

Automated method for routine microplastic detection and quantification

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(Article begins on next page)

1 **Automated method for routine microplastic detection and quantification**

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13

14 **Abstract**

15 Microplastics (MPs) are a heterogeneous group of solid polymers with dimensions less than 5 mm, which  
16 are a widespread contaminant of the environment. Their ubiquitous presence grabbed researchers' attention  
17 in the last decade, and the problem of MPs detection and quantification is currently a topic of utmost  
18 importance. Most identification and quantification protocols are still based on the visual count, which is an  
19 extremely time-consuming and error-prone task due to operator subjectivity. To address such an issue,  
20 different software analysis procedures are available, but they mainly rely either on the use of optical  
21 microscopy, covering a minimal area for each sample (mm<sup>2</sup> size), or they allow only the identification of  
22 the largest particles (>1mm). Here, a semi-automatic innovative image processing method for quantifying  
23 and measuring microplastics on filter membrane substrates is presented and validated, comparing results  
24 with data obtained using visual counting performed by an experienced operator. The algorithm was tested  
25 with artificially generated microplastic images and samples taken from natural environments. Samples of  
26 Borgio Verezzi show cave sediment and Po River water were filtered on a glass filter membrane, and

27 photographs were taken under 365 nm illumination, both without and with Nile Red staining. The proposed  
28 image analysis method, implemented in an easy-to-use Python script, was quite accurate and fast (about 10  
29 s/image average processing time), showing an average deviation below 10%, which is further reduced to  
30 about 8% if the samples are stained with Nile Red.

31

32 **KEYWORDS:** Microplastic pollution, staining dye, fluorescence, water and sediment monitoring, image  
33 analysis

34

### 35 **1. Introduction**

36 Microplastics (MPs) are a heterogeneous group of solid polymers generally considered with a dimension  
37 less than 5 mm by the scientific community, originating from primary production or from the fragmentation  
38 of larger plastics (secondary production) (Corami et al., 2020). MPs lead to environmental contamination  
39 worldwide (Ha and Yeo, 2018) and have been widely found in marine and terrestrial environments, even  
40 transported in the air (Balestra and Bellopede, 2022; Boyle and Örmeci, 2020; Chia et al., 2021; Cutroneo  
41 et al., 2020; Guerranti et al., 2017; Huang et al., 2021; Ren et al., 2021; Samandra et al., 2022; Zhang et al.,  
42 2019).

43 Monitoring MP pollution in the environment is essential to understand better their sources and their  
44 impacts on ecosystems and human health (Barboza et al., 2018; Henry et al., 2018; Prata et al., 2019;  
45 Sharma and Chatterjee, 2017). Despite a large consensus in recognizing the importance of MPs monitoring  
46 protocols, there is no universal methodology for analyzing MPs. The visual identification method for  
47 counting and sorting MPs based on color, size, and shape, is one of the most commonly used (Alomar et  
48 al., 2016; Balestra and Bellopede, 2022; Cannas et al., 2017; Hidalgo-Ruz et al., 2012; Mathalon and Hill,  
49 2014), given its inexpensive and relatively rapid implementation (Crawford and Quinn, 2016). However,  
50 such a technique is highly susceptible to operator biases and errors, thus frequently leading to  
51 misidentification (Crawford and Quinn, 2016; Prata et al., 2019). In fact, it was demonstrated that the visual

52 count by two different expert operators could differ even up to 30% from each other (Esch et al., 2020).  
53 As an improvement to the process, staining dyes, such as Nile Red, are commonly used to increase the  
54 visual identification efficacy of MPs by conferring color or fluorescence to the particles (Erni-Cassola et  
55 al., 2017; Prata et al., 2019).

56 A similar effect can be obtained by exploiting the fluorescence given by fluorescent whitening agents  
57 (FWAs) that are often used in plastic production (Qiu et al., 2015). Indeed, MPs with FWAs or after  
58 fluorescent dye application can easily be detected under a fluorescence microscope or a low-cost ultraviolet  
59 (UV) flashlight (Balestra and Bellopede, 2022; Ehlers et al., 2020; Klein and Fischer, 2019).

60 Based on their color or fluorescence, MPs could be photographed and automatically quantified by  
61 software identification, possibly removing the operator biases, and reducing the processing time, thus  
62 enabling faster processing than traditional methods. For those reasons, recently, there has been an increasing  
63 interest in image analysis techniques for MPs characterization (Gauci et al., 2019; Lorenzo-Navarro et al.,  
64 2021, 2020; Mukhanov et al., 2019; Prata et al., 2020, 2019; Wegmayr et al., 2020). The Image-J software  
65 was used by Mukhanov et al. (2019) to classify MPs into different classes, and the Microplastics Visual  
66 Analysis Tool (MP-VAT) was created by Prata et al. (2019) to automatically count fluorescent MPs stained  
67 with Nile Red dye under a specific wavelength illumination. However, different factors, such as the staining  
68 process, camera conditions and settings, introduce variability in the outcomes, thus requiring improvements  
69 that were subsequently implemented in another release of the software (MP-VAT 2.0) (Prata et al., 2020).

71 Using a MATLAB-based software (Gauci et al., 2019), MP particles extracted from samples  
72 originating from different beaches were characterized. Lorenzo-Navarro et al. (2020) counted and  
73 classified MPs particles using as input two images acquired with a high-resolution flat scanner and their  
74 System for Microplastics Automatic Counting and Classification (SMACC). Deep learning applications  
75 for MPs analysis have been employed to segment synthetic fibers in microscopy images (Wegmayr et  
76 al., 2020) and count and classify MPs using pictures taken with cameras or mobile phones (Lorenzo-  
77 Navarro et al., 2021). However, all these programs are often tested on samples created in the laboratory

78 or images taken from plastic fragments cut in controlled environments, not considering the difficulties of  
79 analyzing real samples. In images or samples created in a laboratory, MPs can be positioned very far  
80 from each other, there are no overlaps of particles, and the contours of the particles are well-defined (e.g.  
81 Lorenzo-Navarro et al, 2020). Moreover, sometimes only particles with larger dimensions are counted (e.g.  
82 Lorenzo-Navarro et al, 2020; Gauci et al., 2019). On the contrary, in real samples, particles overlap is  
83 frequently observed, and MPs are subject to erosion and biofouling, which often change their shape, color,  
84 and contours.

