width and (leaky-wave) tapering and, at any rate, yielding low S_{21} towards the matched load.

The bias scheme of the varactors in the variable-impedance plane is depicted in Figure 4, which shows an alternate-potential scheme. The necessary single DC bias was conveyed by two 0.15 mm-wide buses placed at the opposite sides of the metasurface; the RF reactance of the very thin (high-impedance) lines was considered enough to decouple RF and DC without the need for a filter, and that was confirmed by simulations.

The resulting complete structure of the designed antenna is shown in Figure 5. The upper modulated metasurface is depicted in Figure 5a, while Figure 5c shows the lower reconfigurable impedance plane; the vertical stackup of the antenna can be seen in Figure 5b. The overall thickness of the structure was less than $\lambda_0/6$ at the working frequency of 10.65 GHz, resulting in a very small form factor. It should be noted from Figure 6 that the unit cell of the reconfigurable metasurface was twice as large as that of the upper layer, in order to reduce the total number of varactors needed in the structure, which amounted to 360.

The excitation was provided with a 50 Ohm coaxial cable, which was matched to the antenna by a properly designed tapered section (Figure 5a).

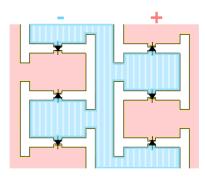


Figure 4. DC voltage distribution in the reconfigurable metasurface.

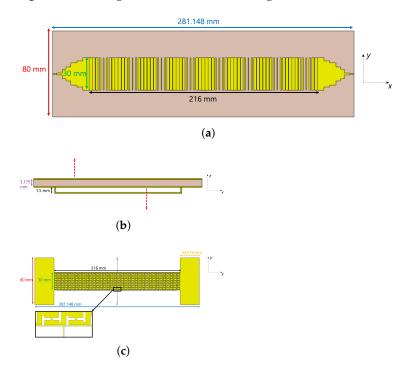


Figure 5. Complete model of the designed antenna. (a) Upper sinusoidally modulated reactance surface.(b) Lateral view of the antenna. (c) Reconfigurable plane; the inset shows one of the two DC buses.

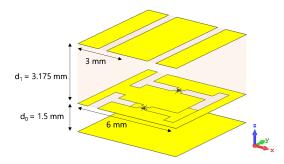


Figure 6. Unit cell of the fully-stacked structure.

3. Results

Full-wave simulations of the designed antenna were performed with the commercial software CST Studio Suite [31]. The varactor diodes were used in a 0–8.2 V biasing range and their capacitance went from 0.233 pF to 0.0548 pF, according to the manufacturer's datasheet [28]. The beam pointing angles obtained from these simulations at the working frequency of 10.65 GHz are listed in Table 1, showing excellent agreement with the main beam directions computed using the approximate model described in Section 2.2.

Table 1. Calculated, simulated, and measured radiation angles at 10.65 GHz.

Voltage [V]	Calculated	Simulated	Measured
0	22.7°	20°	19.5°
8.2	11.9°	13°	12.5°

A prototype was fabricated and tested (Figure 7). The modulated metasurface and the reconfigurable plane are pictured in Figure 7a,b, while Figure 7c,d show the tapered feeding section on the upper layer and the varactor diodes soldered in the lower metasurface, respectively. Radiation measurements were performed in an NF-FF spherical range; the full radiation pattern was obtained, allowing evaluation of directivity and radiation efficiency.

Measured far-field patterns at 10.65 GHz for different bias voltages are shown in Figure 8, together with the simulation results, which are in excellent agreement.

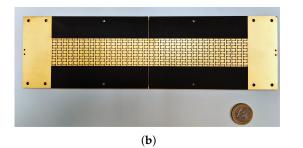
The antenna gain bandwidth was 200 MHz around the working frequency of 10.65 GHz; the impedance bandwidth was larger than the gain one. The scattering parameters S_{11} and S_{21} of the fabricated prototype are shown in Figure 9: S_{11} was always below -10 dB in the working band for all varactors' bias voltages, while S_{21} remained below -20 dB, which is very important for the efficiency of a traveling-wave antenna.

In the considered frequency range, the gain spanned from 11.6 dB to 13.4 dB with varying bias voltage, while the radiation efficiency was between 67% and 76%. The measured aperture efficiency went from 20% to 32%.

In Figure 8, a side-lobe is noticeable in the backward radiation direction; this lobe can be ascribed to radiation of the n = -2 harmonic, which falls within the fast wave region at the working frequency [23]. These results are consistent with what can be predicted using (2), i.e., the n = -2 harmonic radiating at about -41° and -57° for a bias voltage equal to 0 V and 8.2 V, respectively. The radiation pattern also presents an irregular shape and high side-lobes; this can be ascribed to the anisotropy of the impedance planes, in particular of the lower reconfigurable metasurface. In fact, its unit cell geometry and the placement of the varactor diodes inside it are such that a change in the bias voltage alters not only the component of the sheet impedance in the direction of wave propagation, but also the transverse one. This may cause disturbances in the wave propagation.



