

Diffusion of turbulence following both stable and unstable step stratification perturbations

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ABSTRACT

The evolution of a two-phase, air and unsaturated water vapor, time-decaying, shearless, and turbulent layer has been studied in the presence of both stable and unstable perturbations of the normal temperature lapse rate. The top interface between a warm vapor cloud and clear air in the absence of water droplets was considered as the reference dynamics. Direct, three-dimensional, and numerical simulations were performed within a 6×6 -m-wide and 12-m-high domain, which was hypothesized to be located close to an interface between the warm cloud and clear air. The Taylor microscale Reynolds number was 250 inside the cloud portion. The squared Froude's number varied over intervals of $[0.4; 981.6]$ and $[-4.0; -19.6]$. A sufficiently intense stratification was observed to change the mixing dynamics. The formation of a sublayer inside the shearless layer was observed. The sublayer, under a stable thermal stratification condition, behaved like a pit of kinetic energy. However, it was observed that kinetic energy transient growth took place under unstable conditions, which led to the formation of an energy peak just below the center of the shearless layer. The scaling law of the energy time-variation inside the interface region was quantified: this is an algebraic law with an exponent that depends on the perturbation stratification intensity. The presence of an unstable stratification increased the differences in statistical behavior among the longitudinal velocity derivatives, compared with the unstratified case. Since the mixing process is suppressed in stable cases, small-scale anisotropy is also suppressed.

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I. INTRODUCTION

Warm clouds, such as stratocumuli, swathe a significant part of the earth's surface and play a major role in the global dynamics of the atmosphere by reflecting incoming solar radiation—thus, contributing to the Earth's albedo—so that an accurate representation of their dynamics is important for the large-scale analyses of atmospheric flows.¹ Their dynamics are controlled by the close interplay that takes place among radiative driving, turbulence, surface fluxes, latent heat release, entrainment, and the energy captured from acoustic-gravity waves propagating into clouds from below or above cloud layers, or from cosmic rays during their interaction with water drops. The introduction of all these aspects into numerical simulations is still not the state of the art. For instance, compressibility should be included in a numerical simulation to account for internal acoustic and gravity waves and effects of baroclinicity, but efficient techniques that are able to carry out the simulation of clouds at the relevant evanescent values of the Mach number have not yet been developed. However, among all these physical effects, turbulent mixing and entrainment–detrainment processes at the top of a cloud have been identified as being of fundamental importance to determine the internal structure

of warm clouds so that a clear and complete understanding of their physics can be obtained.²

Stratification in the atmosphere is usually stable above the boundary layer,³ that is, a fluid particle that is displaced in the vertical direction tends to return to its initial position. However, unstable perturbations of local stratifications can be expected during the formation and disruption phases of clouds. Terrestrial rotation becomes of secondary importance in local atmospheric dynamics, and the stratification effects dominate.^{4,5} Over the last few decades, there have been important advances in the understanding of turbulence in the presence of intense stratification. For example, in the homogeneous stratified turbulence context, it is known that isotropic turbulence in a stratified fluid initially rapidly becomes anisotropic, with the formation of pancake-like structures on its inside.^{6,7} As pointed out by Malinowski *et al.*,⁸ data from most field campaigns and large-eddy simulations are too poorly resolved to infer the details of the interfacial layer, even though it is known that a high level of turbulence must be present for entrainment to take place. For this reason, in this work, we have studied transport across an unsaturated vapor cloud—clear air interface through the DNS (direct numerical simulation).

While we have considered turbulent transport without shear in thermal stratification conditions, and have also included the Lagrangian dynamics of both monodisperse and polydisperse populations of water droplets in two recent works,^{9,10} we here focus on the phase preceding the formation of a warm cloud containing a liquid phase. We, therefore, focus on the turbulent transport of the unsaturated vapor phase, considered as a passive scalar, and on the associated temperature field, considered as an active scalar. This has allowed us to consider a better spatial resolution by adopting the two-dimensional stencil parallelization method. In fact, this parallelization technique of the three-dimensional DNS code cannot be efficiently adopted in the presence of discrete elements, such as water droplets transported in a Lagrangian way, because of a large latency in the communication among processes (cores). A numerical code for the study of the growth, collision, coalescence, and clustering of water droplets inside turbulent, warm, and cloud-clear air interfaces is discussed here in detail.¹¹

Thus, we have focused on how the dynamics of the smallest scales of an airflow influence vapor and thermal turbulent transport. We have, therefore, simulated an idealized configuration to better understand, under controlled conditions, the basic phenomena that occur at the vapor cloud-clear air interface over length scales of the order of a few meters. Under these conditions, we have solved scales from a few meters to a few millimeters, that is, we have resolved only the small-scale part of the inertial range and the dissipative range of the power spectrum in a small portion ($6 \times 6 \times 12$ m) of the atmosphere across a vapor cloud-clear air interface. This has allowed us to investigate the entrainment dynamics that occur in a thin layer at the top of the cloud, which has a smaller scale than the scale explicitly resolved in the large-eddy simulations of clouds.¹² In this preliminary work, we have focused on two concomitant aspects of the top mixing layer of a vapor cloud: the effect of the presence of stratification and that of a turbulent kinetic energy gradient. We have not considered wind shear or radiative cooling processes, which are important in the presence of buoyancy reversal.^{13,14} Therefore, our simulations have been performed by applying the Boussinesq approximation to Navier-Stokes momentum and energy equations, together with an advective-diffusive passive scalar transport equation. Details on the considered physical problem we have considered and on the governing equations are given in Sec. II. Sec. III contains some of our main results pertaining to intermittency, energy redistribution, and entrainment. The concluding remarks are given in Sec. IV.

II. THE PHYSICAL PROBLEM

We considered the interaction of two homogeneous isotropic turbulence airfields, with different levels of kinetic energy and unsaturated water vapor (passive scalar), in a 6×6 -m by 12-m domain. As can be seen in Fig. 1, the chosen domain size allowed us to simulate the highest wave numbers of the spectral inertial range and the dissipative range of *in situ* measurements of the atmospheric power velocity spectra. As shown in Fig. 2, the two HIT regions make up the system interact through a shearless mixing layer, whose initial thickness was set to the same order of the integral scale as the air turbulence background ℓ , which here has been assumed equal to 3×10^{-1} m.

The two isotropic regions (external to the mixing) have different kinetic energies. The underlying region is the more energetic one, and it is constituted by the vapor cloud region. It hosts the passive scalar,

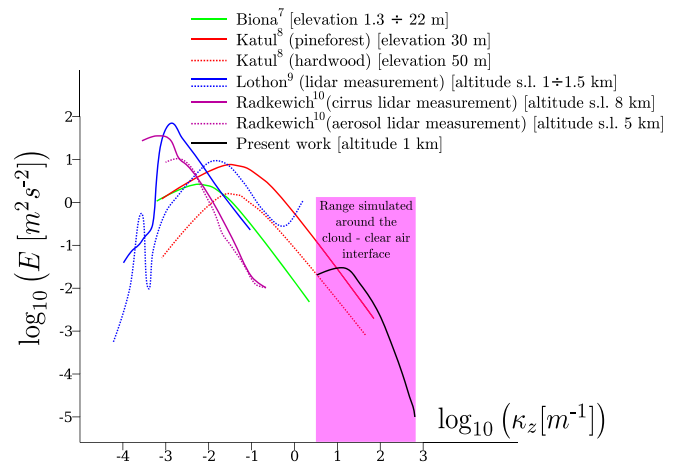


FIG. 1. Kinetic energy spectra. Contextualization of this study (black spectrum, inertial small-scale and dissipative ranges) to *in situ* atmospheric measurements (colored spectra: energy injection and low wave number inertial scales). The aim of the current simulations is to represent the small-scale range of the spectrum that *in situ* measurements have not been able to detect.

which is our model for the water vapor phase, and has a kinetic energy equal to $E_1 = 0.06 \text{ m}^2/\text{s}^2$; the root mean square of the velocity in this region is $u_{rms} = 0.2 \text{ m/s}$. The initial Taylor microscale Reynolds number, Re_λ , is approximately equal to 250 (λ is the Taylor scale). The kinetic energy ratio between the two regions is equal to 6.7. This energy ratio is of the same order as the ones measured in warm clouds

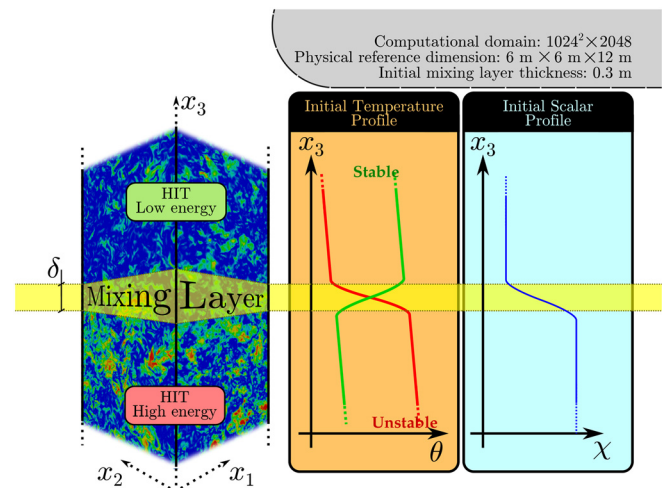


FIG. 2. Scheme of the initial conditions. E_1 is the mean initial turbulent kinetic energy below the shearless mixing layer (vapor cloud, HIT high-energy region), and E_2 is the same, but for the top (clear-air, HIT low-energy region). We assume $E_1/E_2 = 6.7$ for this model of the top interface. A complete overview of the simulation parameters can be found in Table I. The stratification inside this interfacial mixing is represented by a local temperature perturbation with respect to the neutral profile; the perturbation can be either stable or unstable. The unsaturated vapor (passive scalar) is initially only present in the high-energy cloudy region. Gravity is opposite to the positive x_3 direction. A complete overview of the stratification parameters for different simulation cases can be found in Table II.

TABLE I. Key simulation parameters and initial conditions.

Quantity	Symbol	Value	Unit
Domain size	$L \times L \times L_3$	$6 \times 6 \times 12$	m^3
Domain discretization	$N \times N \times N_3$	$1024 \times 1024 \times 2048$...
Grid step	Δx	5.86×10^{-3}	m
Initial rms velocity (cloud)	u_{rms}	0.2	m/s
Initial energy ratio (cloud–clear air)	E_1/E_2	6.7	...
Initial integral scale	ℓ_0	0.3	m
Initial dissipation rate (cloud)	ε_1	0.025	m^2/s^3
Kinematic viscosity of air	ν	1.57×10^{-5}	m^2/s
Initial Kolmogorov time (cloud)	$\tau_{\eta 0} = (\nu/\varepsilon_1)^{1/2}$	2.51×10^{-2}	s
Initial Kolmogorov length scale (cloud)	$\eta_0 = (\nu^3 \ell_0 / u_{rms}^3)^{1/4}$	6.17×10^{-4}	m
Initial eddy-turnover time	$\tau_0 = \ell_0 / u_{rms}$	1.5	s
Initial Reynolds number (cloud)	$\text{Re}_\ell = u_{rms} \ell_0 / \nu$	3821	...
Initial Taylor microscale Reynolds number	$\text{Re}_\lambda = u_{rms} \lambda / \nu$	250	...
Thermal expansion coefficient	α	3.55×10^{-3}	K^{-1}
Prandtl number	Pr	0.74	...
Schmidt number	Sc	0.61	...
Atmospheric lapse rate	G_0	0.0065	K/m^{-1}

(see, e.g., Ref. 8), and furthermore, it allows our results to be compared with laboratory and numerical experiments on turbulent shearless mixing (see Refs. 15 and 16) in the absence of any stratification.

Buoyancy is taken into account through perturbation, θ' , of the profile of the temperature distribution, θ , inside the troposphere, which is located across the shear-free mixing layer. The Prandtl number considered here is $\text{Pr} = 0.74$ (standard atmosphere, altitude of 1000 msl). The initial conditions for the temperature perturbation are described in Fig. 2 and in Table I. The ratio between the inertial and buoyancy forces is expressed by the Froude number Fr , which is defined as

$$\text{Fr} = \frac{u_{rms}}{\ell \mathcal{N}}, \quad \mathcal{N}^2 = \alpha g \frac{d\theta}{dx_3},$$

where u_{rms} is the root mean square of the velocity fluctuation at the lower border of the interfacial layer, ℓ is the macroscale length inside

the cloudy region, \mathcal{N} is the Brunt–Väisälä frequency, θ is the mean temperature, g is the gravitational acceleration, and α is the thermal expansion coefficient. We consider the square of the Froude number, Fr^2 , which is based on the maximum gradient within the initial interface, to characterize each simulation. The initial values of Fr^2 range from 981.6 (negligible stratification) to 0.4 (strong stable stratification). It should be noted that our usage of Fr^2 , instead of Fr , is due to the fact that we consider unstable cases. In fact, in such situations, \mathcal{N}^2 is negative for the initial temperature gradient—and the Brunt–Väisälä frequency is imaginary; it actually yields the amplification rate of the perturbations. The most unstable stratification we, therefore, consider has a Fr^2 equal to -4.0 .

The unsaturated water vapor is taken into account by considering its normalized concentration χ , which is equal to 1 in the lower cloudy region and to 0 in the upper clear-air region. Water vapor is considered as a passive scalar, with a Schmidt number $\text{Sc} = 0.61$ (standard atmosphere, altitude of 1000 m s.l.).

TABLE II. Initial stratification parameters. Temperature gradient values (second column) are also expressed in terms of $G_0 = 0.0065$ in the first column. $\mathcal{N}_{ic} = \sqrt{\alpha g \frac{\partial \theta}{\partial x_3}}$ is the characteristic Brunt–Väisälä frequency of the initial condition (suffix ic). The Froude number, $\text{Fr} = \frac{u_{rms}}{\mathcal{N}_{ic} \ell}$, and the Reynolds Buoyancy Number, $\text{Re}_b = \frac{\varepsilon \mathcal{N}_{ic}^2}{\nu \varepsilon}$, offer an indication of the order of magnitude of the buoyancy forces, compared with the inertial terms (ε is the initial energy dissipation rate, ℓ is the initial value of the spatial integral scale, and ν is the kinematic viscosity of air, see Table I for corresponding values).