85 Moreover, the number of microplastics in real samples is often higher than those considered in the  
86 created images or samples. Finally, laboratory samples have no disturbing factors, while real samples  
87 often have particles and sediment powders that can make the background less uniform and clear for the  
88 optimal visualization of the particles. One of the last developments consist of a thresholding approach  
89 for fluorescence microscope images proposed by Meyer et al. (2022), where machine learning techniques  
90 are also employed for the classification of the different typologies of plastics.

91 Unfortunately, machine learning classification requires supervised training on large datasets, and most  
92 of these techniques may not perform well on real-world images if they are too different from training  
93 ones, especially when trying to detect and classify tiny and small-resolution objects in a vast uncorrelated  
94 background (Liu et al., 2021).

95 The present work aims to develop an automated counting software using images taken with cameras  
96 on filters of real samples selected in different matrices, limiting subjectivity in quantifying MPs particles  
97 and reducing the processing time compared to traditional methods. The adopted approach relies on  
98 traditional image processing techniques where the user tunes process parameters without the need to train  
99 the software on microplastic sample images.

100 The software is provided with a very easy-to-use graphical user interface (GUI) which drives the operator  
101 along all the process workflow and makes it suitable for use by inexpert researchers. The automated  
102 counting has been applied to images created with both artificial (created by an image editing software) and  
103 real samples of Borgio Verezzi show cave sediments and Po River water collected inside the city of Turin.

104

## 105 **2. Materials and methods**

### 106 **2.1. Sampling, laboratory analysis and methods**

107 For all steps, plastic equipment was avoided or replaced with non-plastic utensils. All samples were  
108 collected in glass jars and stored at 6°C until laboratory analysis. The samples were selected in two different  
109 media (water and sediment), in two different environments (open river, underground cave) to demonstrate  
110 that the algorithm can be used effectively in all types of samples, regardless of matrix or environment. The  
111 samples collected from Borgio Verezzi show cave sediments and Po River waters were treated in the  
112 laboratory with the method described in Balestra and Bellopede, 2022, improved and adapted to the specific  
113 characteristics of the matrices. Borgio Verezzi dried cave sediments, particularly rich in organic matter,  
114 were subjected to organic matter removal through the application of 30% hydrogen peroxide solution, added  
115 in 1:1 sample volume ratio, and left to act at room temperature for 5 days. Po River samples were subjected  
116 to organic matter removal through the application of 30% hydrogen peroxide solution, added in 1:10 sample  
117 volume ratio, and left to act at room temperature for 5 days. The filters were photographed under the same  
118 conditions and then observed under a microscope to obtain the abundance and characterization of MPs.  
119 Finally, all filters were stained with Nile Red dye to evaluate a possible improvement of the images to be  
120 used in the software. A volume of 1 mL of Nile Red dye solution in Acetone (1:10µg/mL) was pipetted to  
121 cover all the filters and was left to dry for 30 minutes at room temperature, covered with aluminum foil.  
122 The filters were then dried further for 1 h at 40 °C in an oven.

123 The MPs on filters were observed with a UV flashlight (Alonefire SV10 365 nm UV flashlight 5W) under  
124 a LeitzORTHOLUX II POL-MK microscope equipped with a DeltaPix Invenio12EIII 12 Mpx Camera,  
125 with high magnifications, following the identification method described in Crawford & Quinn, 2016

126

### 127 **2.2. Images setting and identification of microplastics**

128 The quantification of microplastics may be influenced by the time between sample preparation and the  
129 identification of fluorescent particles (Prata et al., 2020). This can result in a relevant miscounting of MP

130 due to the loss of dye fluorescence, particles, or a combination of both over time. Therefore, visual  
131 identification and photographs were taken the day after filtration.

132 The intensity of fluorescence produced by MPs is dependent on the luminous emittance of the LED lantern  
133 used; thus, the UV LED light used to detect and photograph MPs was continuously connected to the power  
134 line electricity.

135 Camera conditions are important when using photographs in the identification of fluorescent MPs.  
136 Evaluation of digital photographs obtained with different cameras, also during the same day (morning,  
137 noon, afternoon) and following days, can lead to variations in the quantification of particles (Prata et al.,  
138 2020). Therefore, the same camera is used for the same tests; on the same day.

139 Different factors can cause errors during the creation of the photographs, such as temperature, influencing  
140 digital camera sensor (Theuwissen, 2008, 2007), presence of visible light, reducing the contrast between  
141 particle and background, focus and stabilization of the camera, which should be kept as constant as  
142 possible (Prata et al., 2020). Picture size could also lead to the loss of particles in lower resolutions,  
143 therefore, the acquired filter membrane area in the final photograph should be maximized to produce the  
144 most reliable results (Prata et al., 2020). No significant variations in temperature and contamination with  
145 visible light are expected in the controlled environment of the dark-room used for the assays. Filters were  
146 photographed with a high-definition SLR camera (Sony ILCE-7RM3 v 1.01) equipped with a Zeiss 100  
147 mm macro 1:2 fixed vertically with an Emlid pedestal under a UV flashlight (Alonefire SV10 365 nm UV  
148 flashlight 5W) placed on a laboratory stand with clamp, with an inclination of 45° at a fixed distance.  
149 Images were taken using an exposition of -2, 200 ISO, exposure time 0.62s, and diaphragm aperture f9 and  
150 f8 for filters with and without Nile Red, respectively. The camera was stabilized, photographs were taken  
151 under constant conditions and only working operators were allowed in the room to reduce potential light  
152 pollution.

