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Effects of bed slope on the flow field of vertical slot fishways

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Abstract

Vertical Slot Fishways (VSF) are the most efficient and least selective typology of technical fish passage, due to their ability to remain effective even when significant upstream and/or downstream water level fluctuations occur. Fishway construction costs can be reduced by increasing its bed slope, but this affects the flow field inside the pools, with higher head drops between the basins, as well as turbulence levels and flow velocities, which may affect fish passage. In light of this, a vertical slot fishway (VSF) was investigated by 3D numerical simulations to identify the possible effects of the bed slope (using values from 1.67% to 10%) on the flow field, and subsequent implications for fish passage. A particular focus was devoted to cyprining species, but results can be extended to other species of similar swimming abilities and therefore, be applicable to multispecies rivers. Flow velocity and turbulence values like turbulent kinetic energy and Reynolds stresses were analyzed from a fish 12 passage perspective in relation to threshold values derived from previous studies. 13 Pool areas where turbulence values are compatible with fish ability and behavior were quantified. Maps of the location of fish friendly zones in the VSF pools were

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produced and can constitute a reference for practical applications in fishway design. The flow field generated with bed slopes lower than 6.67% is more compatible with fish swimming capabilities, since it exhibits a predominantly 2D behavior and more suitable hydraulic conditions whereas, at higher slopes, turbulence levels in the pools increase.

Keywords: bed slope, ecohydraulics, fish passage, fishway, vertical slot fishway

1. Introduction

The interruption of longitudinal connectivity of a natural river by anthropogenic 21 obstructions is perceived as one of the main causes in the decline of freshwater ichthy-22 ofauna (Calles and Greenberg, 2009). With the aim of restoring to an acceptable level the longitudinal connectivity of a river, the construction of fishways represents 24 the best practice where obstacle removal is not feasible. 25 The flow field and turbulence level in a fishway affect the capability of fish to 26 successfully migrate through it (Silva et al., 2011 and 2015). Shear stresses and hy-27 drodynamic resistance generated by flowing water and turbulence on fish body make 28 migration an energetically demanding process. Therefore, the design of a fishway 29 has to take into account the biological characteristics of the migrating fish, i.e their swimming capability, size and fish reaction to external stimuli like turbulence, flow 31 acceleration and velocity (Clay, 1995; Rodriguez et al., 2006; Katopodis and Gervais, 2016; Katopodis and Williams, 2012; DWA, 2014). In Clay (1995), Katopodis and 33

Gervais (2016), Katopodis and Williams (2012), Plaut (2012), Puertas et al. (2012),

35 Silva et al. (2011 and 2015), Tuhtan et al. (2018), Tritico and Cotel (2010), Quar-

anta et al. (2017) the interaction between fish and flow field in fish passes has been

investigated and discussed.

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Pool-and-weir fishways are the most common type of technical fish passage device

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(Hatry et al., 2016; Santos et al., 2016), consisting of a channel with a sloping bed
   divided into a series of pools by cross-walls at regular intervals. The most efficient
   and least selective typology of pool-and-weir fish passage is the Vertical slot fishway
41
   -VSF-, consisting of a sloping rectangular channel divided into a number of pools by
   vertical baffles. Water flows through the vertical slot between the baffles, from one
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   pool to the downstream one. Vertical slot fishways have the advantage of allowing
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   fish to move from one pool to the next without having to jump, being able to swim
   at any desired depth (Cordoba et al., 2018). Under uniform flow conditions, the
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   water level difference \Delta h between two adjacent pools depends on the slope of the
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   fishway i and on the length L of the pool, i.e. \Delta h = iL. VSFs remain effective
   even when upstream and/or downstream water level fluctuations occur (Katopodis,
   1992). VSFs are recommended especially in rivers where several fish species with
   different swimming capabilities are present (FAO, 2002; Stuart and Berghuis, 2002;
51
   DWA, 2014).
52
      The most seminal work on VSF design was presented in Rajaratnam et al. (1992),
53
   where eighteen different designs of VSF were physically tested. Among the inves-
   tigated designs, Design 1 -D1- is the most common and represents the standard
55
   reference typically used in real applications. The geometry of D1 suggested in Ra-
56
   jaratnam et al. (1992) has a slot orientation \alpha = 45^{\circ} (i.e. the angle between the
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   width of the slot and the longitudinal direction). Taking the slot width b_0 as refer-
58
   ence, suggested pool dimensions are L = 10b_0 and B = 8b_0, where L is the length
59
   and B is the width of the pool (Fig.1).
60
      In addition to b_0, B and L, another important parameter in the design of a
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   VSF is the bed slope i. The higher the slope, the lower the costs, since fewer
62
   pools are required for a certain head difference. However, for higher bed slopes,
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   the turbulence and flow velocities can increase to levels that impair fish passage
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efficiency. Furthermore, the topology of the flow field is affected by the slope: bed slope values higher than 10% are commonly considered not fish friendly (Chorda et al., 2010). The bed slope and the pool length determine the head drop Δh between adjacent pools, which is a reference parameter for fishway design, being related to the maximum flow velocity through the slots. Different Δh values are recommended for different biocoenotic regions along the river, according to the swimming capabilities of the target species (DWA, 2014).