Level	$\nabla_z \theta_{ic} (\text{K m}^{-1})$	$\Delta \theta (\text{K})$	$\mathcal{N}_{ic} (\text{s}^{-1})$	Fr	Fr^2	Re_b	Intensity
$2G_0$	1.3×10^{-2}	4.0×10^{-3}	2.13×10^{-2}	31.3	981.6	0.7	Neutral
$30G_0$	2.0×10^{-1}	6.0×10^{-2}	8.24×10^{-2}	8.09	65.4	10.9	Quasi-neutral
$100G_0$	6.7×10^{-1}	2.0×10^{-1}	1.50×10^{-1}	4.43	19.6	36.3	Intermediate
$500G_0$	3.3	1.0	3.36×10^{-1}	2.00	4.00	181.7	High
$5000G_0$	3.3×10^1	1.0×10^1	1.06	0.62	0.4	1817.2	Extreme
$-100G_0$	-6.7×10^{-1}	-2.0×10^{-1}	-19.6	-36.3	Unstable, intermediate
$-500G_0$	-3.3	-1.0	-4.00	-181.7	Unstable, high

We use the continuity, momentum, and energy balance equations within the Boussinesq approximation, which holds for small temperature variations,¹⁷ while we use an advective–diffusive transport equation for water mixing ratio

$$\nabla \cdot \mathbf{u}' = 0, \quad (1)$$

$$\frac{\partial \mathbf{u}'}{\partial t} + (\mathbf{u}' \cdot \nabla) \mathbf{u}' = -\nabla \frac{\tilde{p}}{\rho} + \nu \nabla^2 \mathbf{u}' + \alpha g \theta', \quad (2)$$

$$\frac{\partial \theta'}{\partial t} + \mathbf{u}' \cdot \nabla \theta' + u_3 G = \kappa \nabla^2 \theta', \quad (3)$$

$$\frac{\partial \chi}{\partial t} + \mathbf{u}' \cdot \nabla \chi = d_\chi \nabla^2 \chi, \quad (4)$$

where $\theta = \theta_0 + \tilde{\theta}(x_3) + \theta'(x, t)$ is the temperature, which is composed of the reference constant temperature θ_0 at a given altitude, of the static component $\tilde{\theta}(x_3) = G_0 x_3$, where G_0 is the standard lapse rate, and of the fluctuation $\theta'(x, t)$; moreover, $\tilde{p} = p + \alpha g x_3 (\theta_0 + G_0 x_3 / 2)$ is the total hydrodynamic pressure (p is the fluid dynamic pressure, α is the thermal expansion coefficient, and g is the gravity acceleration); \mathbf{u}' is the velocity fluctuation; and χ is the vapor concentration of the air–water vapor mixture. The constants κ and d_χ stand for the thermal and water vapor diffusivity, respectively. This is a very consolidated basic model that is often used as a representation of Eulerian equations for turbulent fields to which the liquid water component can be added as a Lagrangian set of N point-like droplets.^{9,18–23}

The initial condition for the velocity field is obtained by means of a linear matching of two different HIT fields, u_1 and u_2 , which are randomly generated by respecting the physical solenoid condition, the required integral scale, and the mean kinetic energy, see Ref. 24. The initial energy profile along direction x_3 is obtained by coupling the u_1 and u_2 fields, using Eq. (5). As far as the scalars are concerned, in analogy with previous work,^{9,25} the initial conditions (constant along directions x_1 and x_2) are obtained from Eqs. (6) and (7) for the temperature and water vapor concentration, respectively. These equations are listed below

$$\mathbf{u}'(\mathbf{x}, t = 0) = \mathbf{u}_1(\mathbf{x}) p_1(x_3) - \mathbf{u}_2(\mathbf{x}) (1 - p_1(x_3)), \quad (5)$$

$$\theta(\mathbf{x}, t = 0) = \Delta \theta p_2(x_3), \quad (6)$$

$$\chi(\mathbf{x}, t = 0) = p_1(x_3), \quad (7)$$

where u_1 and u_2 are the two external HIT, and $\Delta \theta$ is the initial temperature step, while the weight functions $p_1(x_3)$ and $p_2(x_3)$ are defined as

$$p_1(x) = \frac{1}{2} \left[1 + \tanh \left(a \frac{x_3}{L_3} \right) + \tanh \left(a \frac{x_3 - L_3/2}{L_3} \right) + \tanh \left(a \frac{x_3 - L_3}{L_3} \right) \right], \quad (8)$$

$$p_2(x) = \frac{x_3}{L_3} - \frac{1}{2} \left[1 + \tanh \left(a \frac{x_3 - L_3/2}{L_3} \right) \right]. \quad (9)$$

The simulations were performed using our in-house computational Navier–Stokes code, which implements a pseudo-spectral Fourier–Galerkin spatial discretization and an explicit low-storage fourth-order Runge–Kutta time integration scheme. Evaluation of the nonlinear (advective) terms is performed by means of the 3/2 dealiased method.²⁶

The grid has $N \times N \times N_3$ points, with $N = 2^{10}$ and $N_3 = 2N$, for a total of 2^{31} grid points. Such a grid allows us to capture all the turbulent scales from the largest (integral scale ℓ) to the smallest (Kolmogorov scale η). In fact, it should be noted that since the turbulence intensity, and thus the dissipation rate, decay in time, the small scales, in particular the Kolmogorov scale, η_k , grow in time. The grid size of 5.86 mm inside the mixing region matches the $k_{\max} \eta \sim 3$ requirement for about two eddy-turnover times.

The code is based on TurIsMi, v1.4, of the Philofluid group (www.polito.it/philofluid), which was released under the terms of the GNU General Public License. A new version of the code has here been implemented using the Fortran 2018 standard. The new features allowed us to design the code as slightly object-oriented, thereby increasing the readability and efficiency of shared routines. Direct/inverse FFTs (Fast Fourier Transforms) are evaluated using FFTW (Fast Fourier Transforms of the West) open-source libraries (which support the shared memory paradigm). Parallelization is performed with a hybrid (shared/distributed) memory paradigm. In particular, we have used a stencil parallelization (parallelization over two directions) to distribute the computational domain over a chosen number of processes (up to $N^2/2$ —theoretical value). This distribution was performed using the MPI 3.0 standard, which allows modern MPI libraries (such as OpenMPI and MPICH2) to be used. In order to perform FFTs along a given direction, a process needs to know the values associated with all the wave numbers in such a direction. For this purpose, matrix transpositions are mandatory to swap the distributed direction. During the inverse transform/transposition process, the domain is “expanded” by including the zero-padded antialiasing region (and vice versa, it is “contracted” during direct transforms). Using the expanded domain in a physical space only reduces the number of needed transforms. For simplicity, we considered a cubic domain, with N^3 in wave number space, and $M^3 = 27/8N^3$ points in physical space. Without the expansion/contraction process, the number of single FFTs required to perform a global transform would be equal to $N^2 + NM + M^2 = 27/4N^2$, thereby a saving of 30% of the computational time was achieved. The MPI 3.0 standard allows us to implement a global communication subroutine for direct/inverse domain transposition and also for input/output routines. The shared part of the parallelization is managed by OpenMP in the rest of the code. As a result of the optimization, the new version of the code is about 5 times faster and has a near-linear speedup, which allowed us to fully exploit the potential of massively parallelized supercomputers, see Fig. 3. The simulations were performed on the TGCC Curie supercomputer, within PRACE project no. RA07732011, for a total of 3 million CPU hours.

III. RESULTS

In this section, we analyze the simulated fields by comparing the results obtained for the different stable and unstable stratification cases. We analyze the statistical behavior of the velocity and scalar fields in Subsection III A. The formation of kinetic energy sublayers in the mixing region is discussed in Subsection III B. The effects related to the entrainment process are presented in Subsection III B 1, while the anisotropy, dissipation, and small-scale effects are discussed in Subsections III B 2.

The temporal evolution of Fr^2 is shown in Fig. 4. Smaller values of the Froude number represent a higher level of stratification.

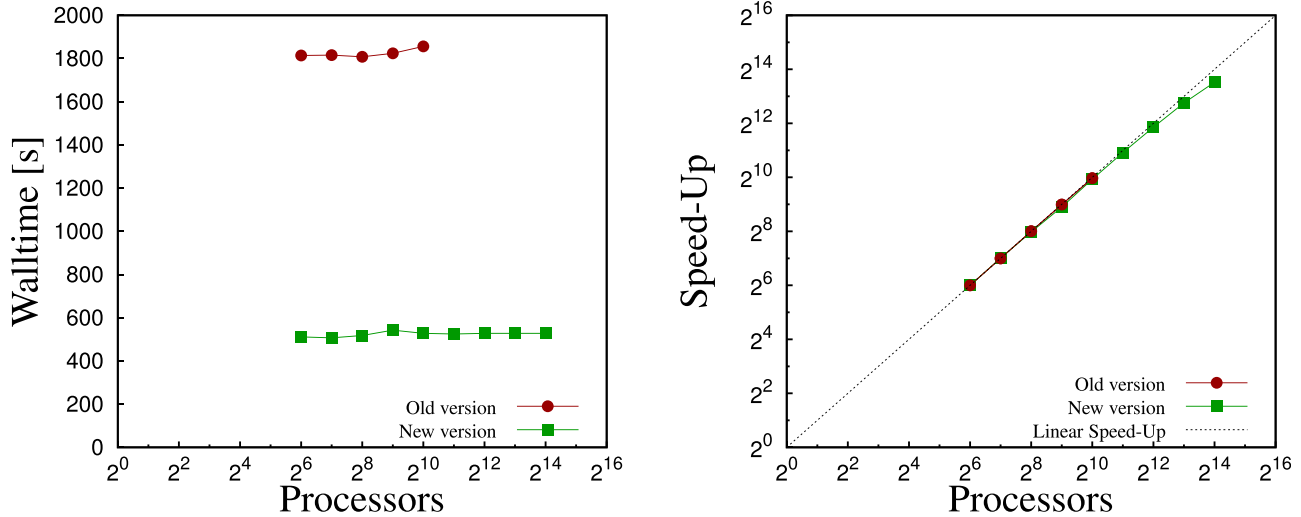


FIG. 3. Left: wall time for a single RK4 cycle in a cubic domain with a discretization of 2048^3 grid points. Wall time = tn , where t is the real time needed for the computation, and n is the number of used processors. Right: speedup of the code. Speedup = $n_R t_R / t$, where t_R and n_R are reference quantities (in this case, $n_R = 64$).

Figure 4 shows that the initially computed absolute values of the Froude numbers are decreasing over time, which means a temporal increase in the stratification level. This is due to the decay of the kinetic energy and the consequent increase in the integral scale, see definition of the Froude number and Brunt–Väisälä frequency in Sec. II.

A. Spatial statistical properties

The statistics are computed by averaging the variables in the planes (x_1, x_2) normal to the mixing direction (with a sample of

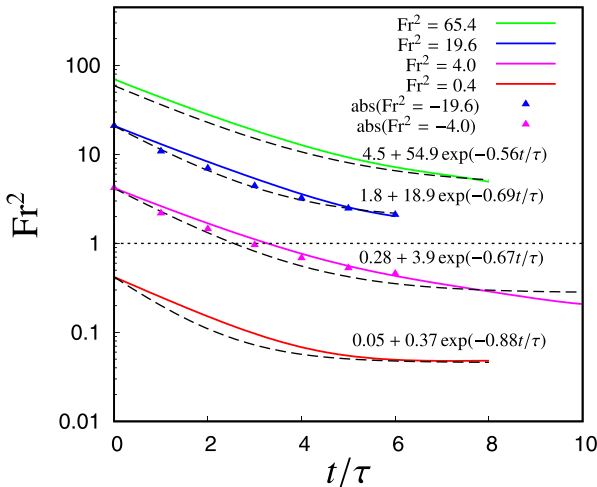


FIG. 4. Time evolution of the instantaneous Froude number $Fr^2(t)$ for the simulations with stable stratification. The evolution in unstable cases is very close to this one, except for the sign, which is negative. Dashed lines represent the fitting exponential laws of these temporal decays. For the readers' convenience, they have also been gathered in Table III. The horizontal dotted line, $Fr^2 = 1$, indicates the moments in time when the buoyancy forces are of the same order as the inertial ones: the relative effects are found when $Fr^2(t) \approx 2 \div 3$.

$2^{10} \times 2^{10}$ data points). We focus on the variation along the vertical (nonhomogeneous) direction, x_3 . We thus define the average operator $\langle \cdot \rangle(x_3)$ as the mean value inside a plane (x_1, x_2) for given values of x_3 ,

$$\langle \cdot \rangle(x_3) = \frac{1}{2^{20}} \sum_{i=1}^{2^{10}} \sum_{j=1}^{2^{10}} \cdot (x_{1,i}, x_{2,j}, x_3).$$

The second-order moment is represented by the variance in scalar fields θ and χ or by the turbulent kinetic energy of the velocity field, which is defined as $E = \frac{1}{2} (\langle u_1^2 \rangle + \langle u_2^2 \rangle + \langle u_3^2 \rangle)$. High-order moments are represented by skewness and kurtosis (third- and fourth-order moments normalized by means of the variance), defined as $S(\cdot) = \langle \cdot^3 \rangle / \langle \cdot^2 \rangle^{1.5}$ and $K(\cdot) = \langle \cdot^4 \rangle / \langle \cdot^2 \rangle^2$, respectively. It should be noted that the definition of skewness and kurtosis for passive scalar field χ slightly differs from the one given in the previous equation. Because of the proximity of the external regions, where the variance $\langle \chi^2 \rangle$ vanishes, in order to prevent numerical problems, the actual definitions of skewness and kurtosis are modified as

$$S(\chi) = \langle \chi^3 \rangle / (\langle \chi^2 \rangle + 0.005 \langle \chi^2 \rangle_{\max})^{1.5}$$

TABLE III. Exponential fits, $f(x) = b + n \exp^{-x/u}$, of the temporal decay of the Froude numbers shown in Fig. 4.

Froude number	Fitting parameters	Asymptotic standard error
$Fr^2 = 65.4$	$b = 4.5, n = 54.9,$ $u = 1.8$	$\delta_b = 5.5\%, \delta_n = 1.7\%,$ $\delta_u = 2.8\%$
$Fr^2 = 19.6$	$b = 1.8, n = 18.9,$ $u = 1.44$	$\delta_b = 15.4\%, \delta_n = 2.2\%,$ $\delta_u = 5.8\%$
$Fr^2 = 4.0$	$b = 0.28, n = 3.9,$ $u = 1.5$	$\delta_b = 10.5\%, \delta_n = 1.7\%,$ $\delta_u = 3.9\%$
$Fr^2 = 0.4$	$b = 0.05, n = 0.37,$ $u = 1.13$	$\delta_b = 2.8\%, \delta_n = 0.7\%,$ $\delta_u = 1.8\%$

and

$$K(\chi) = \langle \chi^4 \rangle / (\langle \chi^2 \rangle + 0.01 \langle \chi^2 \rangle_{\max})^2,$$

where $\langle \chi^2 \rangle_{\max}$ indicates the maximum variance value along direction x_3 .