153 Six images were created with image editing software (artificial samples), using the *clone* tool. In this way,  
154 MPs extracted from photos of real samples were copied and randomly positioned on an empty membrane

155 filter picture. These pictures, with a very uniform background and no disturbance from other fluorescent  
156 particles, are very useful to evaluate first the performance of the automated counting software.

157 MPs on six filters from Borgio Verezzi cave sediments and six filters from Po River water were observed  
158 by an expert operator with a UV flashlight (Alonefire SV10 365 nm UV flashlight 5W) under a Leitz  
159 ORTHOLUX II POL-MK microscope equipped with a DeltaPix Invenio 12EIII 12 Mpx Camera, with 2.5x,  
160 4x, 10x zoom or more (Balestra and Bellopede, 2022). Particles that could not be identified as MPs were  
161 not taken into consideration. Moreover, microplastics were directly counted and measured on ImageJ, using  
162 the photos taken on 12 real sample filters and six images created with an image editing software, and  
163 compared to the data obtained using visual identification under a microscope. Visual counting of MPs on  
164 filters under a microscope and MP counting on photos using ImageJ were used to test and validate the  
165 developed image analysis method, setting the different parameters to reach a maximum 15% deviation for  
166 each filter.

167

### 168 **2.3. Processing of the filter images**

169 Different approaches may be employed for automatizing the detection of fluorescent microplastic on a filter.  
170 The simplest one consists of the manual color thresholding of the image, but this may lead to the omission  
171 of some microplastics from the count since the fluorescence intensity is variable for the different polymers  
172 and can be influenced by the presence of contaminations on the microplastic surface.

173 For the same reason, automatic thresholding techniques are also not applicable and can lead to very  
174 confounding results (see Supplementary Information Figure S1).

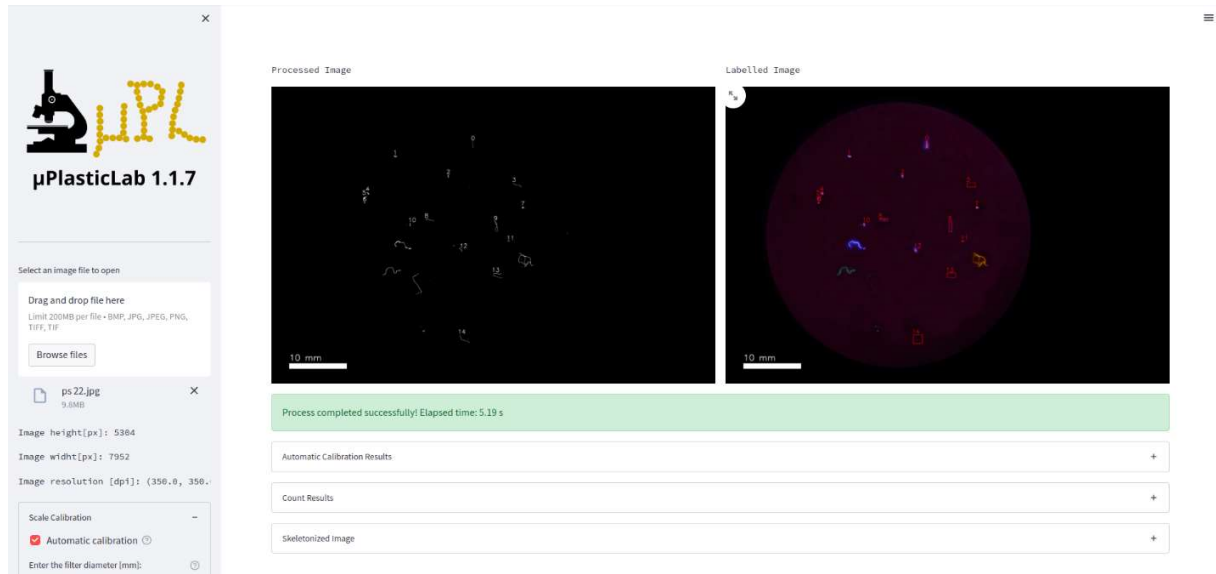
175 Automatic local thresholding algorithms, which apply a different threshold to different portions of the  
176 image determined based on local information of the pixels, could represent a viable solution. Unfortunately,  
177 the presence of strong halos around some fluorescent plastics leads to the failure of this class of techniques  
178 (see Supplementary Information Figure S2). Due to the limitations of the above-mentioned segmentation  
179 techniques, a more elaborate approach is required for the automatic segmentation of the microplastic filter  
180 images.

181 This work introduces and validates a novel segmentation technique based on the Canny edge detection  
182 algorithm (Russ, 2016) that overcomes the problem of low-intensity fluorescent fibers and fluorescence  
183 halos. Fluorescent pixels due to the presence of halo on MP photos under UV light are generally considered  
184 by existing automatic counting programs, generating a size and shape error in the counted MPs. In fact,  
185 instead of thresholding the image according to pixel intensity, the Canny algorithm works on its gradient.  
186 After the gradient calculation, a non-maximum suppression step removes pixels that are likely to be  
187 redundant and not part of an edge, and the image is finally thresholded according to a hysteresis threshold  
188 method (Nixon, 2013). Moreover, morphological information such as length, thickness, and shape factor  
189 are calculated for each microplastic which is eventually categorized as particle, fragment, or fiber.

190

#### 191 **2.4. Development of a tool for the automated processing of sample images**

192 The processing of the images has been performed through a specifically made Python script named  
193 *MicroplasticLab* (MUPL), mainly based on *OpenCV* ("Open CV Releases," n.d.) and *SkImage* ("Installing  
194 scikit-image — skimage v0.19.2 docs," n.d.) libraries. MUPL is released as open-source software under  
195 MIT license and provided with a web-based graphical user interface, shown in Figure 1, powered by the  
196 open-source app framework Streamlit (Richards, 2021; "Streamlit • The fastest way to build and share data  
197 apps," n.d.). The aim is to provide researchers and lab analysts with complete support, and for that, the  
198 software also contains some functionalities to prepare the picture for publications, e.g., cropping, adding a  
199 reference bar, etc. To ensure high performance and minimize processing time, MUPL has been designed  
200 for running its functions, where possible, under Numba Compiler ("Numba: A High Performance Python  
201 Compiler," n.d.).