1.1. Range of VSF bed slopes for practical applications

In general, to ensure good ecological efficiency, the bed slope should guarantee a 2D flow pattern, because high vertical velocity components are likely to disturb fish performance (Wang et al., 2010). If a jet impacts the side-wall of a pool (that generally happens at slopes higher than 10% when the standard dimensions are used, (Rajaratnam et al., (1992)) a swirl is created with a horizontal axis that generates high-velocity vertical components. The formation of recirculation zones, that are too large and that drive the jet in the direction of the baffle, has to be avoided (Wang et al., 2010). Hence 5% slope is considered appropriate for multispecies rivers to limit species selectivity and to ensure a predominant 2D flow field (Marriner et al., 2016; Quaranta et al., 2017), while 10% is a value used to limit fishway construction costs, especially when passage of larger Salmonids or other species of similar swimming ability and behaviour, is expected.

However, there is no clear ecological assessment of VSF for different slopes in the literature. The general question is whether a given bed slope configuration can determine hydrodynamic conditions affecting fish pass efficiency. Field experiments on the ecological efficiency of VSF found in the literature (Laine at al., 1998; Romao et al., 2017; Thiem et al., 2013; Stuart and Cooper, 1999; Duarte et al., 2012; Silva et al., 2015) show that for bed slopes lower than 5%, fish passage efficiency is generally higher than 30% and in certain cases higher than 60% (Stuart and Cooper, 1999; Duarte et al., 2012; Thiem et al., 2013; Silva et al., 2015), while it falls below 30% at higher slopes (Laine at al., 1998; Quaresma et al., 2017; Romao et al., 2017; Romao et al., 2018). Based on experiments in non uniform flow conditions, fish were found making broader use of the fishway pool in scenarios with lower water drops, which are highly correlated with regions of overall lower turbulence and velocity magnitude (Fuentez-Perez et al., 2018). However, geometric and hydraulic configurations of these field experiments significantly differ from each other, not allowing a clear assessment of fish behavior in relation to bed slope. Furthermore, each study tested only one bed slope configuration, making it difficult to generalize results.

On the other hand, experimental and numerical studies on the hydraulic of VSFs at different slopes generally involved only a few slopes, typically 5%, 10% and 15%, with no results for intermediate slopes. In addition, areas compatible with fish rest, based on threshold values available in the literature, were not highlighted (Liu et al., 2006; Tarrade et al., 2008; Chorda et al., 2010; Wang et al., 2010).

In Chorda et al. (2010), Tarrade et al. (2008) and Wang et al. (2010), bed slopes 106 of 5%, 10% and 15% were investigated. At 5% slope, a smaller downwelling jet and 107 a longer jet core occurred, while the turbulence in the lower part of the pool and in 108 the main recirculation zone was less pronounced. Furthermore, at 15\% slope, low 109 velocity areas were substantially limited, thus excluding this steep setup for practical 110 applications. Threshold values distribution inside the pool was not discussed, and 111 3D turbulence effects were not considered. Considering the optimal pool dimensions 112 $(L = 10b_0 \text{ and } B = 8b_0 \text{ according to Rajaratnam et al., 1992}), \text{ at } 5\% \text{ slope the flow}$ 113 field comprised of a well identified jet and two large recirculating areas on its sides, 114 while at 10% slope the left eddy split into two smaller ones, as also found in Quaranta et al. (2018), and at 15% slope the jet impacted on the left wall, completely changing
the flow field by making it more complex. Liu et al. (2006) confirmed such result on
design 18-D18- presented in Rajaratnam et al. (1992), showing that at 10% slope
the flow field substantially changed, and the water jet impacted against the wall
creating conditions not suitable for fish.

Bed slopes lower than 5%, have been investigated by Li et al. (2017), who focused on water depths and 1D water profiles, instead of the flow field which may be more important for fish. Furthermore, the benefit gained at slopes below 5% might not justify the increase in construction costs.

Therefore, with limited hydraulic results from the literature, along with fish tests 125 on only a few slopes and geometric configurations, it is difficult to provide a clear 126 assessment of hydrodynamic variations in relation to the bed slope. In order to 127 improve the knowledge on the effect of bed slope on the flow field and on its potential 128 implications on fish passage efficiency, the present study will investigate the flow field 129 of the standard VSF design D1 (according to Rajaratnam et al. 1992) at different 130 bed slopes, testing six bed slopes between 1.67% and 10%. Higher slopes will not 131 be considered due to their limited passage efficiency, as highlighted in all literature 132 results. The distribution of turbulence parameters inside the pool will be analyzed, 133 in order to determine the pool zones considered suitable for fish passage or rest, 134 according to threshold values derived by previous laboratory experiments (described 135 in section 2.1). In order to provide results directly applicable to VSFs design, the pool 136 dimensions and the tested slopes correspond to head drop values between adjacent 137 pools ranging from 5 to 30 cm, covering the typical range of Δh used in practical 138 applications (e.g. DWA, 2014, Larinier, 2002).

