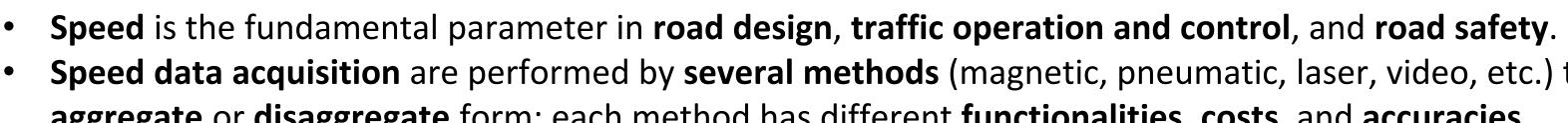
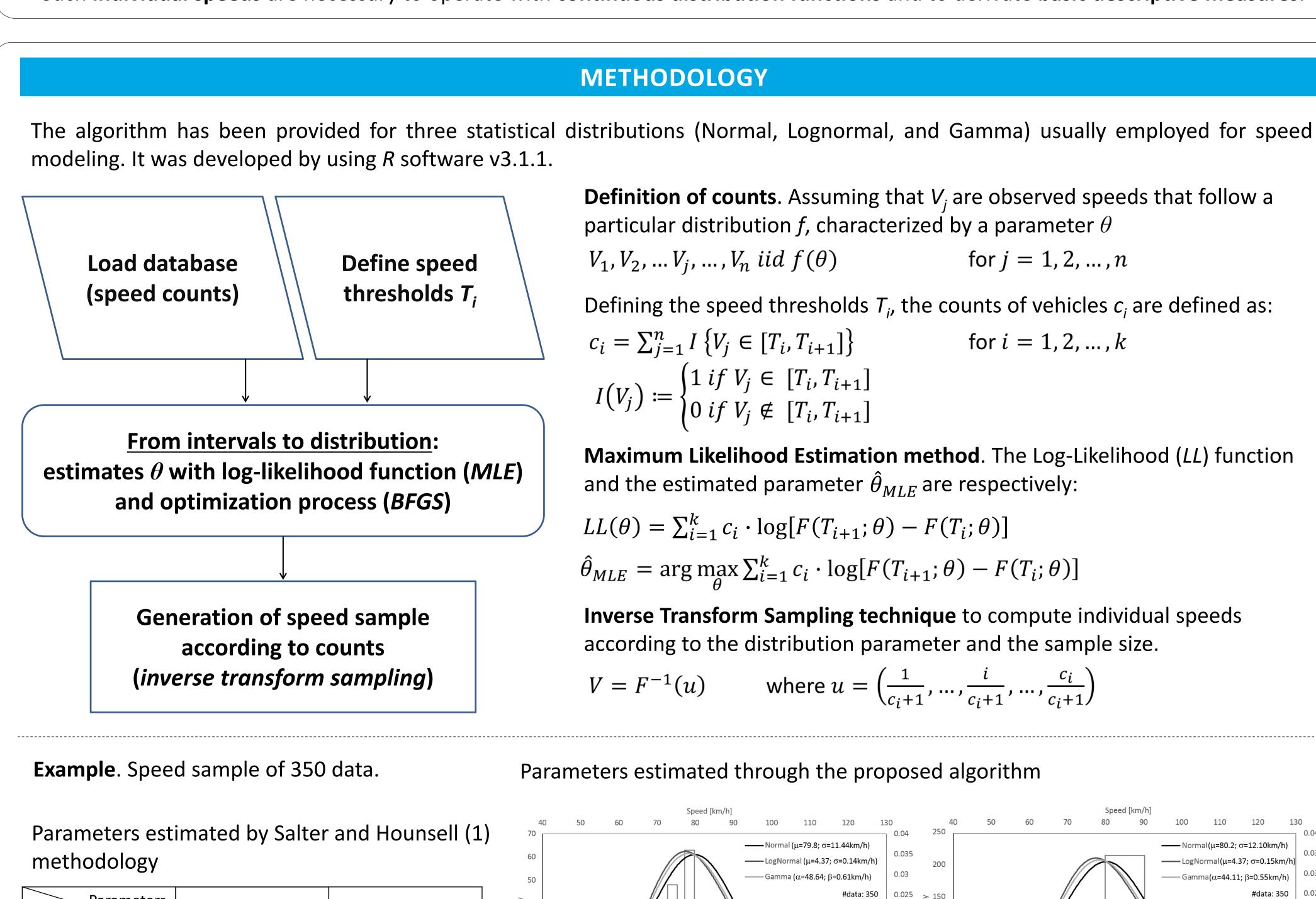
A METHODOLOGY TO DISAGGREGATE SPEED DATA COLLECTED BY **ROAD DETECTORS**