202

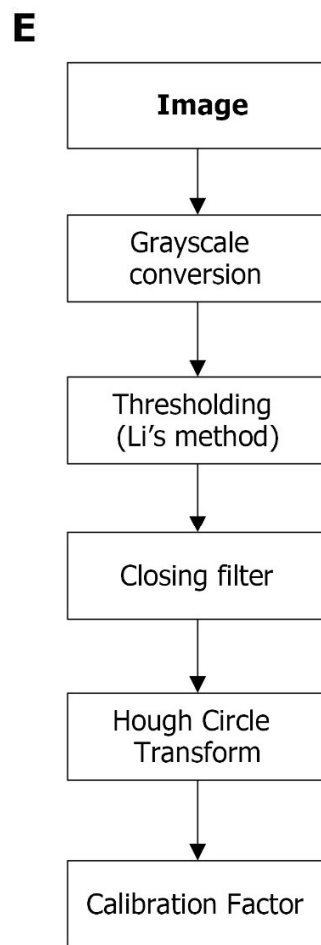
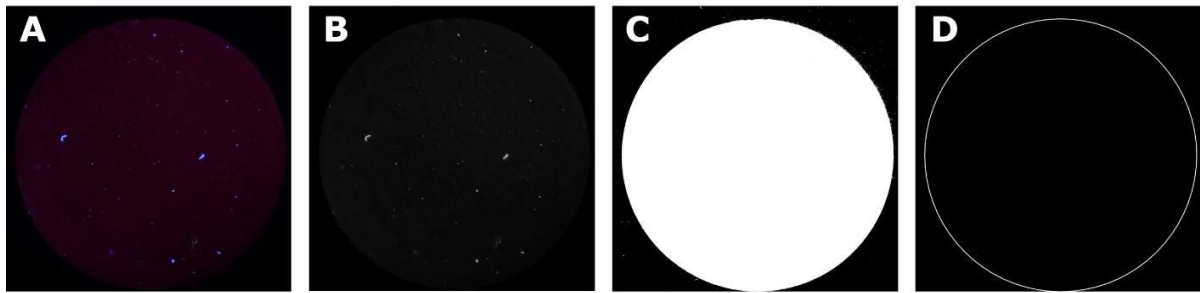
203 **Figure 1:** The user interface of MUPL running in a web browser. The results of processing the pictures  
 204 acquired in the frame of this work are shown in the figure.

205

## 206 **2.5. Automatic Detection of Scale Factor**

207 The computation of the scale factor is undoubtedly required to convert the measurements performed on  
 208 the image from pixel number to a unit of length, i.e., mm. MUPL offers the double possibility of manually  
 209 entering a predetermined scale factor or automatically calculating it from the image if the filter membrane  
 210 diameter (in millimeters) is entered.

211 The automatic determination process, summarized in Figure 2, is based on the grayscale conversion and  
 212 subsequent image thresholding by computing the threshold value according to the entropy method proposed  
 213 by Li (Li and Lee, 1993; Sezgin and Sankur, 2004) to remove all the features but the filter membrane  
 214 background. At this point, the Hough transform allows determining both the center and the diameter of the  
 215 membrane background. The calibration factor is therefore computed as the ratio between the diameter of  
 216 the filter estimated by the Hough Transform (in pixels) and the actual diameter entered by the user (in  
 217 millimeters).



218

219 **Figure 2:** Example of automatic detection of the filter in an image. The original image A) is converted to  
 220 grayscale colorspace B) and thresholded with thresh value 5 C). In D) the contour of the membrane is  
 221 determined by the Hough Transform. E) Workflow for the automatic determination of the calibration factor.

222

## 223 2.6. Preliminary processing

224 The sample images often contain a certain amount of noise which is generally due to the presence of  
225 nanoplastics or fluorescent mineralogic fractions and can lead to a considerable overestimation in the  
226 microplastic count.

227 Mean and median morphological low pass filters have proven to be relatively ineffective in achieving  
228 noise-selective removal, and bandpass filtering in the frequency domain (Russ, 2016) has been chosen as a  
229 valid alternative. Examples of a gaussian bandpass filter on removing image noise originating from  
230 fluorescent mineralogic fraction on a microplastic filter image are shown in Figures S3 and Figure S4.

231 MUPL allows the user to enable Gaussian bandpass filter  $H$  in the following form:

$$232 H = \exp \left\{ -\frac{[d(f_x, f_y) - f_0]^2}{f_w^2} \right\}$$

233 Where  $d^2(f_x, f_y)$  are the frequencies in the  $x$  and  $y$  direction, respectively,  $f_0$  and  $f_w$  are respectively  
234 the center and the width of the bandpass filter.

235 Aiming at filtering all the features whose length is lower than  $l_{min}$  or great than  $l_{max}$ , the  
236 corresponding Gaussian bandpass filter characteristics are calculated as follows:

$$237 f_0 = \frac{1}{2} \left( \frac{1}{l_{max}} + \frac{1}{l_{min}} \right)$$
$$238 f_w = \frac{1}{l_{max}} - \frac{1}{l_{min}}$$

239  
240 After this optional removal step, the image background, mainly consisting of the glass filter, is removed by  
241 subtracting its blurred version obtained with a large radius median filter from the original image.

242

## 243 2.7. Detection and count of microplastics

244 We chose to detect and measure only fibers whose length ranges from 0.4 mm to 10 mm. The lower  
245 limit is imposed because the image resolution does not allow reliable identification of smaller

246 microplastics with the risk of including noise or other non-plastic particles in the counts. In general, to  
247 avoid errors due to poor picture resolution, we highly recommend processing pictures which a scale factor  
248 not lower than 100 pixels/mm; otherwise, the lower length detection limit should be increased.