2. Materials and Methods

Although turbulence can be numerically resolved in its different scales using di-141 rect numerical simulations (DNS), this approach is computationally too demanding. 142 Therefore, RANS and LES methods are the most reasonable alternatives. The ma-143 jority of studies have implemented RANS methods as a numerical technique for the 3D modeling of VSF, since these have shown to be capable of providing a compromise 145 between accuracy and computational cost (Fuentes-Perez et al., 2018). Therefore, 146 in this study a Computational Fluid Dynamic (CFD) RANS model was used. The 147 CFD model was based on the commercial software Ansys Fluent, and it has been 148 validated against experimental data (head-discharge and flow field) in Quaranta et al. (2017). Three momentum equations (one equation for each cartesian coordinate) 150 and the continuity equation were solved. 151 The VOF (Volume of Fluid) method was used to determine the free surface 152 position (Quaranta et al., 2017). The Reynolds shear stresses (RS) in the momentum 153

$$\tau_{i,j} = -\rho \overline{v_i' v_j'} = \mu_t \left(\frac{\partial V_i}{\partial x_j} + \frac{\partial V_j}{\partial x_i} \right) - \frac{2}{3} \rho k \delta_{ij}$$
 (1)

where μ_t is the turbulent dynamic viscosity, ρ is water density, k is the turbulent kinetic energy and δ_{ij} is the Kronecker delta (Ansys Manual, 2018). The fluctuating component v_i' of velocity in direction x_i is the difference between the instantaneous value of velocity and the average velocity V_i . The $k-\epsilon$ Realizable model was used to model the turbulent viscosity since it

equations $\tau_{i,j}$ were modeled by means of the turbulent dynamic viscosity μ_t :

The $k - \epsilon$ Realizable model was used to model the turbulent viscosity since it performs better than the standard $k - \epsilon$ model for recirculating flows (Ansys Fluent manual, 2018). The turbulent viscosity is expressed as a function of turbulent kinetic energy k and turbulent dissipation ϵ .

$$\mu_t = \rho C_\mu \frac{k^2}{\epsilon} \tag{2}$$

where $C_{\mu} = 0.09$.

Turbulent kinetic energy TKE is defined as $k = 1/2[u_i'^2 + u_j'^2 + u_w'^2]$. u_i' , u_j' , $u_w'^i$ are the fluctuating velocities, i.e. the differences between the instantaneous flow velocities and the mean flow velocities along the corresponding direction i, j and w. In the present case, i = x (longitudinal direction), j = y (transversal direction) and w = z (vertical direction).

The pressure-velocity coupling was solved by PISO scheme. Spatial discretizations were realized by the following schemes: PRESTO for pressure and QUICK for
momentum and turbulent kinetic energy, in alignment with Barton et al. (2008).
The Curvature correction was added to sensitize the model to streamline curvatures.
The numerical simulations were run in stationary and uniform conditions (same water level in the pools).

The geometric domain was made of five pools, plus a headrace and a tailrace 12 175 m long. The geometric dimensions of each pool were the standard ones, $L=10b_0$ 176 long and $B = 8b_0$ wide, where $b_0 = 0.3$ m is the slot width. The average pool water 177 level was $y_0 = 2$ m under the uniform scenario, and six different bed slopes were 178 investigated. The flow rate was imposed at the inlet, based on y_0 and geometry 179 (Rajaratnam et al, 1992), while the water depths at the inlet and at the outlet were 180 set to ensure a water depth of $y_0 = 2$ m at the center of the pool. This method was 181 used and validated in Quaranta et al. (2017). As initial condition, all the volume 182 was filled with air, and only at the inlet a water surface was imposed. Table 1 shows, 183 for each slope value, the resulting head difference Δh between two adjacent pools 184 and the flow rate Q for $y_0 = 2$ m.

A tetrahedral mesh was generated, with cell dimensions ranging between 0.025 m and 0.05 m, that is considered a good mesh to simulate hydraulic structures affecting fish behavior. Such mesh size is comparable with mesh dimensions typically used in literature (Khan, 2006; Marriner et al., 2014; Quaranta et al., 2017), and hydraulic phenomena (like eddies) are of one order of magnitude larger than mesh dimensions.

2.1. Examined variables and threshold values

Results were discussed in relation to the central pool, which is generally used as 192 a representative reference in CFD fishways modeling (Khan, 2006; Heimerl et al., 193 2008; Quaranta et al., 2017). The flow field was examined on a deeper plane H_b 194 (bottom plane) located at $0.33y_0$ (representing the flow field for bottom oriented fish 195 species), and on a plane H_t (top plane) located at $0.67y_0$ (flow field faced by fish 196 swimming in the upper portion of the water column). This approach was similar to 197 Silva et al. (2012), and was useful to compare results with those found in Quaranta et al. (2017) for Design 16, which is the simplified version of the design investigated 199 here (D1). 200

The examined turbulent variables were the turbulent kinetic energy TKE, the power dissipation D_{ϵ} and the Reynolds shear stresses RS (more specifically the tangential Reynolds stress $\tau_{x,y}$). Furthermore, the flow topology at different slopes was also analyzed along a vertical plane passing through the center of the slots, in order to better evaluate up- and downwelling phenomena.

Typical threshold velocity values recommended in fish resting zones are 0.2-0.4 m/s; this range is recommended for Cyprinids to rest before a subsequent upstream movement through higher velocity areas (Silva et al., 2012 and 2015, where fish 15-35 cm long were tested). Since Marriner et al. (2016) found that flow velocities must be kept under 0.30 m/s in 30% to 50% of the pool's volume, in this study the upper

²¹¹ reference velocity value was taken as 0.3 m/s.

For TKE, a large portion of the pool should stay below 0.05 m²/s², since higher values might affect fish passage (Marriner et al., 2016; Quaranta et al., 2017). In Romao et al. (2017), average TKE values occurring during Cyprinid passage (Iberian barbel *Luciobarbus bocagei* and Southern Iberian chub *Squalius pyrenaicus*) through a VSF ranged between 0.05 m²/s² and 0.1 m²/s². Therefore, preferable TKE values used in this study stay below 0.05 m²/s², while 0.1 m²/s² was considered a maximum acceptable limit.