It is important here to underline that the shearless turbulent mixing is highly intermittent. Skewness and kurtosis distributions are principal indicators of an intermittent behavior and, therefore, are commonly used to perform the statistical analysis of the turbulent shearless mixing. For the convenience of readers not acquainted with this subject, let us cite some of these properties: the demonstration of the anisotropy of the small scales,¹⁶ the condition for the departure from Gaussianity,²⁷ the measure of the displacement of the mixing

center—a thing commonly determined in terms of the skewness peak displacement, the motivation of nonsufficiency of the description in terms on the first two velocity fluctuation moments,^{15,28–30} and the macroscale spatial variation as a source of intermittency and kinetic energy gradients.³¹

As a result of the evolution of the ratio between the buoyancy force and the other dynamical effects (advection and diffusion) and by looking at the statistical behavior of the turbulent kinetic energy shown in Fig. 5, the evolution of the system can be split into two main stages. As long as the ratio remains small, no significant differences emerge with respect to a nonstratified case. However, as the stratification perturbation becomes more important, buoyancy effects prevail, and differences are present from both the quantitative and qualitative points of view.

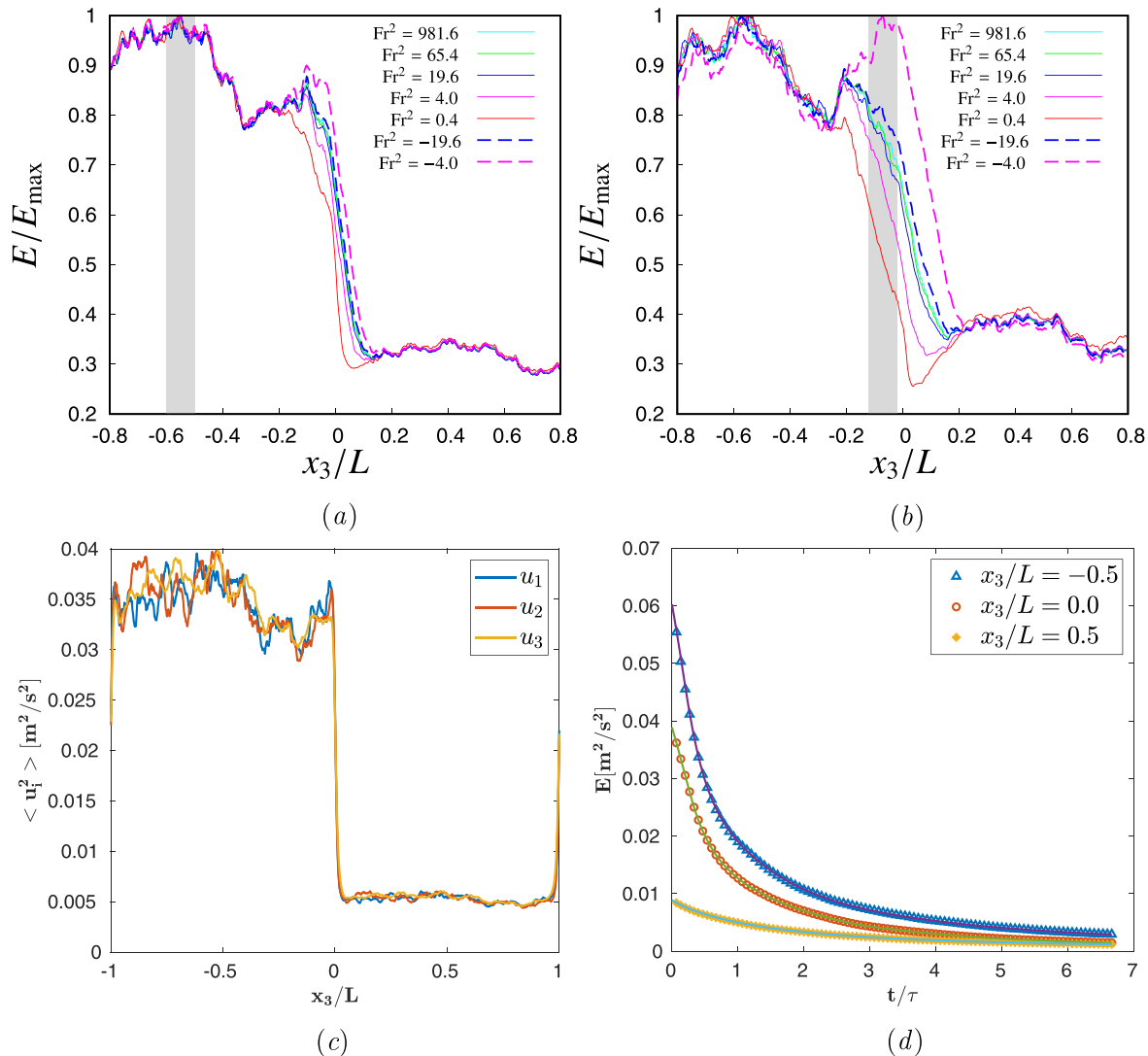


FIG. 5. Turbulent energy along vertical direction x_3 , computed from the velocity variance in the horizontal planes, $x_1 - x_2$, panels (a) and (b): $t/\tau = 3$ and 6, respectively. The data are taken from simulations with different levels of stratification, which are represented by the initial reference squared Froude number. Panel (c): distribution of the initial velocity variance across the computational domain. Panel (d): kinetic energy decay inside the unsaturated cloud (blue triangles), the interfacial mixing layer (red circles), and the clear-air region (yellow diamonds).

The effects of different stratification levels are clearly visible on the turbulent kinetic energy shown in Fig. 5, where two different instants are compared, $t/\tau = 3$ in Fig. 5(a) and $t/\tau = 6$ in Fig. 5(b), where τ is the initial eddy-turnover time. When the buoyancy term becomes comparable with the other forces, a slight downward displacement of the energy gradient location takes place. Subsequently, the onset of a sublayer, characterized by a widening of the pit of kinetic energy in time, can be observed, see also Sec. III B and Fig. 11 [panels (c)–(e)]. The presence of such a sublayer changes the system dynamics, because two interfaces are produced in this situation. The first—which would also be present in the absence of stratification—separates the high-turbulent energy region from the pit. The second one—which would not be present without stratification—separates the low-turbulent energy region from the center of the mixing layer. Therefore, a strong stable stratification induces a kind of physical separation between the

regions below and above the mixing layer, thus decreasing their interaction to a great extent. On the other hand, an increment of the kinetic energy inside the mixing region, a sort of peaky sublayer, can be observed in unstable cases. Again in this case, we observe the formation of a secondary energy gradient, but its location is reversed with respect to the stable case. At this point, the secondary gradient separates the peak from the high-energy region where the vapor cloud is located. In fact, the peak is shifted toward the high-energy region (while the pit is closer to the low-energy one). The principal gradient is now pushed upward (positive x_3), see also panel (e) in Fig. 11.

The parts of the flow where the primary energy gradient acts and the secondary one (when present) intermittently behave. Figure 6 shows the skewness and kurtosis of the vertical velocity fluctuations after 6 timescales [panels (a) and (c), respectively], and the time evolution of their maximum and minimum values [panels (b) and (d)].

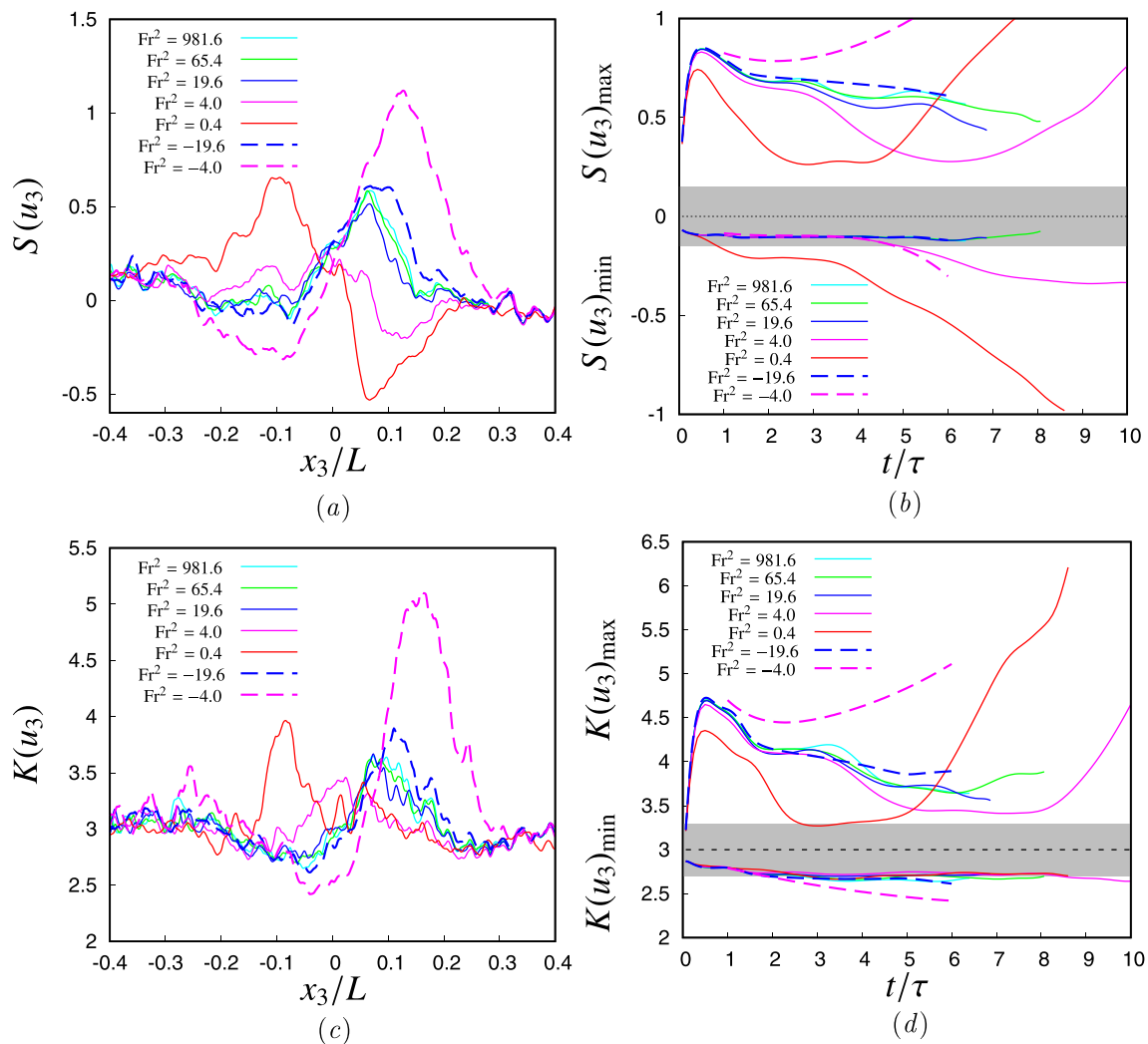


FIG. 6. Vertical velocity skewness [panels (a) and (b)] and kurtosis [panels (c) and (d)] along vertical direction x_3 , computed from vertical velocity central moments in the horizontal planes ($x_1 - x_2$). The data are taken after 6 τ [panels (a)–(c)] and over the temporal evolution [panels (b)–(d)]. Simulations with a different stratification are represented by the square Froude number, Fr^2 . The gray band in panels (b) and (d) represents the intermittency range measured outside the mixing layer.

A reduction in the maximum values, which decay much faster than the nonstratified or weakly stratified cases, can be observed for the stably stratified cases, beyond $t/\tau \sim 1$. Such a fast decay during pit formation leads to a low intermittency, which is characterized by values as low as those observed outside the mixing anisotropic region (the “normal” range is represented by a gray band in panels *b* and *d* in Fig. 6). S and K then quickly grow in time, reaching higher values than the unstratified case. The decay of intermittency in the unstable stratification case is immediately damped, and a growth of S and K is observed for the $Fr^2 = -4.0$ case beyond 3 timescales. The final configuration at the end of the numerical simulation seems to be more intermittent in both the stable and unstable cases, with values that can become even 100% larger than in the unstratified case.

The statistical properties of temperature fluctuation θ' , of the active scalar, and of the vapor passive scalar concentration, χ , are analogous. In fact, the nondifferential term $u_3 G_0$ in energy Eq. (3) does not exert an effect that is comparable with that of the buoyancy term inside the momentum equation. The latter has a vectorial nature and efficiently receives and transposes the gravitational effect to the velocity field. Our simulations show that the transport of temperature is comparable with the transport produced by advective–diffusive Eq. (4) in the vapor field, that is, a simple passive scalar field, see Fig. 7, where the first four statistical moments across the interface are presented at $t/\tau = 6$. The effects on the scalar fields are milder than the ones observed on the velocity. The width of the region with nonzero variance depends on the stratification level and becomes thinner for stable cases. Substantial variations can be observed in the case of very strong stratification, for example, when $Fr^2 = 0.4$. Scalar fluctuations are damped in stable cases and slightly enhanced in the presence of unstable stratification. The shrinking of the mixing layer becomes remarkable after the onset of the pit of energy and is linked to the reduction in entrainment, see Subsection III B 1, and for a complete overview, see Gallana's Ph.D. thesis.³²

As far as the high-order moments are concerned, the scalar fields initially follow the same trend as the velocity fluctuations, with a reduction in S and K when the stratification is stable and a growth when it is unstable, see the panels in the second, third, and fourth rows in Fig. 7. A large difference can be observed, after a few timescales, in the stable stratification case. Here, the onset of the energy pit blocks the mixing process, and the values of the high-order statistics tend to remain almost constant.

