

Live Demonstration: A Real-Time Bio-Mimetic System for Multichannel FES Control

*Original*

Live Demonstration: A Real-Time Bio-Mimetic System for Multichannel FES Control / Rossi, Fabio; Prestia, Andrea; Mongardi, Andrea; Landra, Nicolo; Ros, Paolo Motto; Demarchi, Danilo. - ELETTRONICO. - (2022), pp. 248-248. ( 2022 IEEE Biomedical Circuits and Systems Conference (BioCAS) Taipei, Taiwan 13-15 October 2022) [10.1109/BioCAS54905.2022.9948597].

*Availability:*

This version is available at: 11583/2973190 since: 2022-11-18T11:08:26Z

*Publisher:*

IEEE

*Published*

DOI:10.1109/BioCAS54905.2022.9948597

*Terms of use:*

This article is made available under terms and conditions as specified in the corresponding bibliographic description in the repository

*Publisher copyright*

IEEE postprint/Author's Accepted Manuscript

©2022 IEEE. Personal use of this material is permitted. Permission from IEEE must be obtained for all other uses, in any current or future media, including reprinting/republishing this material for advertising or promotional purposes, creating new collecting works, for resale or lists, or reuse of any copyrighted component of this work in other works.

(Article begins on next page)

# Live Demonstration: A Real-Time Bio-Mimetic System for Multichannel FES Control

Fabio Rossi, Andrea Prestia, Andrea Mongardi, Nicolò Landra, Paolo Motto Ros, Danilo Demarchi  
Dipartimento di Elettronica e Telecomunicazioni, Politecnico di Torino, Torino, Italy, Email: fabio.rossi@polito.it

**Abstract**—This demonstration presents a bio-mimetic system for the real-time multichannel control of Functional Electrical Stimulation (FES). The intensities of the FES profiles are directly mapped by processing surface ElectroMyoGraphic (sEMG) signals detected from synergistic muscles, thus achieving a user-comfortable stimulation that follows the monitored physiological patterns. Furthermore, a user-dedicated calibration routine and multiple versatile operating configurations allow the system to be integrated into standard rehabilitation protocols to enhance the restoration of motor functionalities.

**Index Terms**—Activities of Daily Living, Electromyography, Functional Electrical Stimulation, Rehabilitation Engineering

## I. OVERVIEW

Spinal cord injury, stroke, and multiple sclerosis neurological disorders are still among the leading causes that gravely compromise the quality of life for people suffering them. Depending on the severity of the neuromuscular damage, some motor functions could be (partially) restored by participating in rehabilitation sessions. The application of Functional Electrical Stimulation (FES) therapy to skeletal muscles has been demonstrated to induce several benefits, e.g., promoting neuro-plasticity, maintaining muscular body mass, and preserving tissue circulation. Recent studies [1] explored how the combination of the active modulation of the FES parameters, defined by processing the surface ElectroMyoGraphic (sEMG) information, and the synergistic stimulation of coordinated muscle groups further enhances functional recovery.

In this demonstration<sup>1</sup>, we present the latest implementation of our sEMG-controlled FES system, which correlates voluntary muscle activity profiles with computed bio-mimetic FES patterns. Starting from the system architecture reported in [2], here we replace the sensing units with our new custom wearable acquisition devices [3]. Furthermore, additional processing modules have been implemented to achieve independent and synergistic muscle stimulation simultaneously, thus allowing the operator to perform and control the evolution of coordinated movements easily.

Fig. 1 represents one of the proposed operating scenarios, which involves two subjects, the therapist (left) and the patient (right), during the execution of a typical daily-life action, e.g., drinking from a bottle. The subjects are supposed to be seated one in front of the other to follow the entire motion visually. The fast setup requires placing the acquisition devices and the stimulation electrodes above the desired muscle bellies. After the system initialization (e.g., pairing between acquisition

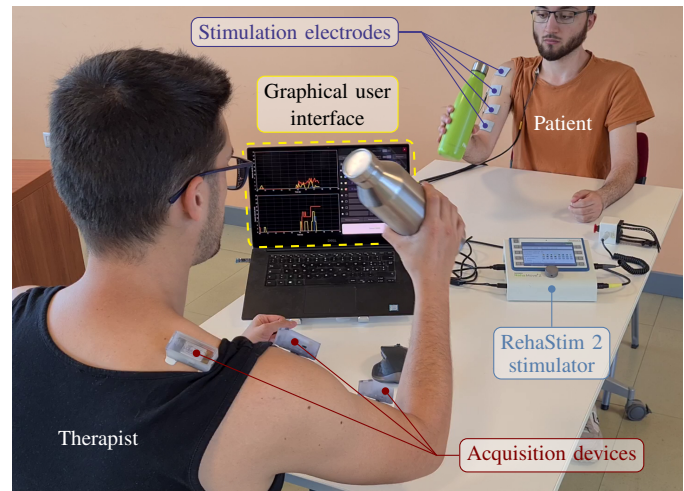


Fig. 1. Representative setup for the therapist-patient configuration.

and stimulation channels), a calibration routine balances the therapist's muscular activity with the FES pulse intensity suitable to elicit an adequate muscle response in the patient. Then, the FES session can start: the exercise performed by the therapist is induced in the patient, who, as instructed during the calibration phase, would try to complete the movement to the best of her/his physical condition.

## II. VISITORS EXPERIENCE

Visitors can view and eventually participate (limited to the therapist role for medical-security reasons) to a simulated rehabilitative session, experimenting the following system functionalities:

- Bio-mimetic FES profiles generation;
- Therapist-patient real-time movements replication;
- Self-controlled FES patterns modulation;
- Pre-computed stimulation sequences.

## REFERENCES

- [1] M. A. Khan, M. Saibene, R. Das, I. Brunner, and S. Puthusserypady, "Emergence of flexible technology in developing advanced systems for post-stroke rehabilitation: a comprehensive review," *Journal of Neural Engineering*, vol. 18, no. 6, p. 061003, dec 2021.
- [2] A. Prestia, F. Rossi, A. Mongardi, P. Motto Ros, M. Ruo Roch, M. Martina, and D. Demarchi, "Motion analysis for experimental evaluation of an event-driven FES system," *IEEE Transactions on Biomedical Circuits and Systems*, vol. 16, no. 1, pp. 3–14, 2022.
- [3] F. Rossi, A. Mongardi, P. Motto Ros, M. Ruo Roch, M. Martina, and D. Demarchi, "Tutorial: A versatile bio-inspired system for processing and transmission of muscular information," *IEEE Sensors Journal*, vol. 21, no. 20, pp. 22 285–22 303, 2021.

<sup>1</sup>A preview is available at [https://youtu.be/9-rx6uZ4w\\_I](https://youtu.be/9-rx6uZ4w_I).