With regards to RS, on the horizontal plane Iberian barbel occupied positions with absolute RS between $20 - 60 \text{ N/m}^2$ (Silva et al., 2011), so that 60 N/m^2 can be considered the upper reference threshold (in Romao et al., 2017, average RS were estimated to be about 30 N/m^2 in a regular pool). Note that the upper limit 60 N/m^2 may not be enough to cause injuries or mortalities, which typically occur at much higher levels (> 700 N/m^2) (Silva et al., 2011).

Finally, the power dissipation inside the pool, defined as $D_{\epsilon} = \frac{1}{V_p} \int_{V_p} \rho \epsilon dV_p$, where 225 dV_p is the infinitesimal pool wet volume and ϵ is the dissipation of turbulence coming from the turbulent model, was evaluated. Usually, for the sake of simplicity in the 227 design of technical fishways, the global volumetric dissipated power D_V is used as a 228 reference parameter, calculated as $D_V = \frac{P}{V_p}$ where $P = \rho g Q \delta h$ (ρ is water density, g229 is gravity, Q is the flow rate and δh is the head difference). In general, $D_V > D_{\epsilon}$, since 230 D_V includes all power losses and friction losses, not only the turbulent ones computed 231 with D_{ϵ} . However, D_{ϵ} allows the determination of the dissipation distribution inside 232 the pool, while D_V is just a global pool parameter (Chorda et al., 2010). Analyzing 233 D_{ϵ} , the pool area was subdivided according to the following threshold values: 1) 234 D_{ϵ} = 200 W/m³: highly turbulent areas not suitable for fish resting, where generally 235 fish use burst speed to pass through slots (Liu, 2004); 2) 150-200 W/m^3 : acceptable for larger salmonids; 3) 100-150 W/m³ acceptable for most cyprinids species; 4) \leq 100 W/m³ conservative upper threshold for fish species with weaker swimming ability (ICPDR, 2013; Larinier, 2002).

Flow velocity and turbulent values were discussed by considering absolute local values (like maximum values), and averaged values (\overline{V} , \overline{RS} and \overline{TKE}). Velocity and turbulence results were quantitatively described distinguishing between jet and low-velocity areas. Finally, based on threshold values reported within the current section 2.1, pool areas considered fish friendly were quantified and their topology within the VSF pool is presented.

3. Results and discussion

Figures 2-3 show the flow field in the pool by means of flow velocity vectors on 247 the planes H_b and H_t . Along the plane H_b , a well visible jet and low-velocity areas 248 on its sides are present. It can be noticed that the left eddy is progressively shifted 249 downstream; at i=6.67%, it disappears reappearing again at i=10% splitted into two 250 smaller ones, in agreement with Tarrade et al. (2008). As reported in Romao et al., 251 (2018), turbulent flow fields with vortices of various sizes represents an additional 252 difficulty for fish passage, especially for small individuals with limited swimming 253 ability; therefore, VSFs with 10% slope are not recommended. The absence of the 254 vortex at i=6.67% and 8.33% is due to the increased vertical component of velocities, i.e. upwelling and downwelling phenomena. This implies a higher level of turbulence 256 in the vertical plane. Instead, the right eddy tends to be quite stable as the bed 257 slope changes, except at i=10% where it approaches a more circular shape. Looking 258 at the plane H_t in Fig.3, the left eddy is initially circular and located upstream. At 259 i=5% it becomes elliptical and moves downstream, splitting into two smaller ones at i=6.67-8.33%. In all cases, average jet flow velocities are generally smaller than

the maximum theoretical ones V_m , while locally maximum effective values could be 262 slightly higher than V_m . Furthermore, as also shown in Wang et al. (2010), there is 263 an increase in flow velocity near the left wall of the pool and in the proximity of the 264 main transversal baffle, due to the rotation of the big vortex on the left of the pool. 265 When looking at a longitudinal vertical plane passing through the center of the 266 slot (Fig.4), it can be seen that flow velocities increase from the center of the pool 267 towards the slot downstream; this is because, in the downstream portion of the pool, the vertical plane intersects the main jet. Instead, in the upstream portion of the 269 pool, the resting zone on the right side of the jet is shown, where the horizontal 270 axis eddy generates flow velocities directed upstream as confirmed by Tarrade et 271 al. (2008). This may help the upstream movements of fish that swim near the free 272 surface. This hydraulic configuration does not occur at i = 1.67% and i = 5%, where 273 instead upstream pointed flow velocities appear in the lower portion of the pool. 274 Indeed, the eddy on the right is more elongated, and the vertical plane intersects it 275 in its internal part (flow velocities pointed downstream), while at the other slopes 276 it is intersected in its external part, where flow velocities are directed upstream. 277 Another interesting output is related to the zone where flow velocities start pointing 278 downstream. At i = 1.67% and i = 5% the velocity increase starts from the upper 279 portion of the pool, while at the other slopes from the bottom portion, and this is 280 coherent with the rotation of the horizontal axis eddy. Therefore, at each slope and 281 corresponding head difference, vertical flow velocities occur, i.e. up- and downwelling 282 phenomena. The higher the slope, the higher the intensity of the vertical velocities, 283 ranging from $0.05 V_m$ to $0.25 V_m$, where V_m is the maximum flow velocity in the slot. 284 The water jet is responsible for the flow rate transport, and it has to be sensed 285 readily by fish which will use their burst speed to move upstream along or through 286 the jet length. Mean jet velocity and maximum flow velocities increase with the slope (Tab. 2). On the bottom plane, velocity values are generally higher, because the jet is more straight between the slots and less affected by the free surface. As the bed slope increases, maximum flow velocities pass from $\simeq 1$ m/s to 2.6 m/s; this is an expected behavior, since as the slope increases also the flow rate increases, and thus the flow velocity. Instead, average jet values range between 0.71 m/s to 1.76 m/s from i = 1.67% to i = 10%, which is a smaller range than that found for the maximum velocities, where the variation range of the mean velocity can be calculated as $\frac{\overline{V_{10\%}} - \overline{V_{1.67\%}}}{\overline{V_{1.67\%}}}$.