It is also interesting to note that the morphology of the spatial distribution of the vapor statistics, the passive scalar, is not affected to any great extent by the presence of a population of either monodisperse or polydisperse water drops. Indeed, if a comparison is made between our simulations containing the aqueous phase, which is equivalent in quantity to what is present inside warm clouds (LWC, liquid water content, equal to $0.8 \text{ gr}/\text{m}^3$), see Golshan *et al.*⁹ and the work of Fossa' *et al.* 2022,¹⁰ which was carried out under almost the same Froude numbers, it can be seen that only the temporal evolution of the maximum and minimum peaks of the vapor statistical distributions is in fact affected, albeit only slightly, by the presence of drops, and by the related phenomenology of evaporation–condensation and collision–coalescence, see Fig. 8. Moreover, there is a variation of the maximum values of the kurtosis function, which does not settle, in the long term, on the same asymptotic values, see the bottom right panel in Fig. 8. Furthermore, it can be observed that the thinning of the

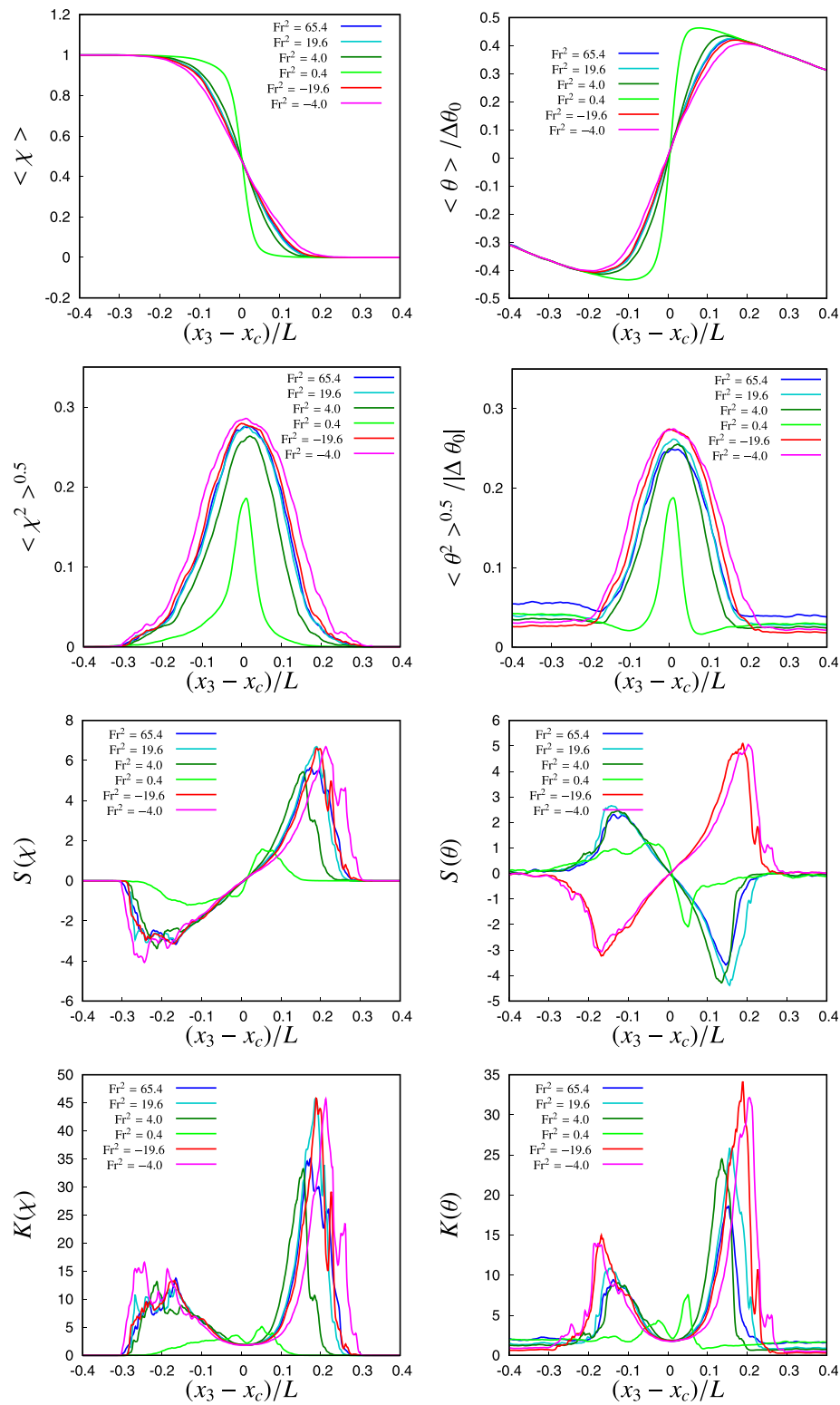
mean temperature profile when the stratification is increased, which thins by about four times as the stratification increases from neutral to $Fr = 0.4$, that is, $5000 G_0$, is the same as that measured by Jayesh and Warhaft,²⁸ see Fig. 7, and in particular, the curve where the mean temperature profile half width is normalized by the integral length scale of the large-scale turbulence on the lower side of their mixing layer.

As a validation of our simulations, we present a comparison with the results of a similar laboratory study carried out by Jayesh and Warhaft (JW in the following) in 1994 at Cornell University.²⁸ In their experiment, a stably stratified interface, with strong turbulence below and quiescent air above, was studied in a wind tunnel with the aim of simulating the conditions at the inversion cap at the top of the atmospheric boundary layer. Thus, this system is the same as the one in our study as regards the transport of momentum, turbulent energy, and temperature, although the transport of the passive scalar is missing. They generated the interfacial layer by means of a composite grid, with a small mesh size above and a large one below, see Ref. 28. In the laboratory study, the system is steady state and is generated by means of a uniform mean flow with different levels of turbulence above and below the interface. The present numerical simulations are instead in temporal decay. No background mean flow is present. Though the comparison is more qualitative than quantitative because both the Richardson and the Reynolds numbers are different ($Ri = 0.8$, $x/M = 32$, and $Ri = 63$, $x/M = 148$, in JW; $Ri = 0.11$, $t/\tau = 2.5$, roughly equivalent to $x/M = 40$, and $Ri = 18.2$, $t/\tau = 3.2$, roughly equivalent to $x/M = 48.32$, in this study), the laboratory and numerical statistical trends are very similar, as can be observed in Fig. 9. Here, the distributions across the mixing layer of the fluctuations of the temperature flux, of its spatial derivative, and of the covariance between $\langle u_3^2 \theta' \rangle$ are shown. Note that in JW, the coordinate x_3 is represented by z and u_3 by w . The reverse sign of the flux of the temperature inside the weak turbulence region, which corresponds to a counter-gradient heat flux (see also Riley, Metcalfe and Weissmann 1981,³³ and Yoon and Warhaft 1990³⁴), should be noted in particular. The correspondence of the trends across the layer between our numerical experiment and the laboratory ones of JW extends to the kinetic energy flow, see Subsection III B 1 and Fig. 17, panel (a), in JW and our Fig. 14. A dynamic aspect, which accompanies the formation of the kinetic energy pit and the blockage of the mixing layer growth, can be observed.

To complete this section, we report a comparison between the active and passive scalars studied here in Fig. 10, for the same distributions shown in Fig. 9. Once again, a remarkable similarity can be observed in the behavior of the two scalars, thus demonstrating the clear dominance of convective transport on the scalar, which, in principle, should be of the active type.

B. Stratified shearless turbulent mixing and the formation of energy pit/peak sublayers

In Sec. III A, the onset of a sublayer can be observed beyond the time instant of the transient when buoyancy starts to be non-negligible in the center of the domain, where the initial temperature gradient is located. The formation and time evolution of such a sublayer are shown in Fig. 11, where the time-variation of the temperature and vapor interface thicknesses and the normalized kinetic energy profiles, $E_{\text{norm}} = (\langle E \rangle - E_{\text{min}})/(E_{\text{max}} - E_{\text{min}})$, are shown. Here, E_{max} and E_{min} are the maximum and the minimum mean kinetic energies,


 FIG. 7. Comparison of the passive (left) and active (right) scalar statistics, $t/\tau = 6$.

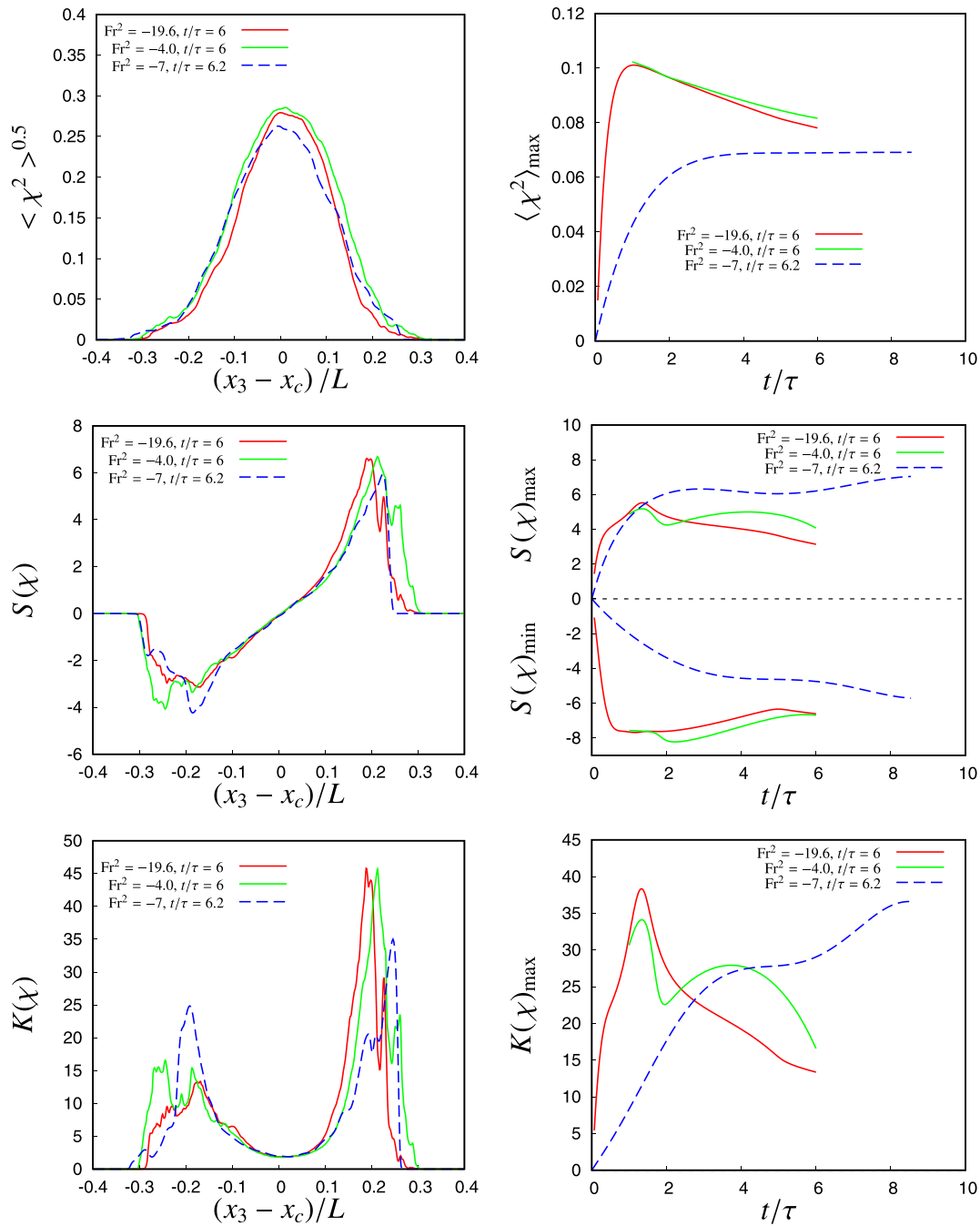


FIG. 8. Comparison of vapor moment statistics for simulations with droplets (dashed) and without (solid, same data as shown in the left column of Fig. 7).

respectively. The normalized energy is almost equal to 0 in the low-energy clear-air region and nearly equal to 1 in the high-energy vapor cloud region. In stable cases, the presence of the pit of energy changes the location of E_{\min} , which is now placed inside the pit, while E_{\max} always remains inside the high-energy region. As a consequence, after

the onset of the pit, E_{norm} is approximately equal to 1 in the high-energy region, to 0 inside the pit, and to > 0 in the low-energy region, as can be observed in panel (c) in Fig. 11 for the $Fr^2 = 4.0$ case. An opposite trend can be observed in unstable cases, after the formation of their peak sublayer, E_{norm} is 0 in the low-energy region, 1 inside the

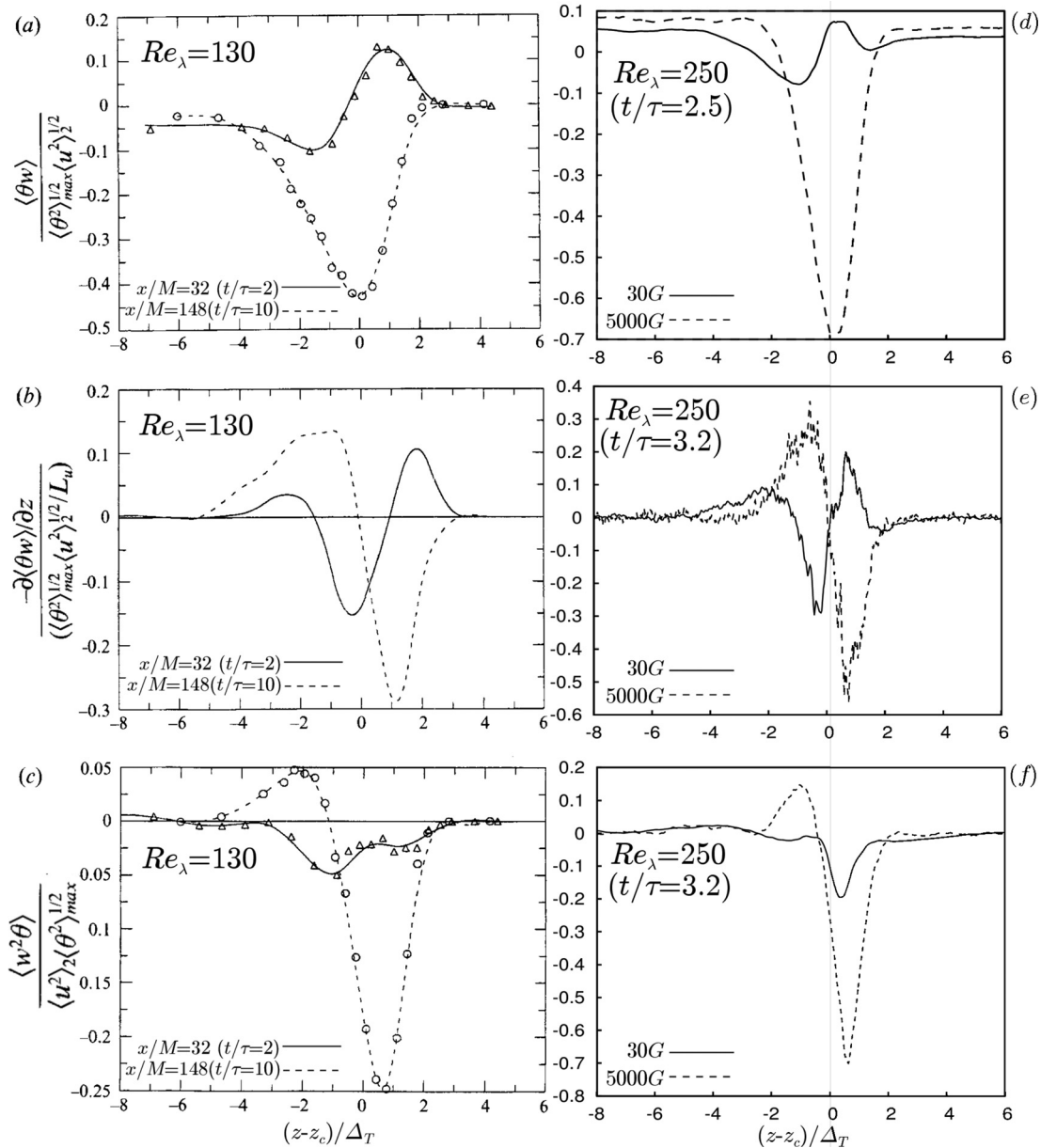


FIG. 9. Comparison of the flow statistics between the Jayesh and Z. Warhaft laboratory experiment [“Turbulent penetration of a thermally stratified interfacial layer in a wind-tunnel,” *J. Fluid Mech.* 277, 23–54 (1994)] (left column, spatial evolution) and the present numerical experiment (right column, temporal evolution). In their experiment, Jayesh and Warhaft considered a turbulent mixing between two regions with different kinetic energies and temperatures (see Fig. 2). The velocity fluctuations were generated by forcing a flow into grids of different mesh sizes. Jayesh and Warhaft’s data refer to $Ri = 0.8$ ($x/M = 32$, dashed line) and $Ri = 63$ ($x/M = 148$, solid line). By using a Taylor transformation, it is possible to see that $x/M = 32$ corresponds to a 2 timescale long temporal evolution while $x/M = 148$ corresponds to a 10 timescale long temporal evolution. The flows simulated in this work refer to $Ri = 0.11$ (30 G case, dashed line) and to $Ri = 18.2$ (5000 G case, solid line). In panel (d), $t/\tau = 2.5$, while in panels (e) and (f), $t/\tau = 3.2$. Panels (a) and (d): temperature flow. Panels (b) and (e): derivative normal to the mixing of the temperature flux. Panels (c) and (f): the temperature fluctuation flux (correlation between the second-order moment of the velocity fluctuation across the layer and the temperature fluctuation).

peak sublayer, and < 1 in the high-energy region, see panel (e) in the same figure.