(a)



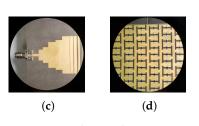
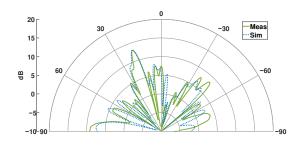
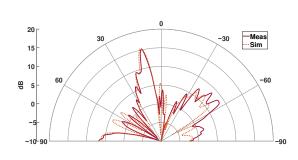


Figure 7. Fabricated antenna prototype. (a) Top modulated metasurface. (b) Reconfigurable impedance plane. (c) Coaxial cable and matched tapered input section at the left end of the upper metasurface (same tapered section is present at the opposite end). (d) Zoom showing the soldered varactors in the lower reconfigurable metasurface.







(**b**) 8.2 V

Figure 8. Measured and simulated radiation pattern in the E-plane at 10.65 GHz for different values of bias voltage.

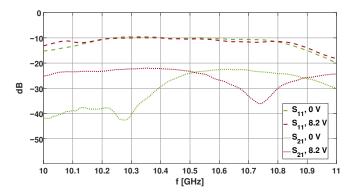


Figure 9. Measured S_{11} and S_{21} for two different values of bias voltage.

4. Discussion

In Table 2, the performances of the antenna described in this paper are compared to those of other solutions found in the literature. In the table, "efficiency" stands for radiation efficiency.

Table 2. Comparison with other LWAs found in the literature.

Reference	Frequency [GHz]	Scanning Range	Antenna Length	Thickness	Efficiency	Gain [dB]
[14]	5.6	21°	$5\lambda_0$	$3\lambda_0/4$	60–75%	5–13
[18] Band 2	5.75	22°	$7.15\lambda_0$	$\lambda_0/17$	40-50%	9.5-12
[4]	9.3	43°	$13\lambda_0$	$\lambda_0/3$	38-46%	8-11.8
This work	10.65	7°	$7.7\lambda_0$	$\lambda_0/6$	67–76%	11.6–13.4

Radiation efficiency and gain values are comparable to those reported in the other works (above the average). The comparison is conservative because all reported references work at a lower frequency, which inherently entails lower losses. The small form factor, simple biasing and high efficiency make the proposed architecture interesting for several low-profile applications. The angular scanning range achieved with this first prototype is, on the other hand, limited: improvement of this is thus important and the subject of current work. Here, some of the reasons for this limitation are listed and ways to improve it are proposed.

A possible degree of improvement is represented by the choice of the dielectric substrate and its thickness, especially for the side lobes. In particular, a higher relative permittivity results in a wider range of surface reactance values, X_s , which allows for a larger modulation factor M and, consequently, a higher leakage constant [23]. This in turn translates into the reduction of side-lobes.

Figure 10 shows the simulated radiation pattern at 10.75 GHz for an alternative design of the proposed antenna, featuring a Rogers RO3006 substrate ($\varepsilon_r = 6.5$) of a thickness equal to 2.56 mm: the radiation angle steers from 15° to 5° when the bias voltage goes from 0 V to 8.2 V. In this case, no other harmonic beside the n = -1 radiates, and the very small backward-directed side-lobes are due to the spurious radiation of a second, higher-order TM mode. Directivity values are the same as in the previous configuration. A further reduction of side-lobes could be obtained by tapering the modulation index *M* along the length of the antenna [32], which was not pursued here.

Another margin of improvement involves the geometry of the reconfigurable metasurface's unit cell. The tunable unit cell used in this first prototype was inspired by the literature and had a different original use [27]; a new geometry could be devised to obtain a wider impedance range for the same diodes.

Moreover, the design presented in this paper was based on the combination of a capacitive impedance (top) and an inductive one (bottom), and the propagation of the TM mode. However, different combinations of impedances can be employed (e.g., capacitive-

capacitive) that may increase the scanning range if properly designed, especially if a dielectric material with higher electric permittivity is used. In particular, analyses carried out with the approximate analytical model show that use of the TE mode (instead of the TM) yields a much larger steering range. This possibility is currently being studied and will be the subject of future work (excitation of the TE mode is less natural than that of the TM).

Finally, the radiating surface employs the standard sinusoidal modulation scheme; the scan range can be improved (for the same impedance variation of the bottom plane) by more advanced impedance modulation schemes, and especially by ad-hoc numerical optimization of the profile [33,34]; this has shown the potential of increasing sensitivity to phase velocity, thus enhancing the scanning range.

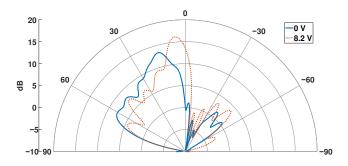


Figure 10. Simulated radiation pattern at 10.75 GHz for different bias voltages for an alternative design with Rogers RO3006 substrate ($\varepsilon_r = 6.5$).

5. Conclusions

In this work, a novel beam steering configuration with varactor diodes, a single voltage bias, and no bias has been demonstrated. The small form factor, simple biasing, and high efficiency make the proposed architecture interesting for low-profile applications. The angular scanning range achieved with this first prototype is limited, but several ways to improve it were discussed.

Author Contributions: Conceptualization, G.V.; methodology, L.T. and F.V.; software, L.T.; validation, L.T., F.V., G.G. and R.G.; formal analysis, L.T. and F.V.; investigation, L.T., F.V. and G.G.; resources, G.G. and G.V.; data curation, L.T. and R.G.; writing—original draft preparation, L.T.; writing—review and editing, G.G., R.G. and G.V.; visualization, L.T., G.G. and R.G.; supervision, G.V.; project administration, G.V.; funding acquisition, G.V. All authors have read and agreed to the published version of the manuscript.

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