249 Due to the presence of fibers of different materials, each of which produces a different fluorescent  
250 response when exposed to an ultraviolet (UV) lamp, each color channel requires a separate treatment. A  
251 thresholding approach on the grayscale version of the image has proven to be rather ineffective as the  
252 fibers with low fluorescent emission are lost (See Supplementary Information Figure S4). Local and  
253 adaptive thresholding techniques give inadequate results for a particle with high-intensity fluorescence  
254 that can saturate the camera detector and produce the typical halo.

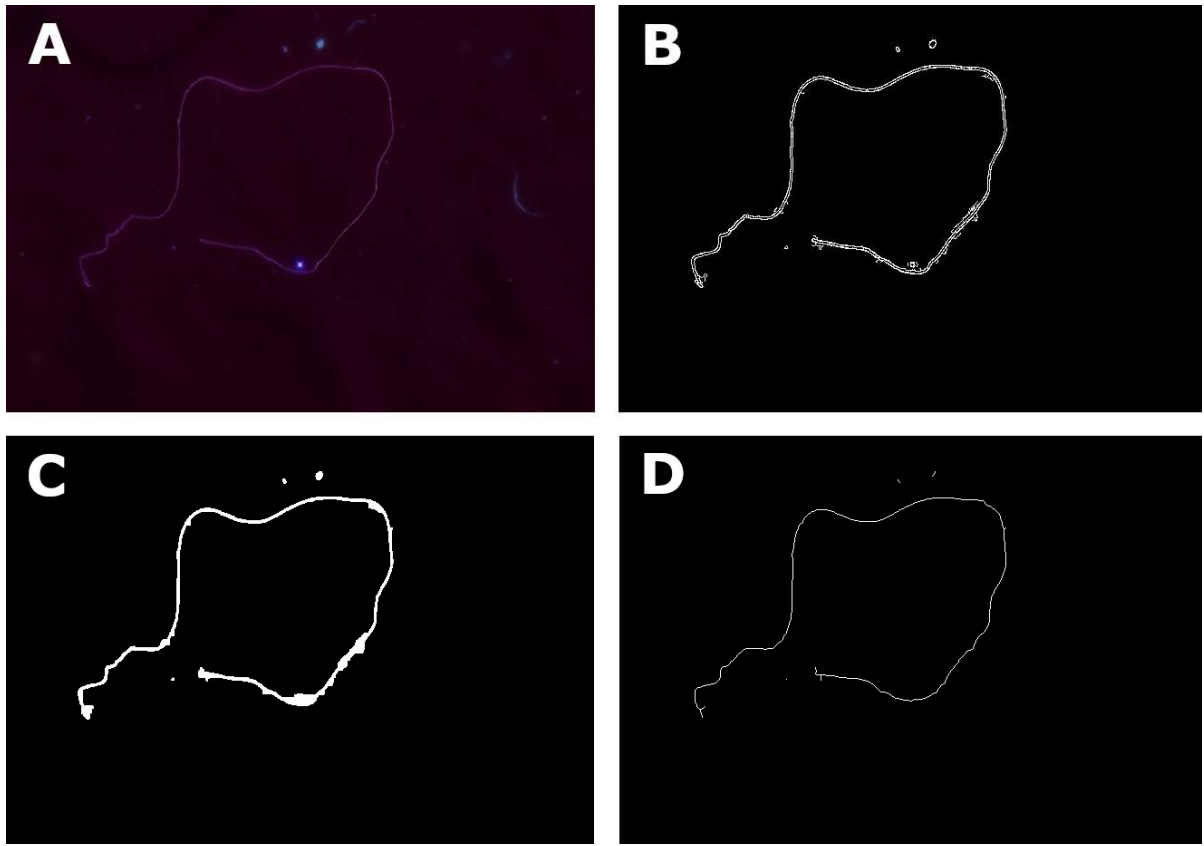
255 The workflow and results of the method we propose are presented in Figures 3 and 4. Such a method  
256 is based on the segmentation of the separate color channels. Once the image is decomposed in its RGB  
257 colorspace channels, the background for each of these is calculated through a wide radius median filter  
258 and then subtracted from the initial image. To further limit the presence of fluorescence halos, a Canny  
259 filter is also applied to the image to extract the boundaries of each fiber. The three channels are then  
260 summed together, and the image is binarized by employing a thresholding operation. Finally, a closing  
261 filter is applied to remove holes within the fiber area left by the Canny filter.

262 The skeletonization operations reduce each fiber to a 1-pixel wide binary representation whose area is  
263 equal to the fiber length. Despite that, identifying each fiber as a separate entity also requires a connected  
264 components analysis, easily obtained by the *connectedComponentsWithStats* ("OpenCV: Structural  
265 Analysis and Shape Descriptors," n.d.) OpenCV function.

266 The thickness of the fiber is computed by dividing the area (number of non-zero pixels) in the  
267 thresholded image before skeletonization within the fiber bounding box by its length. An example of size  
268 and shape statistics generated by MUPL on the Po River sample set is reported in Figure S5.