Same analogies can be found for TKE and RS, whose variation ranges are wider when considering maximum values (Tab. 2). TKE and RS at 10% slope are around 7 times compared to those at 1.67% slope when considering mean values, and approximately 10 times when considering maximum values. Furthermore, maximum and average values of turbulence and velocity change substantially from H_b to H_t (from bottom to top) as the bed slope increases, due to the highly 3D character of flow behavior and due to the flow rate increase.

In contrast, flow behavior in the low-velocity areas (Tab. 3) is more quiet, and 303 average values change from H_b to H_t only at the highest slope, corresponding to 304 i=10%. Maximum velocities in the low-velocity areas occur in the boundaries with 305 the jet emanating from the slot. Variation ranges for the average values of TKE and 306 RS are again around 7, and less than 10 times when considering maximum values, 307 because in the low velocity areas flow behavior is less turbulent, and, therefore, the 308 slope may have a lesser influence on turbulence in the low velocity areas with respect 309 to the jet. 310

Results related to the extension of low velocity areas in the pool are reported in Tab. 4, showing the area percentage where effective values of flow velocity, TKE and RS are lower than threshold values (see section 2.1). In Tab. 4 the average values of

velocity, TKE and RS inside the pool are also reported with reference to planes H_b and H_t .

Area percentages below threshold values decrease with bed slope increase, due 316 to the increase in turbulence. In particular, a substantial decrease of low velocity 317 areas occurs passing from i=1.67% to i=3.33% (see Tab.4). No substantial 318 difference between the two planes $(H_b \text{ and } H_t)$ can be noticed. Fish friendly areas, 319 i.e. areas with values below the threshold ones, are more developed when considering RS instead of TKE, showing that the threshold value of TKE= $0.05~\mathrm{m^2~s^{-2}}$ is more 321 conservative than RS=60 N m⁻². Nevertheless, fish friendly TKE areas are generally 322 extended by about 30% of the pool, according to recommendations suggested in 323 Marriner et al. (2016). 324

Areas with high TKE values are confined in the jet at low bed slopes (Fig.5), 325 while at higher slopes, these start appearing downstream, because the water flow 326 impacts on the downstream wall, and then spreads upstream. This is in agreement 327 with Wang et al. (2010) and Liu et al. (2006). Instead, RS values higher than 328 $60~\mathrm{Nm^{-2}}$ are restricted only inside the main jet. Therefore, it is expected that fish 329 resting would occur in the upstream part of the pool, where turbulence is lower, as 330 confirmed in Laine et al. (1998), where it was found that fish gathered behind the 331 baffles attempting to swim through the slot. 332

With regard to the power dissipation, in Tab.4 D_V is compared with D_{ϵ} , as suggested in Chorda et al. (2010). The maximum difference in percentage is 30% at i=5%, comparable with the values found in Chorda et al. (2010). The local power dissipation $\rho\epsilon$ along the plane is illustrated in Fig.7. The highest dissipation values occur near the slot and along the jet. Such distribution is in agreement with the RS distribution, because, in turbulent regimes, RS are those factors that generate power dissipation. The distribution of D_{ϵ} is also in agreement with results described

in Chorda et al. (2010).

Looking at Figs.5-6, it can be seen that areas where flow velocity and turbulence values are lower than the maximum threshold ones are restricted to the water jet for bed slopes smaller than 5% (included). This means that low velocity areas are well developed, and they are suitable for fish to rest up to the 5% slope. The bed slope of 6.67% may still be considered fish friendly, although TKE values are not below threshold values.

Several hydraulic parameters used in this study were derived from research on 347 a few Cyprinid species, especially Iberial barbel and chub (Silva et al., 2011; Ro-348 mao et al., 2017). It is worthwhile to note that several groups of species display 349 similarity in swimming performance (Katopodis and Gervais, 2016). For example, 350 Sanz-Ronda et al. (2016), reported that two Cyprinids (barbel and nase) ascended 351 Moreover, the meta-analysis on swimming performance by the vertical slot easily. 352 Katopodis and Gervais (2016) grouped cyprinids and salmonids, indicating that fish 353 of similar body length from these large groups of species have similar fish speeds. 354 Furthermore, results from a recent field study on a vertical slot fishway, demon-355 strated that the Iberian barbel and another Cyprinid, the northern straight-mouth 356 nase (Pseudochondrostoma duriense), performed similarly to a Salmonind, the brown 357 trout (Salmo trutta), which were of similar size (Sanz-Ronda et al., 2016). These 358 findings allow recommendations on VSF bed slope from this study to apply to a 359 greater number of species.