It is worth analyzing these “loss” or “gain” variations with reference to the neutral case of $Fr^2 = 65.4$. We can define the following relative kinetic energy variation:

$$\mathcal{E} = \frac{E_{\text{mix}} - E_{\text{mix}, Fr^2=65.4}}{E_{\text{mix}} + E_{\text{mix}, Fr^2=65.4}}, \quad (10)$$

where E_{mix} and $E_{\text{mix}, Fr^2=65.4}$ are the kinetic energies within the mixing layer. This variation is obtained by integrating over thickness Δ_χ ,

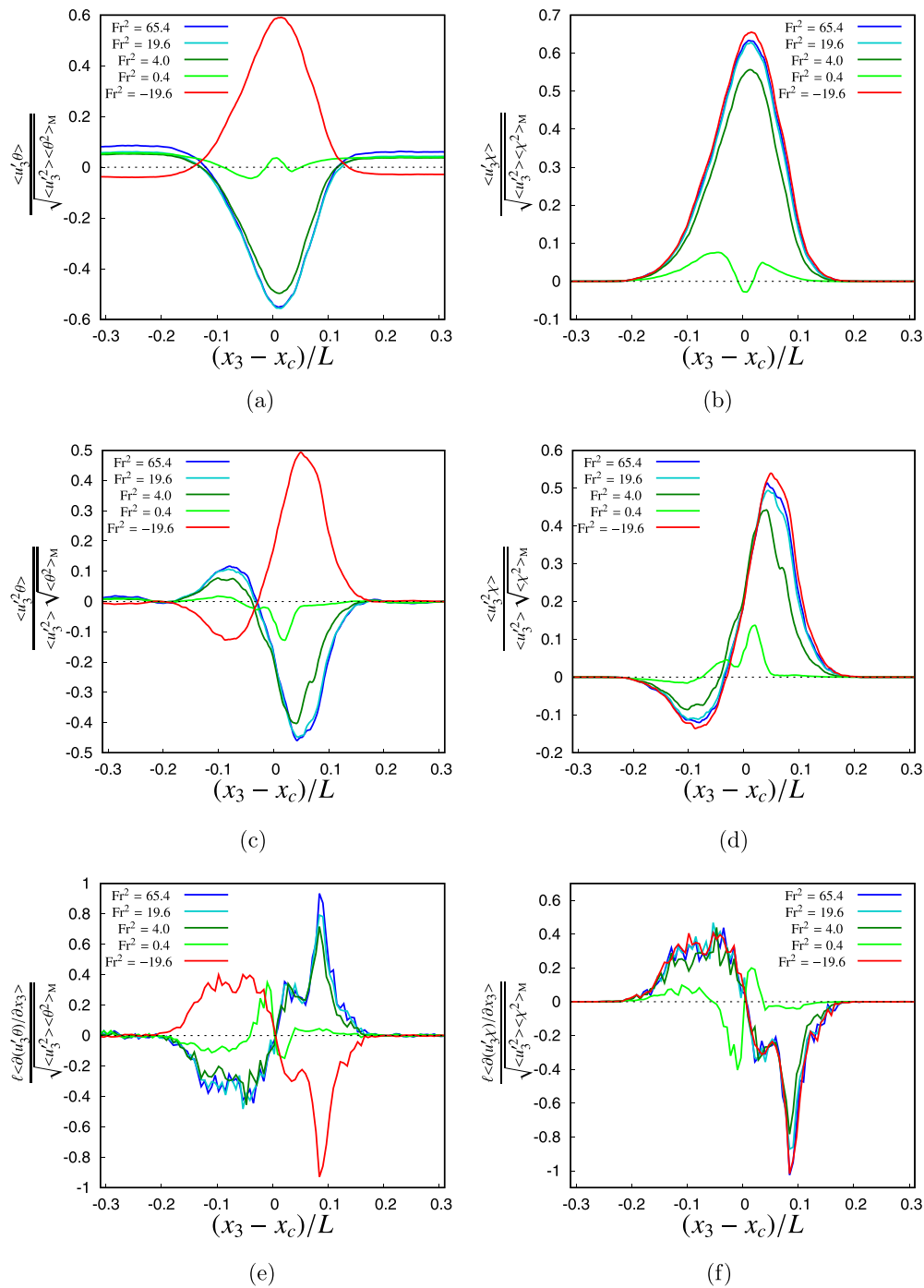


FIG. 10. Comparison across the interface of the normalized plane averages of the heat (active scalar) and vapor (passive scalar) flux profiles [panels (a) and (b)], of their fluxes of $u_3^2 \theta$ and $u_3^2 \chi$ [panels (c) and (d)], and of their vertical derivatives [panels (e) and (f)] for different levels of stratification at $t/\tau = 3$.

which is conveniently defined on the passive scalar distribution. In fact, the complex behavior of the kinetic energy profiles makes it difficult to provide an unambiguous definition of the layer thickness. The definition of Δ_χ is given by

$$\delta_\chi(t) = x_{\text{top}}(t) - x_{\text{bot}}(t), \quad (11)$$

where x_{top} and x_{bot} are the vertical locations in which the mean scalar concentrations are equal to 0.25 and 0.75, respectively,

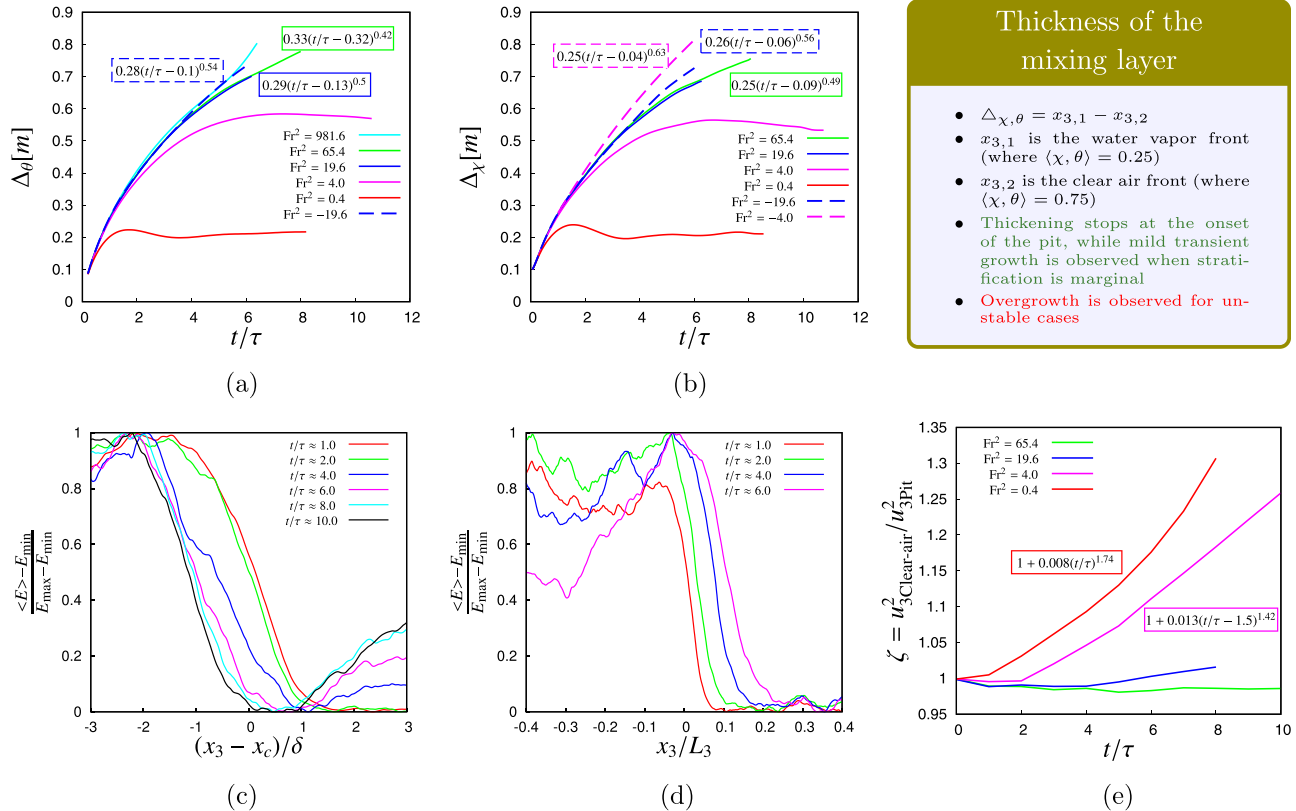


FIG. 11. Mixing layer thicknesses. (a) temperature and (b) passive scalar vapor. Distribution of the normalized kinetic energy at different time instants for $Fr^2 = 4.0$ (c) and $Fr^2 = -4.0$ (d). E_{min} , E_{max} , minimum, and maximum kinetic energy inside the mixing layer. The clear-air top region in panel (c) (right part of the plot) initially shows a value of around 0. Panel (d), in this case, the clear-air low-energy region always shows a value of around 0. The temporal reduction in the high-energy cloudy region highlights the formation of a peak, which remains in the very center of the mixing. (e) Time evolution of the pit width with Fr^2 . The pit onset starts at around $t/\tau = 2$, and it is clearly visible beyond $t/\tau = 4$, when the layer portion with normalized energy close to 0 is located in the $0 - 1$ range of $(x_3 - x_c)/\delta$.

$$\langle \chi \rangle(x_{top}, t) = 0.25, \langle \chi \rangle(x_{bot}, t) = 0.75,$$

see Fig. 11(b). However, it should be noted that, in the absence of any stratification, the thicknesses of the algebraic growth of both the passive scalar and the kinetic energy have a common exponent, see Fig. 6 in Ref. 25 and also Refs. 15 and 35.

The time evolution of \mathcal{E} is shown in Fig. 12. The relative energy variation in the presence of unstable stratification increases in time with an algebraic trend; the exponents increase as the stratification increases—1.84 for $Fr^2 = -19.6$ and 2.14 for $Fr^2 = -4.0$. The situation is more complex in stable cases. An initial transition phase can be observed, where \mathcal{E} is almost constant. There is then an algebraic decay, with lower exponents than 1. It should be noted that the initial transition is not present in the case of a very strong stable stratification ($Fr^2 = 0.4$).

We define the pit sublayer as the region where the kinetic energy (averaged in the $x_1 - x_2$ planes) is lower than 80% of the mean energy inside the low-energy clear region. The intensity variation of the energy pit sublayer in time is represented in Fig. 11(d). After the initial transition, the pit width almost linearly grows in time. This is in good agreement with the hull length growth found in a stratified Rayleigh–Taylor instability simulation by³⁶ and, at least qualitatively,

with the temporal evolution of the downdraught penetration length in buoyancy reversal in cloud tops.³⁷

It can be seen, from Figs. 11(a) and 11(b), that the thickness of the mixing layer is still growing during pit formation. Only after a couple of timescales beyond the pit onset does the growth stop, and it is then followed by small oscillations around an asymptotic value. A different behavior is observed for unstable stratifications. In these cases, the generation of the energy peak enhances the mixing by providing a faster thickening of the layer, with greater exponents, that is, -0.63 for $Fr^2 = -4.0$, 0.54 – 0.56 for $Fr^2 = -19.6$ —than the neutral case for which the exponent is 0.42 – 0.49 .

1. Transport and Entrainment

The entrainment of external fluid inside mixing layers is an important inertial aspect of interface dynamics, and such an entrainment can range from those of the typical turbulent–nonturbulent interfaces of boundary layers, jets, hyperbolic tangent shear layers, and wakes, to those of the shear-free interfaces observed in planet atmospheres and astrophysical clouds. Only downward velocity fluctuations can transport clear air into a vapor cloud in any plane parallel to the interface, in the absence of a mean velocity. Their presence can be

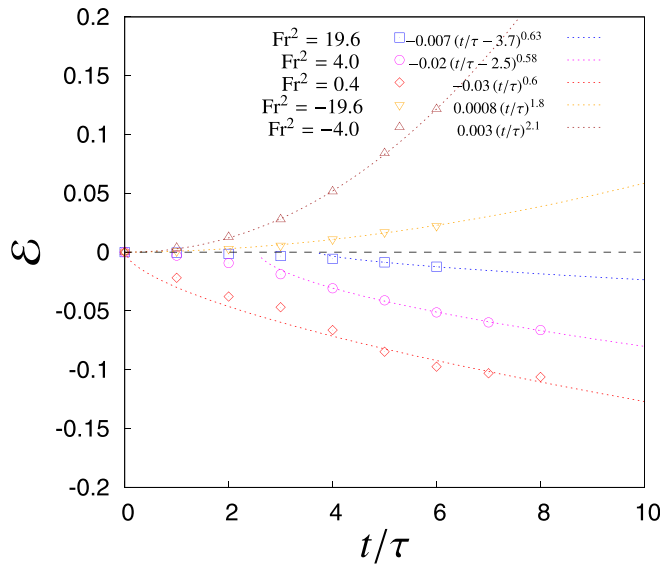


FIG. 12. Time evolution of the relative turbulent energy variation \mathcal{E} , which is defined as the difference in the kinetic energy inside the mixing layer from the neutral case $Fr^2 = 65.4$ [see Eq. (10)]. \mathcal{E} follows an algebraic trend. In stable cases, after an initial transition that can last four eddy-turnover times, a decay of the relative energy is observed inside the mixing, with lower exponents than 1. In unstable cases, the exponents are greater than 1 and the initial transition is absent.

highlighted by a marker function, ψ , that is, equal to 1 when u_3 is negative, and 0 otherwise. The entrainment mean value outside the mixing region is approximately constant and equal to 0.5 ± 0.01 , a value which would be observed for homogeneous and isotropic turbulence. Instead, the deviation inside the mixing layer is greater (up to $\sim \pm 0.05$), with a spatial distribution and a temporal evolution, which somehow follow the ones observed in the third-order moment of the

velocity, see Fig. 6. Figure 13(a) shows the vertical derivative of the downward vapor flux when $Fr = 2.05$. The downward flux reduces as the flow evolves and its derivative, which represents the net variation of $1 - \chi$ at a given instant, rapidly tends to zero inside the vapor cloud; this implies that the entrainment of clear air is confined to a thin interfacial layer.