269 All the values are converted to millimeters by dividing by the scale factor and rounded to 2 decimal  
270 digits.

271



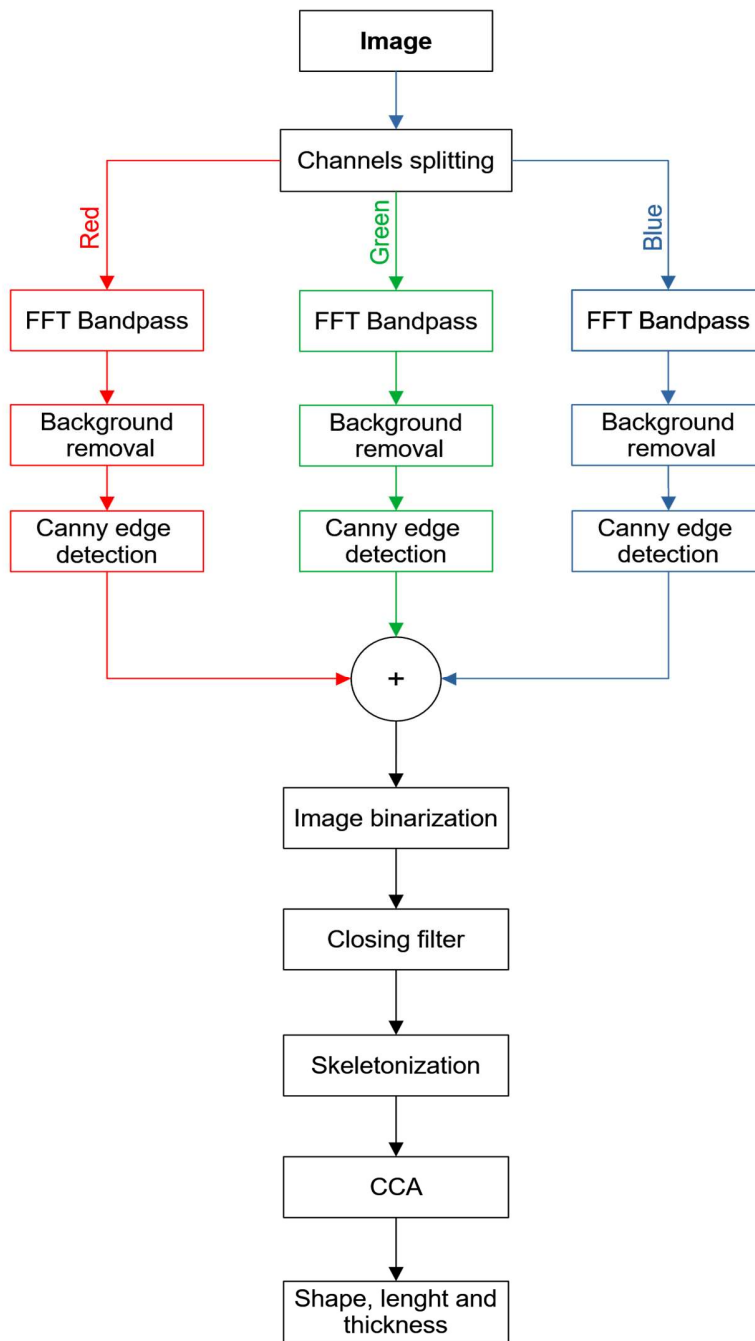
272

273 **Figure 3:** Sequence of image processing operations on a sample image. Original image of a microplastic  
274 fiber observed under UV light A). The same image after background removal and edge detection B), after  
275 a closing filter C) and after skeletonization D).

276

277

278



279 **Figure 4:** Workflow for the segmentation of UV-fluorescent microplastics on a filter.

280

281

282

283

284 **3. Results and discussions**

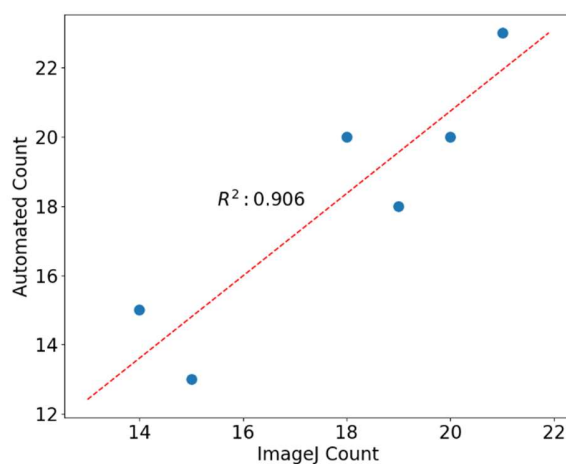
285 The first tests were carried out on the six images artificially created with an image editing software (Table  
286 1). For each dataset, the deviation is defined as the percentage difference between the counts obtained by  
287 the operator visual count and the counts returned by MUPL. The automated count results on each sample  
288 set turn out to be quite accurate, returning a deviation smaller than 13.3% on each filter and an average  
289 absolute deviation below 8% (Table 1). The correlation between the visual count and the automated MUPL  
290 is reported in the graph of Fig. 5.

291

292 Table 1. Microplastic abundance under UV light on filters created with an image editing software MUPL  
293 set parameters: Background removal filter 30, Canny lower threshold 150, Canny upper threshold 210,  
294 Close filter size 3, Close filter size iterations 1.

<b>Filter Sample</b>	<b>ImageJ Count</b>	<b>MUPL Count</b>	<b>Deviation [%]</b>
<b>PS-1</b>	21	23	9.5
<b>PS-2</b>	15	13	-13.3
<b>PS-3</b>	18	20	11.1
<b>PS-4</b>	20	20	0.0
<b>PS-5</b>	14	15	7.1
<b>PS-6</b>	19	18	-5.3
<b>Average</b>	17.8	18.2	1.5

295



296

297 **Figure 5.** Correlation of MUPL Automated Count against ImageJ Count for the sample artificially  
 298 produced with an image editing software.