Catani L., Tremblay J.-M., Bassani M., Cirillo C.

BACKGROUND, MOTIVATIONS AND OBJECTIVES Speed data acquisition are performed by several methods (magnetic, pneumatic, laser, video, etc.) that may collect data in **aggregate** or **disaggregate** form; each method has different **functionalities**, **costs**, and **accuracies**. • Aggregate data conceal information about the real trend of discrete values, that are more powerful for operating purposes. Algorithm that computes disaggregate values from aggregate speed samples by considering different statistical distributions. Such individual speeds are necessary to operate with continuous distribution functions and to derivate basic descriptive measures. **METHODOLOGY**





Parameters Agg.classes	mean, $ar{v}$	std.dev, s	Ao Frequency 30			
20	79.9 km/h	11.5 km/h	20 10			
5	80.3 km/h	13.4 km/h	0	1		

(1) Salter, J., and N. B. Hounsell. *Highway Traffic Analysis and Design*, 3rd ed. Palgrave Macmillan, Houndmills, 1996. ISBN 0333609034.

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Definition of counts. Assuming that V_i are observed speeds that follow a particular distribution f, characterized by a parameter θ

 $V_1, V_2, \dots, V_j, \dots, V_n \text{ iid } f(\theta)$ for j = 1, 2, ..., n

Defining the speed thresholds T_i , the counts of vehicles c_i are defined as:

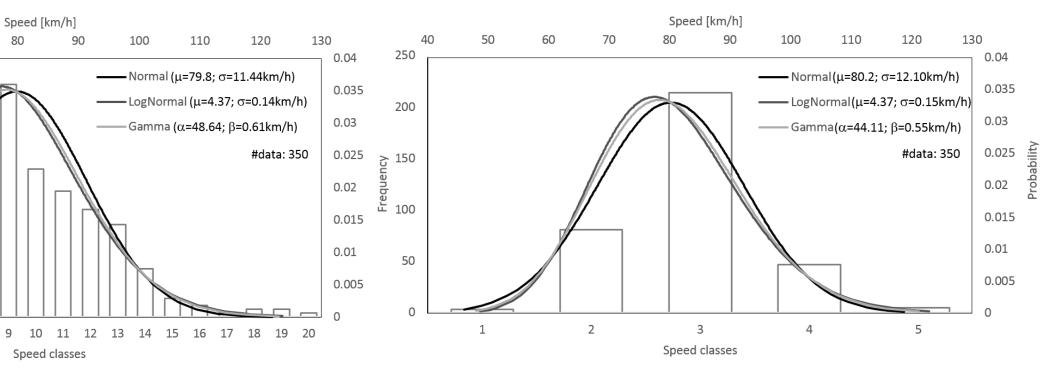
- for i = 1, 2, ..., k $c_i = \sum_{j=1}^n I\{V_j \in [T_i, T_{i+1}]\}$
- $I(V_j) \coloneqq \begin{cases} 1 \ if \ V_j \in [T_i, T_{i+1}] \\ 0 \ if \ V_j \notin [T_i, T_{i+1}] \end{cases}$
- Maximum Likelihood Estimation method. The Log-Likelihood (LL) function and the estimated parameter $\hat{\theta}_{MLE}$ are respectively:

$$LL(\theta) = \sum_{i=1}^{k} c_i \cdot \log[F(T_{i+1}; \theta) - F(T_i; \theta)]$$
$$\hat{\theta}_{MLE} = \arg\max_{\theta} \sum_{i=1}^{k} c_i \cdot \log[F(T_{i+1}; \theta) - F(T_i; \theta)]$$

Inverse Transform Sampling technique to compute individual speeds according to the distribution parameter and the sample size.