4. Conclusions

The general question addressed by this study was whether a given slope configuration may allow more fish to pass; this is a complex matter, involving hydraulics and fish behavior, since the bed slope can significantly affect flow characteristics. The limited field experiments in the recent scientific literature make it difficult to relate ecological performances of VSFs with the slope. Meanwhile, there is a lack of a clear and comprehensive flow field assessment of VSFs at different slopes since existing studies have only tested a maximum of three slopes.

Therefore, in this study the effects of bed slope on the flow field of a standard VSF type were analyzed by 3D numerical simulations, testing six bed slope values from 1.67% to 10%, corresponding to head drop values between pools commonly used in fishway design (from 5 to 30 cm). Comparison with results from existing literature indicate good agreement, validate simulated parameters and offer greater generalizations. The flow field was discussed analyzing flow velocities and turbulent variables as TKE, RS and power dissipation.

The velocity field was characterized by a main water jet with recirculating areas on the sides of the pools. These areas changed with the bed slope, both in size and flow behavior: indeed, at 6.67% and 8.33% the vortex on the left split into two smaller ones, and due to their dimensions more comparable with fish size, they could be perceived as obstacles for fish passage (Silva et al., 2012).

Low velocity areas in the pools, that are important for fish rest and energy recovery, decreased with the bed slope increase. Areas where flow velocity and turbulent values are higher than the maximum threshold ones are restricted to the water jet for bed slopes smaller that 5% (included). With the exception of TKE, the 6.67% $(\Delta H = 20 \text{ cm})$ bed slope may be considered fish friendly. Higher slopes are not recommended, because turbulence may form a barrier for migrating fish.

Therefore, the slope of 6.67% ($\Delta H = 20$ cm) can be considered the upper limit in the design of fishways except for larger salmonids or species of similar swimming abilities and behavior. The 6.67% slope may be reasonable only when there is a need to reduce construction costs related to a 5% slope. Milder slopes would result in an

increase in fish passage construction costs, whilst no significant improvement in the ecological efficiency would occur, and may be recommended only when passage has to be provided to species with very weak swimming abilities. It is also essential to guarantee a maximum flow velocity lower than the burst speed of fish.

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Table 1. Summary of investigated conditions: VSF bed slope i, head difference between two pools Δh and flow rate Q.

i %	$\Delta h(m)$	$Q (m^3/s)$
1.67	0.05	0.479
3.33	0.10	0.677
5	0.15	0.829
6.67	0.20	0.958
8.33	0.25	1.071
10	0.30	1.173

Table 2. Average and maximum values of velocity, TKE and Reynolds stresses of the jet along the planes H_b and H_t .

$\frac{i}{\%}$	Δh	Plane	\overline{V} m/s	V_{max} m/s	$\frac{\overline{TKE}}{\text{m}^2/\text{s}^2}$	TKE_{max} m^2/s^2	\overline{RS} N/m ²	RS_{max} N/m ²
1.67	5	H_b	0.730	0.920	0.050	0.080	11.210	41.370
3.33	10	H_t H_b	0.710 0.944	0.930	0.048 0.110	0.075 0.162	9.980 23.380	41.030 100.560
5	15	H_t H_b	0.936 1.143	1.301 1.649	0.091 0.138	0.162 0.263	18.809 38.617	104.786 259.040
6.67	20	H_t H_b	1.227 1.115	1.671 2.015	$0.145 \\ 0.229$	$0.332 \\ 0.361$	38.456 54.440	272.850 202.210
8.33	25	H_t H_b	1.295 1.342	1.905 2.248	0.224 0.285	$0.355 \\ 0.438$	47.876 65.970	209.251 258.680
		H_t H_b	1.361 1.762	2.164 2.586	$0.270 \\ 0.276$	$0.431 \\ 0.594$	57.112 69.370	261.130 410.360
10	30	H_t°	1.548	2.403	0.333	0.684	79.338	469.850

Table 3. Average values of velocity, TKE and Reynolds stresses in the low velocity zones along the planes H_b and H_t .

\overline{i}	Δh	Plane	\overline{V}	\overline{TKE}	TKE_{max}	\overline{RS}	RS_{max}
<u></u> %			m/s	$\mathrm{m}^2/\mathrm{s}^2$	$\mathrm{m}^2/\mathrm{s}^2$	N/m^2	N/m^2
1 67	_	H_b	0.180	0.023	0.081	3.980	36.72
1.67	5	H_t	0.180	0.021	0.063	3.760	29.08
3.33	10	H_b	0.286	0.048	0.143	7.540	52.54
5.55	10	H_t	0.275	0.045	0.146	8.241	73.03
5	15	H_b	0.321	0.055	0.184	10.176	83.67
9 1	10	H_t	0.295	0.059	0.269	12.076	150.09
6.67	6.67 20	H_b	0.370	0.083	0.360	14.095	142.21
0.01 20	H_t	0.393	0.092	0.285	14.865	120.08	
8.33	8.33 25	H_b	0.409	0.114	0.438	20.716	162.84
0.00	20	H_t	0.395	0.114	0.362	18.197	135.14
10	30	H_b	0.447	0.097	0.515	15.727	197.57
	30	H_t	0.333	0.147	0.570	22.535	185.62

Table 4. Area fractions inside the whole pool where values of velocity, TKE and Reynolds stresses are lower than threshold values $(A_V, A_{TKE} \text{ and } A_{RS})$. Area fractions range from 0 to 1 (1=100%). The average flow velocity, TKE and RS on the plane are also shown, considering the whole plane (low velocity areas and jet) and values of power dissipations D_V and D_ϵ are also included (as comparison with D_V). Threshold values are 0.3 m/s, 0.05 m²/s² and 60 N/m², respectively (Silva et al., 2011; Marriner et al, 2016).