299

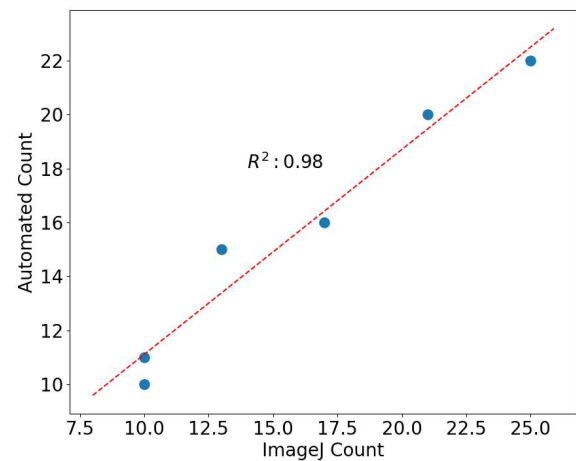
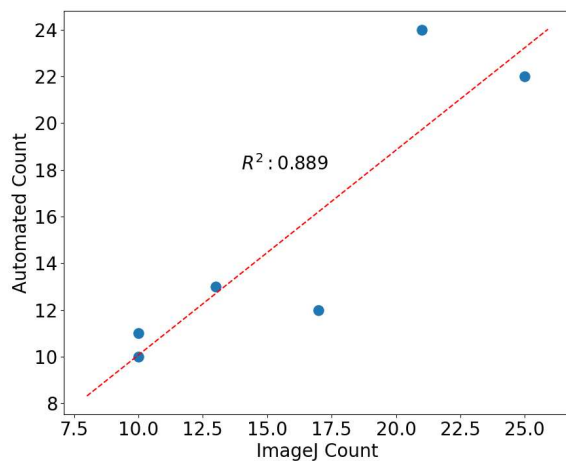
300 Microplastics were found in all sediment samples of Borgio Verezzi show cave and in all water samples  
 301 of Po River (Table 2,3). The automated count results on each sample set turn out to be quite accurate,  
 302 returning a deviation of less than 15% on each filter and an average absolute deviation below 11% (Table  
 303 2,3). An exception is the single filter BV5, whose deviation is 29.4%. The correlation between the visual  
 304 count and the automated MUPL for the samples from Borgio Verezzi show cave and Po River are  
 305 reported in the graphs of Fig. 6 and 7 respectively. In the figures, it is also reported the correlation  
 306 between the two types of counting for the Nile Red stained MPs.

307 Considering the mean value, the count error was further reduced when processing stained sample images:  
 308 from 10.9% to 8% for Borgio Verezzi samples and from 8.3% to 6.9% for Po River samples (Table 2,3).  
 309 Figures 5, 6 and 7 correlate the Automated count and ImageJ determination with regression coefficient  
 310 calculation on the different samples without and with Nile Red staining. A summary of the count deviation  
 311 obtained with MUPL for each sample is summarized in Figure 8.

312

313 Table 2. Microplastic abundance on filters of Borgio Verezzi show cave sediments [items/20 g of superficial  
 314 sediment] under UV light. MUPL set parameters: Background removal filter 15, Canny lower threshold  
 315 100, Canny upper threshold 155, Close filter size 5, Close filter size iterations 1. UV photo with Nile Red:  
 316 Background removal filter 10, Canny lower threshold 230, Canny upper threshold 230, Close filter size 3,  
 317 Close filter size iterations 1.

Filter Sample	ImageJ Count	MUPL Count	Deviation [%]	MUPL Count (Stained)	Deviation (Stained) [%]
BV-1	10	10	0.0	11	10.0
BV-2	25	22	-12.0	22	-12.0
BV-3	21	24	14.3	20	-4.8
BV-4	13	13	0.0	15	15.4
BV-5	17	12	-29.4	16	-5.9
BV-6	10	11	10.0	10	0.0
<b>Average</b>	16.0	15.3	10.9	15.7	8.0



318  
 319 **Figure 6.** Correlation of MUPL Automated Count vs ImageJ Count for the sample of sediment of Borgio  
 320 Verezzi show cave without (A) and with (B) Nile Red staining.

321

322 **Table 3.** Microplastic abundance on filters of Po River water [items/L of shallow water] under UV light.

323 MUPL set parameters: Background removal filter 30, Canny lower threshold 150, Canny upper threshold

324 210, Close filter size 3, Close filter size iterations 1. MUPL set parameters with Nile Red: Background

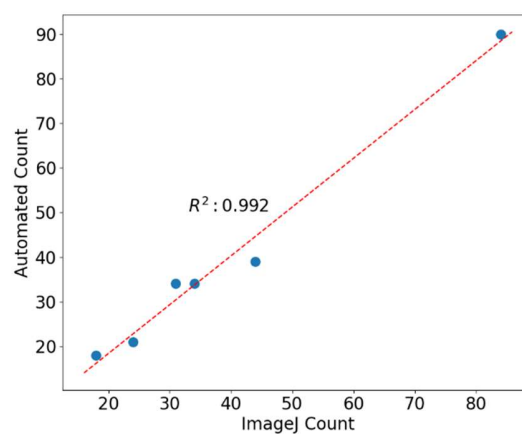
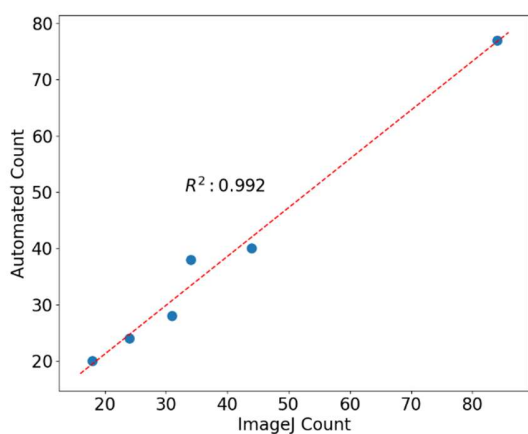
325 removal filter 15, Canny lower threshold 195, Canny upper threshold 230, Close filter size 3, Close filter

326 size iterations 1.