(*u*) where
$$u = \left(\frac{1}{c_i+1}, \dots, \frac{i}{c_i+1}, \dots, \frac{c_i}{c_i+1}\right)$$

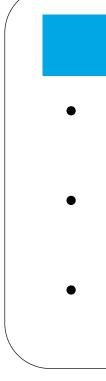
Parameters estimated through the proposed algorithm



Road

SΡ

Collected data were also analyzed to estimate the sample estimates (\bar{v} , s or α , β) and to define if they are prone to follow a specific distribution by using the Kolmogorov-Smirnov test.



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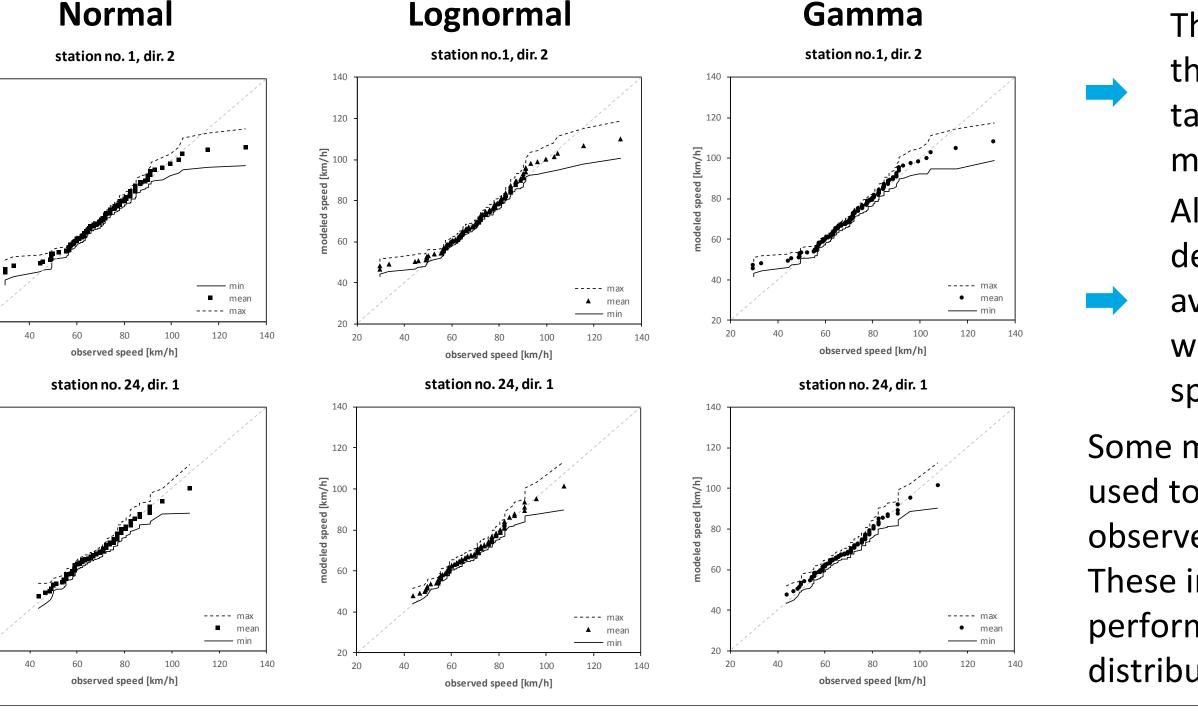
CASE STUDY