Since the entrainment of clear air is responsible for the growth of a cloud, it can be defined, and thus quantified, by considering the velocity with which the cloud expands. The velocity $w_e = dz/dt$, where $z = \langle x_{3,i} \rangle$, is the mean vertical position of the cloud top interface and is here defined as the location where the mean vapor concentration χ is equal to 25%. The time-variation of z has often been used as a parameter to measure the entrainment rate, see for instance.^{12,13}

Figure 13(b) shows the time evolution of w_e for different perturbation stratification levels. In the presence of a quasi-neutral stratification, w_e gradually decreases, with an algebraic trend, which is related to the natural decay of the turbulent kinetic energy. However, when a stable, strong stratification is present, the decay of w_e is much faster and the entrainment vanishes after a few time scales. It should be noted that such an entrainment is related to the mixing thickness (see Fig. 11), since the presence of the kinetic energy pit reduces the transport efficiency. On the other hand, in the case of unstable stratification, the presence of a kinetic energy peak enhances the mixing, and the entrainment speed, therefore, more slowly decays.

The fact that a different level of entrainment is related to different efficiencies of the transport of any physical quantity can also be appreciated by observing the kinetic energy flux shown in Fig. 14, and the passive scalar flux shown in Fig. 10. Compared to a neutral case, the presence of stable or unstable stratification produces an initial reduction/increase in the energy flux, respectively, with a maximum flux always positioned around $x_3/\delta = 1$, see Fig. 14. In the case of stable stratification, the flux decreases until it reaches a very low value. The formation of two fluxes can then be observed, according to the experimental results of.²⁸ The first one, which is located below the pit at

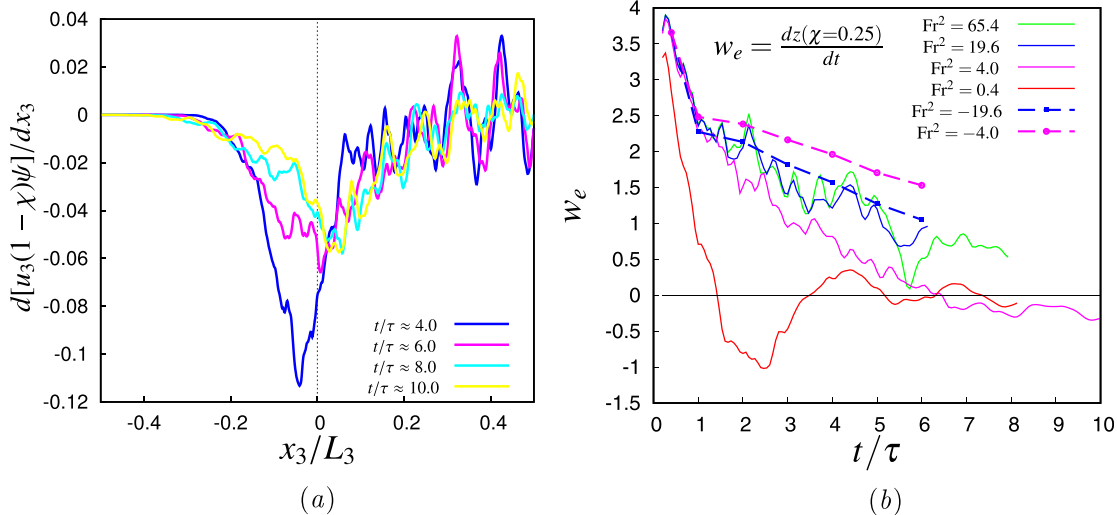


FIG. 13. Panel (a): vertical variation of the mean flux of the vapor in the cloud; the marker function ψ only takes into account the spatial points where the velocity is directed downward. Panel (b): time evolution of the mean entrainment velocity fluctuation, w_e , which is normalized with the high kinetic energy E_1 root mean square. w_e is calculated in the horizontal plane where $\chi = 0.25$. Both stable interfaces (solid lines) and unstable interfaces (dotted lines) are represented here.

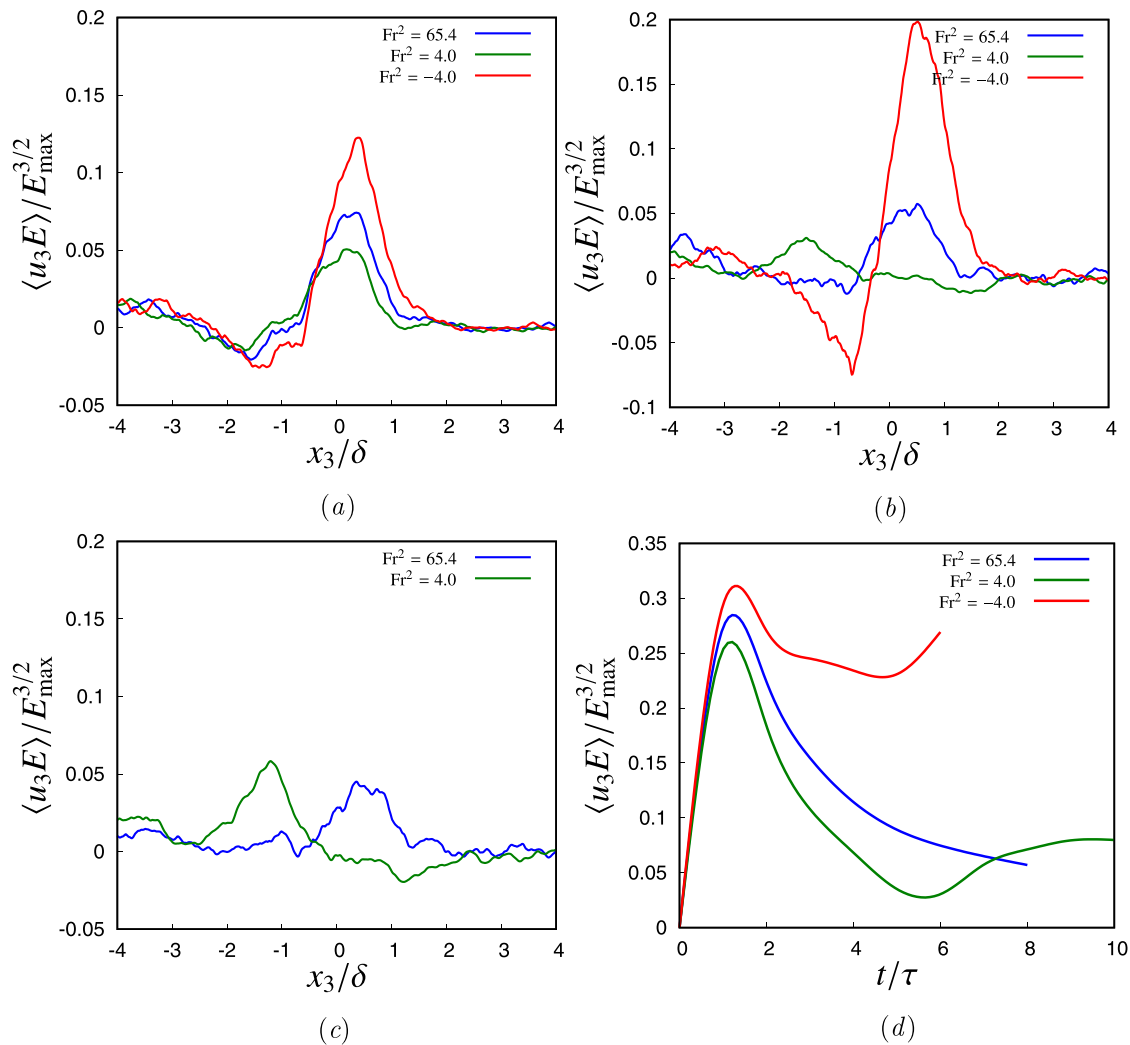


FIG. 14. Panels (a)–(c): kinetic energy fluxes along the vertical direction x_3 , averages of the horizontal planes $x_1 - x_2$, after 4, 6, and 8 timescales, respectively. It should be noted that, for the unstable simulations, it is not possible to reach 8 timescales for the computational stability problems self-generated by the physical condition of the flow. Data from simulations considering different initial squared Froude's numbers normalized on the mean kinetic energy of the high-energy vapor cloud region. Panel d shows the temporal trend of the maximum normalized kinetic energy flux.

$x_3/\delta = -1$, is positive (upward flux), and the second one, which is located above the pit, in between $x_3/\delta = 1$ – 3 , is negative (downward flux)—see Figs. 11(c) and 14(c). A minimum value of 0.025 for the stable case with $Fr^2 = 4.0$ can be noted for the time evolution of the integral value of the flux in the layer, see, Fig. 11, panel (d). The ratio between the two fluxes is around 0.25 for $Fr^2 = 4.0$. No mean flux is present in between these two fluxes: this means that the energy tends to accumulate at the pit edge without being able to cross it, thus limiting the mixing thickness to a fixed width. In particular, if panel (a) in Fig. 17 of JW is compared with the temporal sequence of panels (a)–(c) in our Fig. 14, it can be seen that both show a reduction and inversion of the kinetic energy flow in the case of large stable stratification. The trend in panels (b) and (c) in Fig. 17 in JW also shows a substantial agreement between the derivative of the energy flow along the

vertical and the trend of our flow for $Fr^2 = 65.4$ and 4.0 at the end of the transient. In the case of unstable stratification, although the maximum flux located at $x_3/\delta = 1$ keeps growing, the formation of a secondary negative flux, located near $x_3/\delta = -1$, can be observed. In this case, the energy is spread from the peak sublayer to the external homogeneous vapor cloud region, thereby promoting the thickening of mixing layer.

A similar behavior characterizes the passive scalar flux, which is shown in the top panel on the right in Fig. 10. The unstable stratification enhances the flux, which becomes increasingly important, in comparison with the scalar variance. However, no particular changes in the spatial trend can be seen: the flux is always directed toward the upper region. On the other hand, important differences can be seen for the case of stable stratification: after an initial damping, the flux

becomes zero or even negative in the center of the mixing layer (see $Fr^2 = 0.4$ in the above-cited panel), which agrees with the experimental results of Ref. 28. In particular, the flux derivative along with the vertical direction can be noticed in the bottom panel on the right. A positive derivative can be interpreted as the entrainment of clear air (the passive scalar moves away), while a negative derivative implies a detrainment of clear air (the passive scalar moves into the layer).³⁸ In the case of neutral (and unstable) stratification, the mixing moves the scalar upward, where it is not initially present. We observe two sublayers (dark yellow solid line, $Fr^2 = 0.4$) for a stable stratification with a positive derivative that surrounds one sublayer with a negative derivative: the scalar is thus retained within the mixing layer.

A reduction in communication between the two regions external to the mixing layer can also be observed by looking at an instantaneous three-dimensional visualization of the flow streamlines, see Fig. 15, where three stratification cases are shown as follows: neutral $Fr^2 = 65.4$, stable $Fr^2 = 4.0$, and unstable $Fr^2 = -4.0$.

The streamlines are computed for fluid particles initially placed at a distance of $2\delta_0$ above (red) and below (blue) the center of the mixing layer, and are visualized at 6 initial eddy-turnover times. It is possible to observe that, in the neutral case, panel (b), streamlines from the upper side can cross the interface to reach the bottom region, and vice versa. This does not happen in the presence of stable stratification, panel (a); in this case, crossing of the interface becomes increasingly rare, and almost all the particles located on one side of the interface remain there. On the contrary, in the presence of unstable stratification, panel (c), mixing is enhanced and the streamlines more frequently cross the layer.