327

**MUPL Count Deviation**

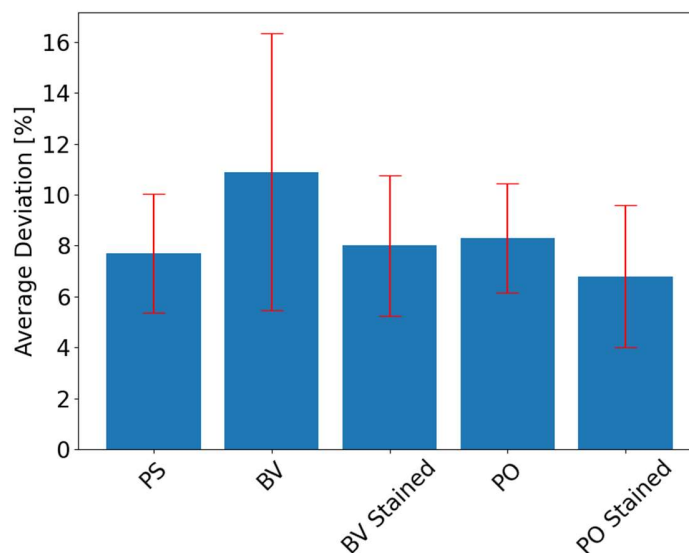
Filter	ImageJ Count	MUPL Count	Deviation [%]	(Stained)	(Stained) [%]
PO-1	84	77	8.3	90	7.1
PO-2	31	28	9.7	34	9.7
PO-3	24	24	0.0	21	12.5
PO-4	18	20	11.1	18	0.0
PO-5	44	40	9.1	39	11.4
PO-6	34	38	11.8	34	0.0
<b>Average</b>	39.2	37.8	8.3	39.3	6.8



328

329 **Figure 7.** Correlation of MUPL Automated Count vs ImageJ Count for the sample of Po River water  
330 without (A) and with (B) Nile Red staining.

331 The use of Nile Red dye has not made substantial improvements in the MPs coloring; however, it has  
332 improved and uniformed the filter background allowing a better distinction of the plastic material on the  
333 filters. Moreover, the results indicate that staining with Nile Red dye reduced the average deviation on both  
334 Borgio Verezzi and Po River samples. This can be related to the fact that the majority of MPs found on our  
335 filters were synthetic fibers, often made of polyester materials, which are hard to stain. However, under UV  
336 exposure, these fibers presented a strong fluorescence under UV light due to the presence of FWAs, making  
337 them easy to identify.



338  
339 **Figure 8.** Summary of MUPL count deviations for each sample. The blue bars represent the average of  
340 absolute deviation; the red bar represents the range of deviation that comprises all the processed filter  
341 images.

342  
343 The MP abundance value found in the first six Borgio Verezzi show cave samples examined (about 500-  
344 1250 items/kg) is very small compared to those found in Bossea show cave sediments (2500-8700 items/kg

345 along the tourist path and 1600 items/kg in the speleological area) (Balestra and Bellopede, 2022).  
346 However, the Bossea show cave values have been calculated considering fluorescent and not-fluorescent  
347 MPs, and a 12.3% of the total MPs in this cave sediments were not fluorescent. Therefore, it is reasonable  
348 to consider for Borgio Verezzi cave at least 10% more MPs than the value obtained with the counting of  
349 fluorescent particles.

350 The MP abundance value found in the Po River water samples (about 18-84 items/L) are similar to those  
351 found in the Gallatin River, USA (0.001-67.5 items/L) (Barrows et al., 2018), and relatively high compared  
352 to those found in the Yangtze River Estuary water, China (0,5-10,2 items/L) (Zhao et al., 2014) or  
353 Amsterdam canal water, Netherland (4.8-18.7 items/L) (Leslie et al., 2017). The large amount of MPs found  
354 in the Po River could be linked to the different methods used or to the sampling place on shore, where the  
355 currents are less noticeable and, therefore, an accumulation may occur.

356

#### 357 **4. CONCLUSIONS**

358 The importance of image analysis for the recognition of microplastics is linked to the rapidity of the process  
359 and could lead to the detection of microplastics directly in situ. Existing detection methodologies often  
360 require a long processing time and specific dedicated equipment. The complexity of the real samples  
361 highlighted the necessity to remove organic matter and take photos of high quality for better image analysis.

362 The new software proposed in this work, MicroplasticLab (MUPL), uses an approach for the automatic  
363 segmentation of the image and solves the halo problem that can be found around the fluorescent particles.

364 This fact avoids identification errors and misattribution of microplastic shapes. This software can be used  
365 on filters photographed under UV light with and without using a staining dye. The results obtained with  
366 this software on images of real samples gave an average deviation on a single filter of less than 15.4%.  
367 If we consider the whole set of filters within the same sample set, the deviation is, on the stained samples,  
368 always lower than 10%.

369 For these reasons, MicroplasticLab can undoubtedly provide useful and reliable support for quantifying  
370 microplastic pollution in different environments and matrices, paving the way for a new semiautomated

371 approach. Moreover, its capability of producing statistical information on the size and shape of the  
372 detected particles can help detecting their sources and assist in establishing removal strategies.

373 The proposed process can also filter the presence of fluorescent mineralogic particles by a Fast Fourier  
374 Transform (FFT) filter which might affect the overall count in some cases. To improve microplastic  
375 recognition for these cases, further investigation should explore the possibility of using digestion techniques  
376 that combine biological and inorganic fraction removal.

377 MicroplasticLab is conceived as a tool to help the environmental researcher to identify and estimate the  
378 contamination from microplastics in different environments. At the same time, identification of the type of  
379 plastic is of great importance for a complete analysis. In this direction, an improvement would be to couple  
380 the MUPL technique with some algorithm for identifying the microplastics based on a particle-by-particle  
381 spectroscopic analysis directed to microplastics automatically identified by the software. In this way, with  
382 a quick analysis of a filter membrane, the researcher could count, measure, and identify the nature of MP  
383 particles.

384

#### 385 **ASSOCIATED CONTENT**

386 -SupportingInfo.pdf (PDF): contains additional images of microplastic samples processed in Fiji showing  
387 results of Automatic thresholding techniques. It also includes an example of an FFT bandpass filter on a  
388 sample image and examples of size/shape statistics generated by MUPL.

389 -MUPL\_sourcecode.zip: contains the source code of MUPL Python script. The main user interface can be  
390 run, upon installation of required dependencies, by typing in the system terminal the following command

391 *streamlit run Main.py*

392 -MUPLTutorial.pdf: quick tutorial to show how to process microplastic on membrane filter images on  
393 MUPL.

394

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404

#### 405 **ABBREVIATIONS**

406 MP microplastic, MPs microplastics, MUPL MicroplasticLab, UV ultraviolet

407

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