Speed surveys were performed in six stations on rural roads in the Province of Turin (North-West of Italy). Data we collected at the same time both with loop detectors (counts) and cross-registration (individual), during off-peak hours to avoid traffic congestion.

	e Station ID	Inductive loop stations (1 hour)		Video speed survey (15 minutes)					
id name									
		Time	sample size	Time	sample size	V _{min}	V _{max}		
SP6	1	12 - 1 pm	791	12.27 – 12.42 pm	202	33.5	116.5		
380			733		208	29.7	131.2		
P177	10	12 - 1 pm	205	12.37 – 12. 52 pm	48	30.9	92.7		
99177	7 12		330		81	27.6	93.3		
P176	1 /	11 am - 12 pm	199	11.44 – 11. 59 am	38	47.4	91.4		
09170	14		150		51	42.6	106.6		
P267	67 15	1F 0 10 am	386	0.45 10 am	103	16.5	95.7		
04201		/ 15	9 - 10 am	365	9.45 – 10 am	95	34.7	105.4	
P220) 16	10 11 am	248	10.27 10.52 am	64	44.5	89.1		
		10 10-11	10 - 11 am -	231	10.37 – 10.52 am	51	43.0	99.4	
102	183 24	24 1 - 2 pm		1 2 0 00	384	1 20 1 44 mm	106	43.8	107.5
L TO2			363	1.29 – 1.44 pm	90	36.9	134.8		
		Total	4385	Total	1137				

- estimated parameters are consistent (max difference equal to 12%) 🔿 STATIONARITY of flow
- no evidence to suggest that one function distribution (Normal, Lognormal or Gamma) is superior to the others

Algorithm application. Distribution means are similar to those computed in the preliminary analysis; standard deviations are influenced by data aggregation (only seven classes) and by the sample composition process (inverse transform sampling). Due to different observation periods, to compare observed and modeled speeds, reduced samples were created through a random extraction from the outcome vector, with the actual number of values inside each interval. The algorithm accuracy has been evaluated by evaluating the range in variability of the modeled speeds. For each statistical distribution, the algorithm was iterated a hundred times to define the limits of the estimates (solid line).



CONCLUSIONS

the modeled distribution parameters are similar to those of original data; the mean is generally not affected by aggregation, while some discrepancies are noticed in the standard deviation; the choice of the statistical distribution which best interprets the field observations may be made on the basis of accuracy measures such as those considered in this manuscript; the proposed algorithm facilitates the construction of databases of individual data that are essential for conducting

a variety of investigations which deal with speed analysis.



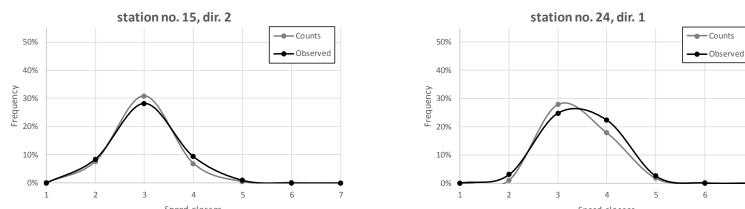
No. of classes: 7

ble-loop detectors: thresholds: 30, 50, 70, 90, 110, and 130 km/h

ss-registrations:

aggregation period: 1 hour recording period: 15 minutes

but comparable observation frequencies inside each speed interval (difference lower than 10%)



- The range in variability is small in the central part of the distribution, while it tends to increase towards the tails of the functions, leading to a greater variability in modeled speeds
- Although the maximum and minimum values can deviate from the equality line, the data close to the average are very close to it. As expected, the algorithm works reasonably well and sometimes very well for the speed located across the central speed classes.
- Some measures of accuracy (MPB, MAD, SDE, MPE) were used to provide information on the goodness-of-fit between observed and modeled data.
- These indexes confirm the results of statistical analysis performed on observed samples, or rather there is no one distribution that fits better with respect to the others.





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