2. Anisotropy and dissipation

In the present system, the anisotropy is first set by the initial velocity fluctuation condition, which introduces a gradient of kinetic energy, which, in turn, induces the flux of momentum and kinetic

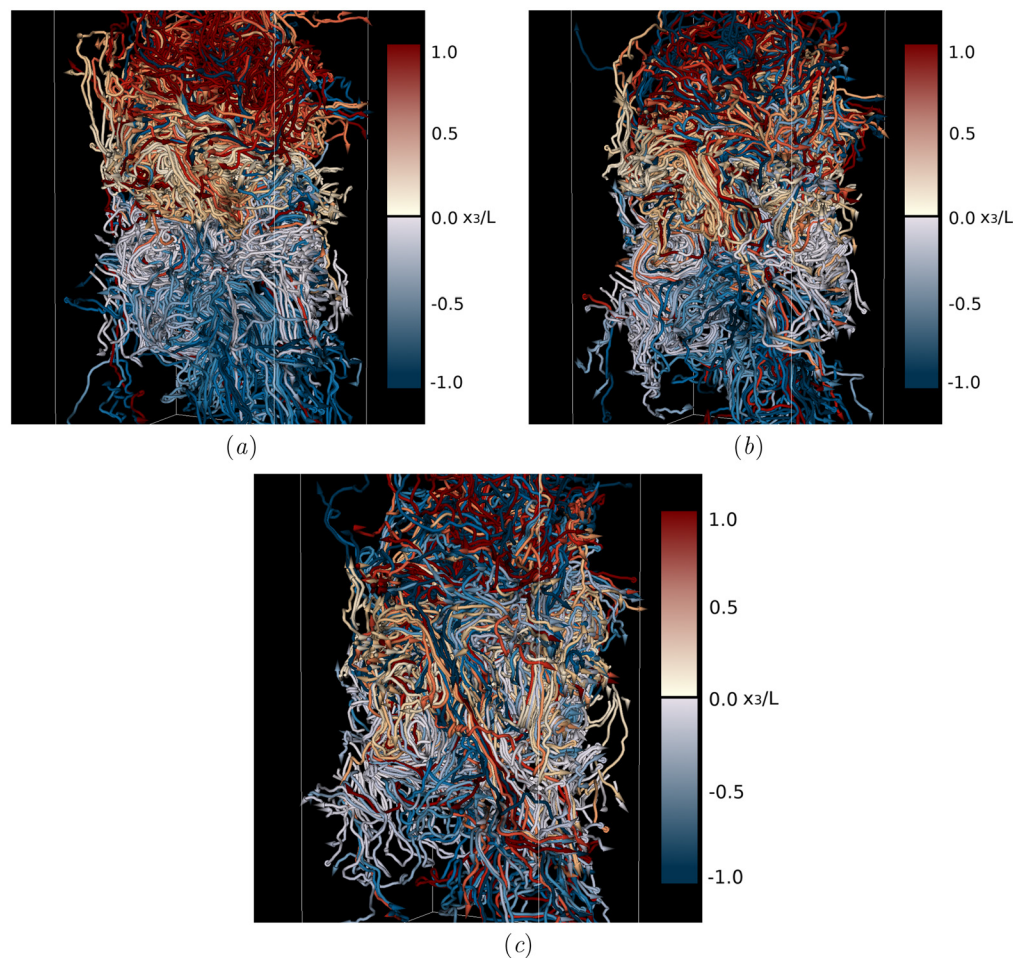


FIG. 15. Streamlines after 6 timescales for different stratification levels—(a) $Fr^2 = 4.0$ highly stable, (b) $Fr^2 = 65.4$ negligible stratification, and (c) $Fr^2 = -4.0$ highly unstable. The starting position of each streamline is placed at a fixed distance from above (yellow/red tubes) and below (cyan/blue tubes) the center of the interface. In panel (b), where the buoyancy forces are negligible, streamlines from the upper side can cross the interface to reach the lower region, and vice versa. Instead, in panel (a), where stable stratification effects are relevant, crossing of the interface becomes increasingly rare: what is located on one side of the interface tends to stay there, and the mixing process is damped. Finally, in the case of unstable stratification shown in panel (c), the mixture of red and blue lines is enhanced, which means that the streamlines more frequently cross the interface.

energy. Second, the temporal evolution of the vertical velocity component feels the effect of the buoyancy stable/unstable forces, which damp/enhance the transport. By considering the relative weight of the energy associated with the vertical velocity fluctuation, with respect to the other components,³⁹ the large-scale anisotropy is represented by the ratio

$$B_3 = \frac{\langle u_3 u_3 \rangle}{\langle u_k u_k \rangle} - \frac{1}{3}.$$

Figure 16 shows the behavior of the B_3 ratio along the vertical direction (panel a) and the time evolution of its peak value in time. Anisotropy is present on a large scale for a neutral stratification condition, but is limited, with a maximum deviation of 5%. Anisotropy becomes very intense in the presence of stratification. It is, in particular, possible to observe that the vertical fluctuation undergoes a large dumping under stable stratification conditions ($\langle u_3^2 \rangle < \langle u_{1,2}^2 \rangle$) and, vice versa, an intense growth under unstable conditions ($\langle u_3^2 \rangle > \langle u_{1,2}^2 \rangle$). These differences are responsible for the different behaviors of the transport and fluxes observed in the previous sections. It is also possible to observe, in Fig. 16(a), that the variation concerns the global mixing layer (and not only the previously introduced pit/peak sublayers of the kinetic energy). In fact, together with the formation of such sublayers, a concomitant shift in the main energy gradient is also observed. This fact confirms the observation that the time evolution of a cloud during mixing is somewhat sensitive to large scales²¹ in concomitance with the important effects directly induced on the drop size distribution and supersaturation fluctuation by the small scale.⁹

As for the small-scale anisotropy of the flow, it should be mentioned that it is accurately represented by the higher moments of the first-order longitudinal derivative of the velocity components.⁴⁰ It is well known that HIT departs from Gaussianity at small scales, and the longitudinal derivative skewness, $S(\partial u_i / \partial x_i)$, is almost equal to -0.5 ± 0.1 , with a slight dependency on the Reynolds number.⁴⁰ In previous works,^{16,27} it was found that, in the presence of a mixing layer due to a mean kinetic energy gradient, at Taylor Reynolds numbers of

between 45 and 150, $S(\partial u_i / \partial x_i)$ not only shows that there is a significant departure of the longitudinal velocity derivative moments from the values found in homogeneous and isotropic turbulence but also that the variation in skewness has the opposite sign for the components across the mixing layer and parallel to it. The anisotropy induced by the presence of a kinetic energy gradient also has a very different pattern from the one generated by homogeneous shear. The transversal derivative moments in the mixing are in fact found to be very small, which highlights that the smallness of the transversal moments is not a sufficient condition for isotropy. In addition to the Reynolds number, the level of anisotropy depends on the energy gradient, see Ref. 16.

The presence of buoyancy forces does not directly influence the tilting/stretching of the vortex filament. Let us consider the vorticity equation, obtained as the curl of Eq. (2),

$$\frac{\partial \omega}{\partial t} + (\mathbf{u} \cdot \nabla) \omega = (\omega \cdot \nabla) \mathbf{u} + (\mathbf{u} \cdot \nabla) \omega + \nu \nabla \times \nabla^2 \mathbf{u} + \alpha \nabla \times (\mathbf{g} \theta), \quad (12)$$

where the compressibility stretching and the baroclinic terms have been neglected as a result of the incompressibility and Boussinesq approximations. By considering that the buoyancy term is a vector that lies along the vertical direction, its curl has horizontal components, which depend on the derivative along the direction parallel to the mixing,

$$\alpha \nabla \times (\mathbf{g} \theta) = \alpha \nabla \times \begin{pmatrix} 0 \\ 0 \\ g\theta \end{pmatrix} = \alpha g \begin{pmatrix} \partial \theta / \partial x_2 \\ \partial \theta / \partial x_1 \\ 0 \end{pmatrix}. \quad (13)$$

It is possible to see that, if a mean variation of θ only occurs along the vertical, there will not be a mean contribution of buoyancy to the vorticity balance. Thus, in HIT, the presence of stratification does not influence small-scale anisotropy. However, this is not true inside a mixing layer. Figures 17 and 18 show that the presence of stratification modifies the behavior of the skewness and kurtosis of the longitudinal derivatives. Mild stratification does not affect small-scale anisotropy:

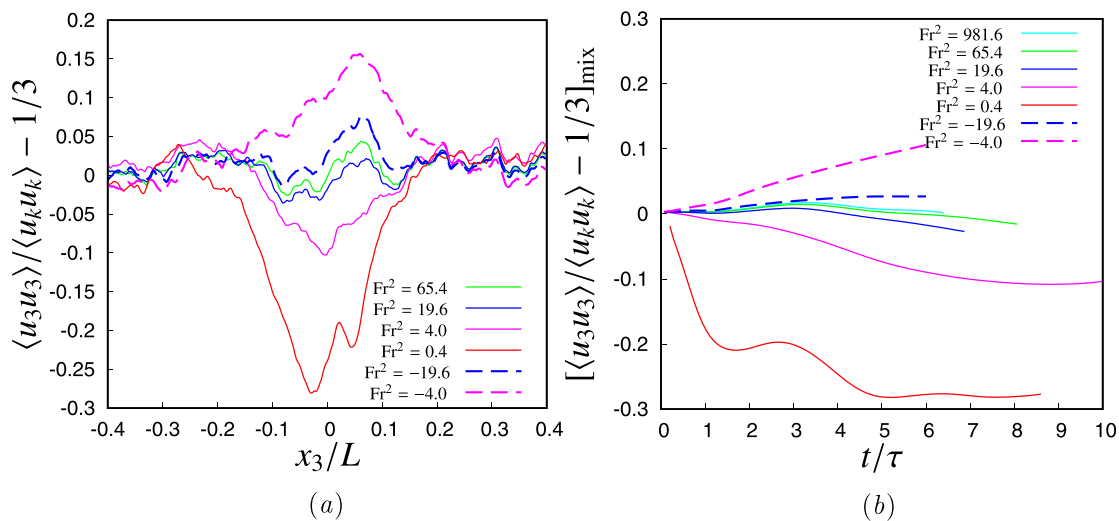


FIG. 16. Anisotropy of the turbulence on large scales. (a) B_3 ratio along the vertical direction obtained by varying the Fr^2 number. (b) Temporal evolution of the B_3 peak value.

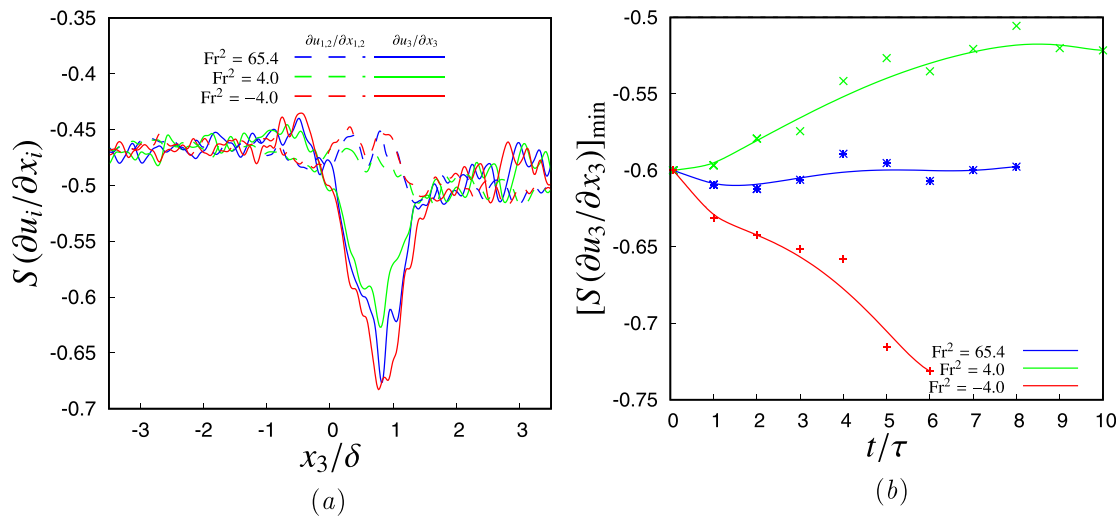


FIG. 17. Anisotropy of the skewness of the longitudinal derivatives. (a) Spatial distribution of the skewness of the longitudinal derivatives normal to the mixing surface (solid lines) and parallel to the mixing interface (dashed line). (b) Evolution of the mean peak value of the longitudinal derivative crosswise direction of the mixing layer, and the spatial location is close to $x_3/\delta \approx 1$. The symbols represent discrete values averaged over 11 adjacent computational planes, parallel to the layer, while the solid lines represent their spline interpolations.

the skewness of $\partial u_3 / \partial x_3$ tends to an asymptotic value of -0.63 ± 0.02 , as expected, for $Re_\lambda \approx 200 - 250$.^{16,41} In the case of stable stratification, the skewness of all the longitudinal derivatives tends to the isotropic value of 0.52, while it tends to diverge in the case of unstable stratification $S(\partial u_3 / \partial x_3)$, reaching values as low as -0.75 at $Fr^2 = -4.0$, with an overgrowth of 30%.

In the case of stable stratification, as soon as the energy pit appears, the mixing process decreases and the small-scale anisotropy sublayer tends to disappear, as can be seen in Fig. 17(b), since the longitudinal derivative in the direction across the mixing is gradually

reaching the typical value of homogeneous isotropic fields. Thus, the behavior of the system is similar to when the energy gradient is not present—which would seem to indicate that the exchange of information between the two outer regions is blocked. On the contrary, mixing is enhanced in the case of unstable stratification, and the layer becomes even more anisotropic for small scales and acts as if the energy gradient is larger. According to the results of Ref. 16, derivatives along a homogeneous direction do not show peaks in the center of the mixing layer, and it should be recalled that Re_λ is 250 in the present cases.

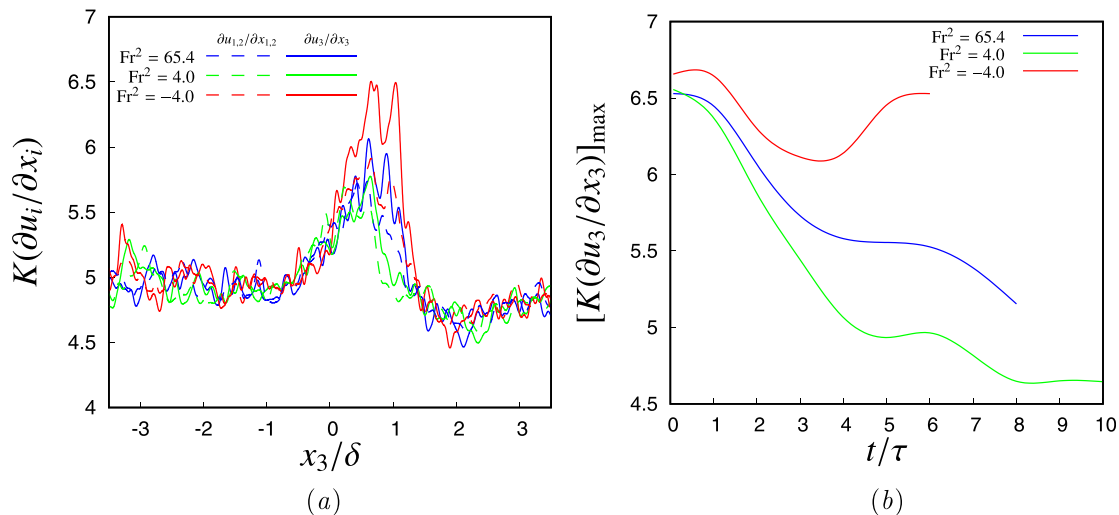


FIG. 18. Anisotropy of the kurtosis of the longitudinal derivatives. (a) Spatial distribution of the kurtosis of the longitudinal derivatives normal to the mixing surface (solid lines) and parallel to the mixing interface (dashed line). (b) Evolution of the mean peak value of the longitudinal derivative crosswise direction of the mixing layer, and the spatial location is close to $x_3/\delta \approx 1$.