\overline{i}	Δh	Plane	A_V	A_{TKE}	A_{RS}	\overline{V}	\overline{TKE}	\overline{RS}	D_V	D_{ϵ}
%			-	-	-	m/s	$\mathrm{m}^2/\mathrm{s}^2$	N/m^2	W/m^3	$\mathrm{W/m^3}$
1.67	5	H_b	0.750	1.000	1.000	0.233	0.025	4.67	16	16
1.07	3	H_t	0.710	0.921	1.000	0.241	0.024	4.50	10	10
3.33	10	H_b	0.496	0.470	0.992	0.373	0.056	9.63	46	35
ა.აა	10	H_t	0.505	0.489	0.989	0.396	0.053	10.18	40	55
5	15	H_b	0.458	0.428	0.967	0.470	0.070	15.35	85	60
9	10	H_t	0.473	0.459	0.959	0.472	0.075	17.07		
6.67 20	20	H_b	0.237	0.367	0.871	0.525	0.113	22.53	131	101
0.07	20	H_t	0.297	0.316	0.922	0.550	0.115	20.60	191	101
8.33 25	25	H_b	0.232	0.295	0.821	0.571	0.144	28.60	182	138
	20	H_t	0.277	0.259	0.880	0.592	0.145	26.12	102	100
10	30	H_b	0.289	0.282	0.870	0.760	0.140	28.51	240	194
	3 0	H_t	0.285	0.203	0.775	0.663	0.198	37.97	240	134

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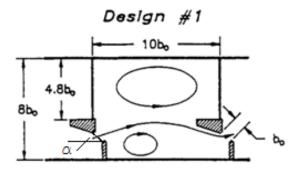


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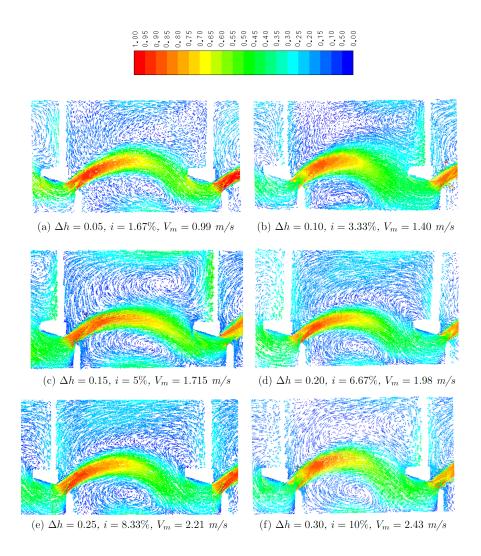


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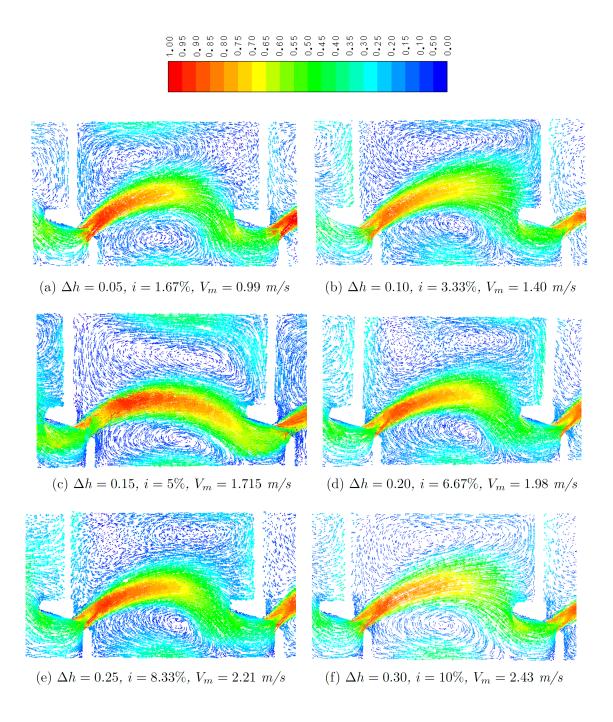


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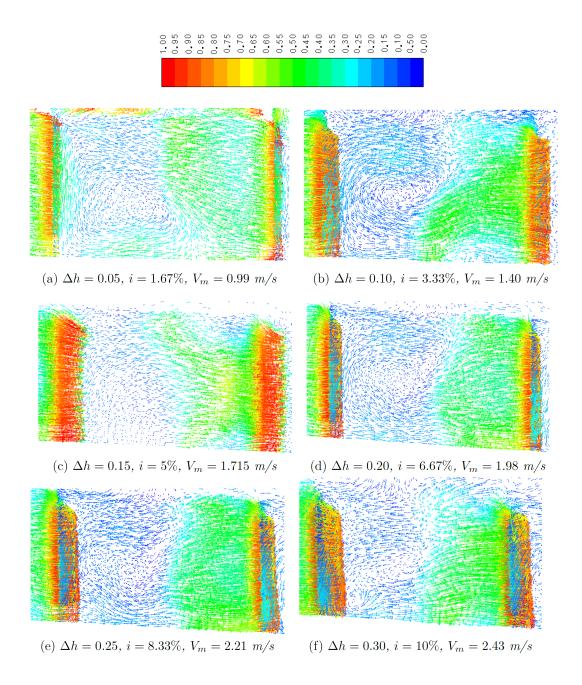


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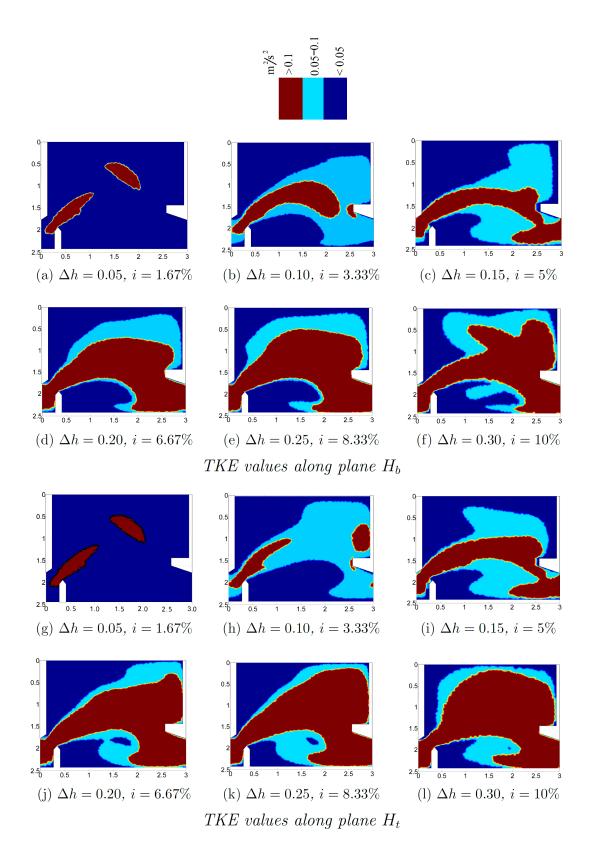


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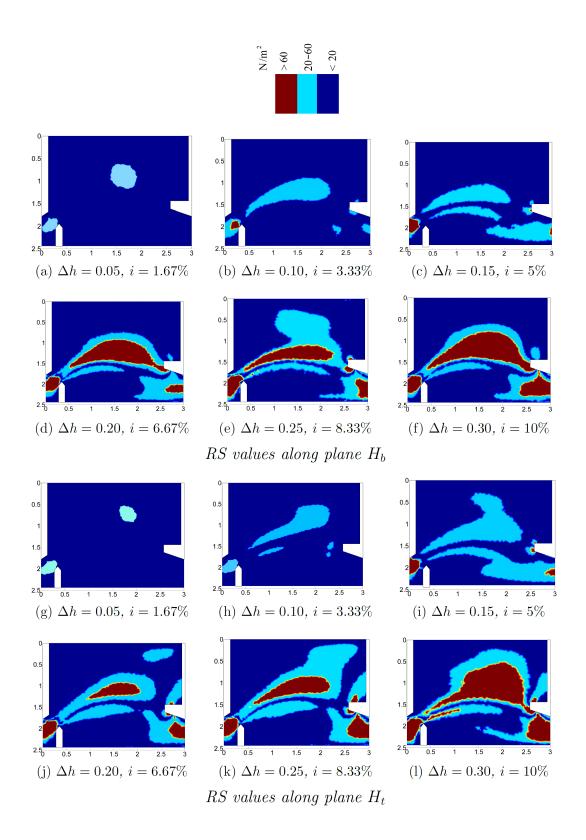


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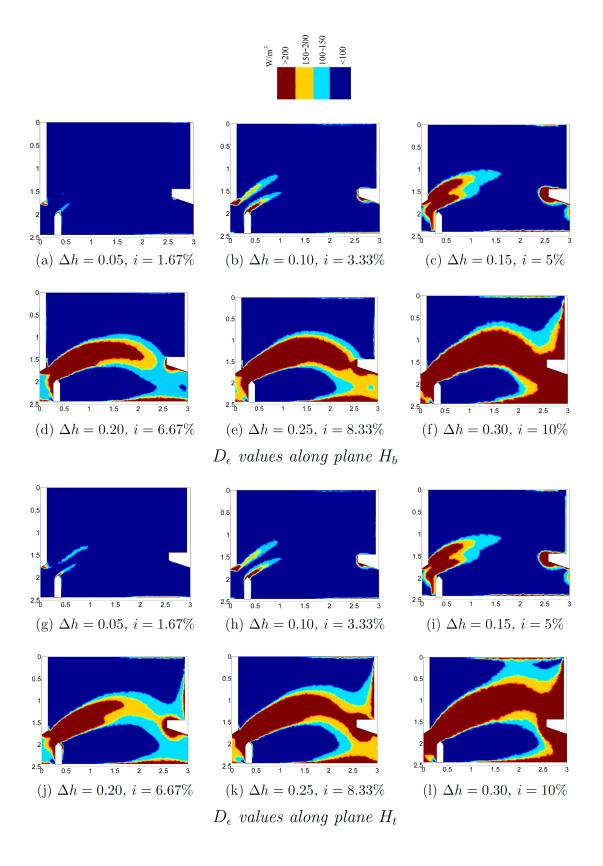


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