Another interesting feature concerning anisotropy can be noted by observing the spectra at the edges of the inertial range in the presence of stratification. This feature can be evaluated by comparing the one-dimensional spectra of each velocity component inside the mixing region with the neutral case. To achieve this, we computed spectra $\hat{u}_i(k, x_3)$ as the average of the transforms along each of the two homogeneous directions, that is,

$$\hat{u}_i(k, x_3) = 0.5\langle \hat{u}_i(k_1, x_2, x_3) \rangle + 0.5\langle \hat{u}_i(x_1, k_2, x_3) \rangle, \quad k = k_1 = k_2, \quad (14)$$

where the average operator $\langle \cdot \rangle$ acts along the homogeneous direction in which the transform is not carried out. The obtained spectra are then compared with the neutral case, $Fr^2 = 65.4$, by considering the relative variation

$$\frac{\|\hat{u}_i^{Fr^2=\dots} - \hat{u}_i^{Fr^2=65.4}\|}{\|\hat{u}_i^{Fr^2=\dots} + \hat{u}_i^{Fr^2=65.4}\|}.$$

The results of such a comparison are shown in Fig. 19 for the stable case, $Fr^2 = 4.0$ [panels (a) and (c)], and the unstable case, $Fr^2 = -4.0$ [panels (b) and (d)]. The first observation that can be made concerns the different behavior of the vertical velocity fluctuation from the other two components. As can be seen, stratification directly acts on the larger scale of the vertical motion, generating a relative deviation from the neutral case. Such a variation is negative (less energy in vertical motion) in the presence of a stable stratification and positive (more energy) in unstable situations, in agreement with what has been observed for large-scale anisotropy. As the mixing evolves, these effects are transmitted to smaller scales through the inertial cascade, until the

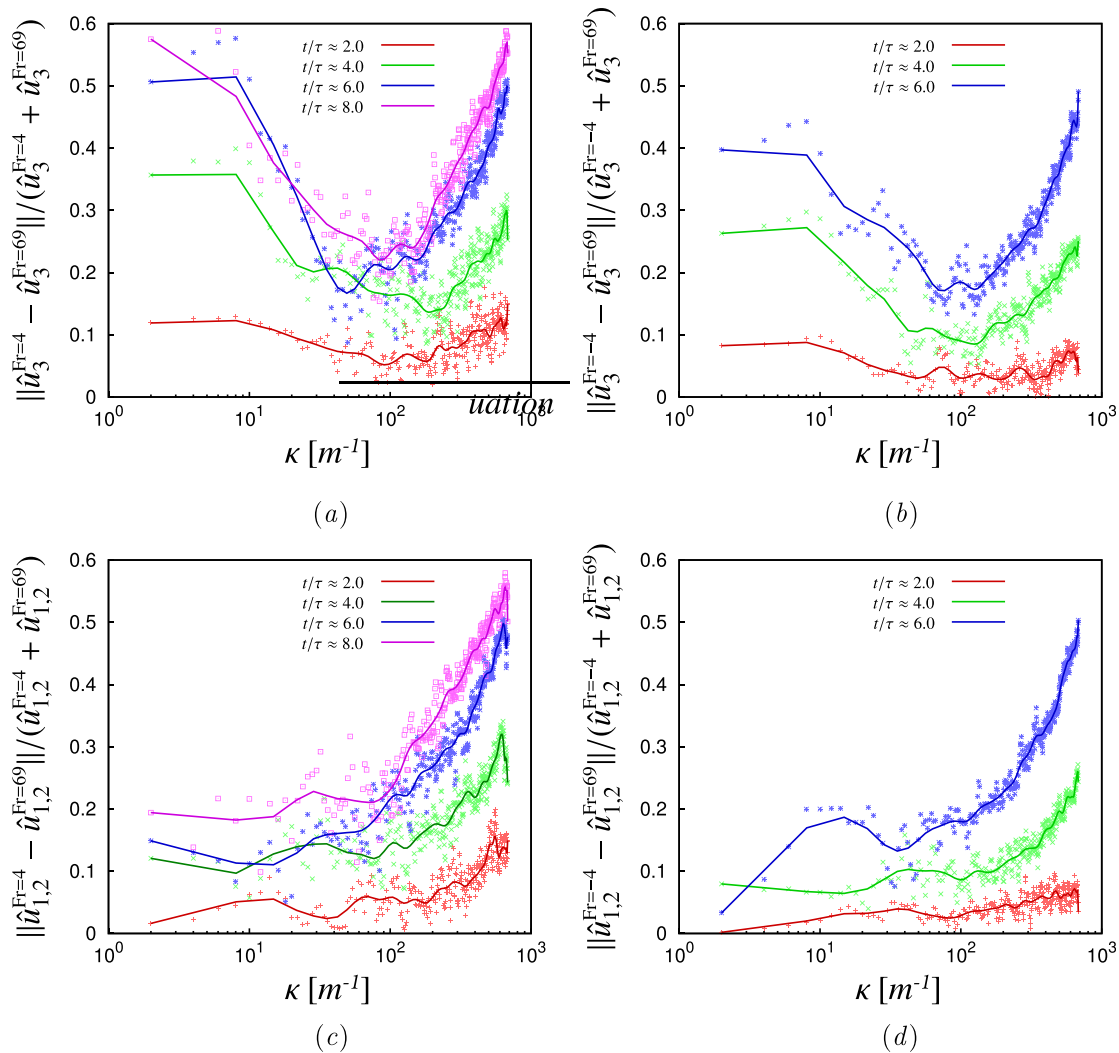


FIG. 19. One-dimensional velocity spectra along with homogeneous directions. Unlike the neutral case, $Fr^2 = 65.4$, panels (a) and (b) show the effects on the vertical velocity fluctuations in the presence of stable [(a), $Fr^2 = 4.0$] and unstable (b), $Fr^2 = -4.0$] stratifications, respectively. Panels (c) and (d) show the effects on the other two velocity components. The spectra were computed inside the mixing layer, at $x_3/\delta \approx 0.8$. Here, $\hat{u}_{1,2}$ is the arithmetic average of the one-dimensional spectra computed along with the directions parallel to the mixing layer. The symbols represent the computation of discrete spectra, while the solid lines represent their Bézier interpolation.

dissipative range is reached, with the consequent effect of enhancing/dampening of the dissipation rate for stable/unstable stratification, respectively. The stratification effects in this scale range are widespread in all the velocity components: as a consequence, absolute small-scale differences (and, therefore, small-scale anisotropy) are dumped in the presence of stable stratification and enhanced in unstable cases.

We observed that Kolmogorov $-5/3$ scaling is present over the whole domain. The inertial range is rather narrow, as it extends for about one decade. See Figs. 20(a) and 20(b), where energy spectra are shown at $t/\tau > 6$ inside both the unsaturated cloud and the interfacial layer. The normalized kinetic energy spectra are somewhat similar along the vertical direction, with small deviations, due to the different local Reynolds numbers. These spectra are also quasi-self-similar in time, and the main difference is represented by a reduction in the extension of the inertial range due to the temporal growth of the Kolmogorov scale and of the dissipative range. A symmetrical variation has been observed in the inertial range, with respect to the non-stratified condition, on the spectral indices of the velocity spectra: -1.99 , when $Fr^2 = 4.0$, and -1.35 , and when $Fr^2 = -4.0$. The inertial range of the passive scalar power spectra shows an index of about -1.45 inside the cloud portion and of about -1.56 inside the mixing layer. These values slowly decrease over time.

The dissipation rate is computed over the whole domain using the general definition (see Ref. 42)

$$\varepsilon = \frac{1}{2} \nu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)^2. \quad (15)$$

Figure 21 shows the plot of the normalized turbulent dissipation rate C_ε , which is defined as

$$C_\varepsilon(x_3) = \frac{\langle \varepsilon \rangle \langle \ell \rangle}{\langle E \rangle^{3/2}},$$

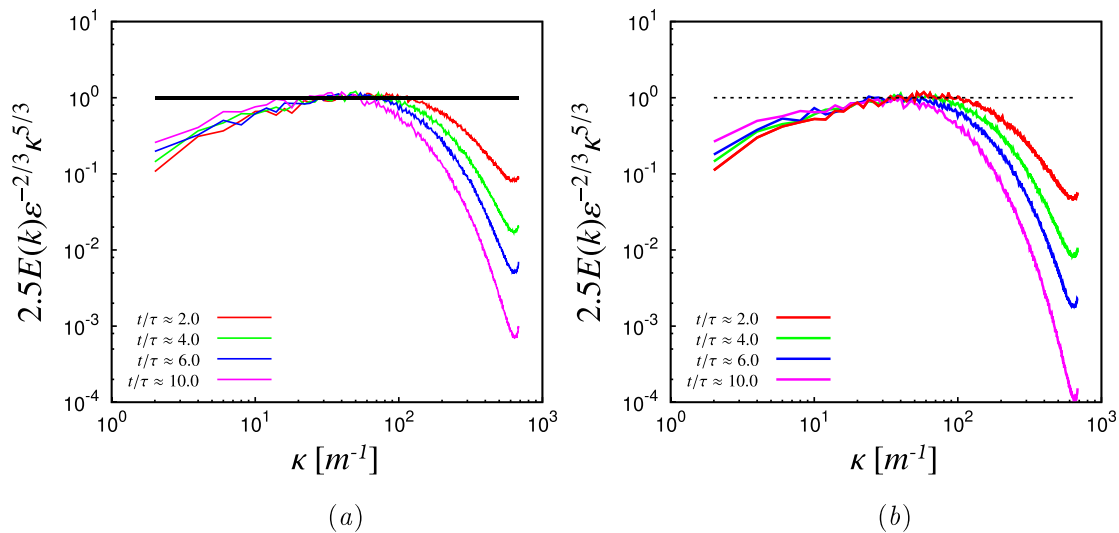


FIG. 20. Kinetic energy spectra at different instants for the case with $Fr^2 = 4.2$. Spectra are compensated according to the Obukhov–Corrsin normalization, in which $E(k) = 0.4\epsilon^{-2/3}k^{-5/3}$. Panel (a) shows the spectra in the high-energy region while panel (b) in the center of the mixing layer.

where the averages in the horizontal planes have been implemented. It can be observed that the normalized dissipation rate is initially almost constant in the transient and equal to 0.55 ± 0.05 , that is, the same value as the unstratified case. However, as the buoyancy becomes relevant, in the case of stable stratification, $Fr^2 = 4.0$, the formation of a dissipation “peak” can be observed inside the pit of kinetic energy, where C_ε reaches values as high as 0.9, that is, an increase of nearly 70%. On the other hand, in the case of unstable stratification, $Fr^2 = -4.0$, the dissipation decreases inside the sublayer by nearly 20%. Thus, dissipation is affected to a great extent by buoyancy.

IV. CONCLUDING REMARKS

The evolution of a freely decaying, shearless, and turbulent mixing layer hosting both air and a vapor phase, considered as a passive scalar phase, is obtained by coupling two homogeneous isotropic turbulent fields with different kinetic energies. A large range of Froude numbers ($Fr^2 \in [-19.6, 981.6]$) has been studied to evaluate the changes that take place in the mixing dynamics, due to both stable and unstable temperature conditions.

Our numerical simulations have shown that both stable and unstable stratifications modify the dynamics and transport characteristics of a shear-free turbulent layer. First, the formation of a sublayer inside the mixing region is observed: (i) a pit of kinetic energy under a stable condition, a sort of intense decay overshoot that is characterized by a lower level of energy than the external regions; (ii) the formation of a peak of kinetic energy under unstable stratification conditions, where the turbulent energy becomes higher than in the external regions (15% larger at $Fr^2 = -4.0$). The temporal scaling law of the energy variation inside the mixing region has been quantified. The exponent depends on the stratification intensity. It reaches a value of 2.1 at $Fr^2 = -4.0$, which is about four times larger than the exponent determined at $Fr^2 = 4.0$. Stable stratification almost suppresses vertical motion, since any fluctuations within it are inhibited by buoyancy forces. In such a condition, an increased anisotropy is observed for the

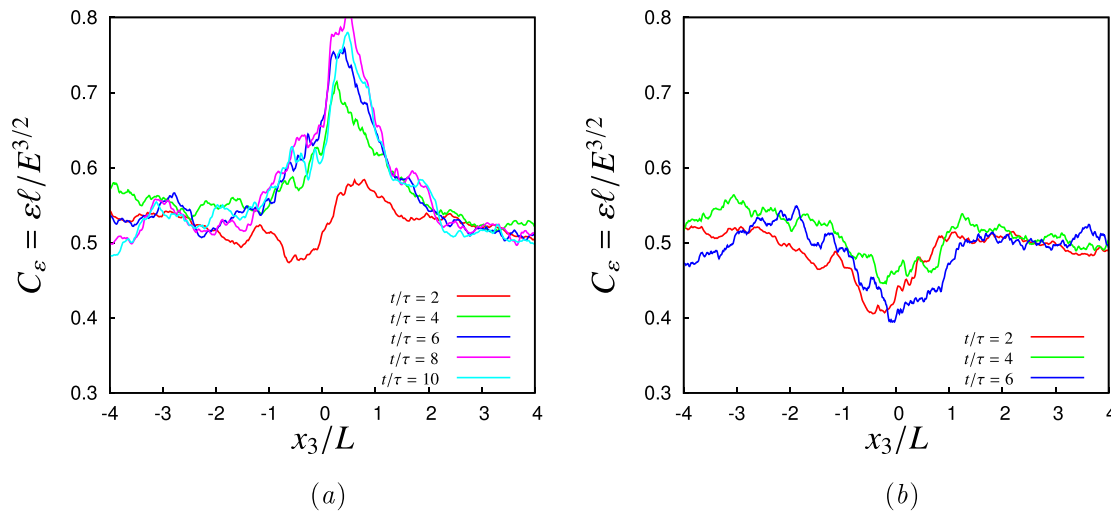


FIG. 21. (a) and (b) Normalized plane-averaged dissipation $C_\epsilon = \{\epsilon\}l/\{E\}^{3/2}$ for $Fr^2 = 4.0$ and $Fr^2 = -4.0$, respectively. Values outside the mixing layer are close to 0.5, as in the case of isotropic homogeneous turbulence.⁴³ In stable cases, the normalized dissipation shows a maximum at the kinetic energy pit; in an unstable case, the dissipation shows a minimum at the energy peak.

large-scale structures, compared to the neutral case. In fact, the energy associated with vertical fluctuations gradually becomes smaller than the other components. On the other hand, vertical fluctuations, under unstable conditions, amplify with respect to the horizontal components.

Turbulence diffusion becomes damped in the presence of a stable stratification, as do intermittency, kinetic energy, passive scalar transport, and clear-air entrainment. Entrainment almost vanishes when the Froude square number becomes lower than 1. A detrainment phase, lasting from 1.4 to 3.5 eddy-turnover time, is observed at $Fr^2 = 0.4$. On the other hand, unstable stratification enhances the mixing process.

The dissipation function increases to a great extent for stable perturbation conditions. An increase of 70% at $Fr^2 = 4.0$ has been observed here. Conversely, at $Fr^2 = -4.0$, a decrease of 2% has been observed. Log-normal probability density functions of the dissipation rate have resulted to be self-similar inside different layers across the mixing. This is a result that can be explained by considering that stratification has more effect on the energy associated with the vortical structures than on their morphology.

As far as small-scale anisotropy is concerned, it has been found that the presence of unstable stratification increases the differences in the statistical behavior between the longitudinal velocity derivatives. As a consequence, the compression of the fluid filaments normal to the interface is greater, due to the increased mixing intensity. Since the mixing process tends to vanish in stable cases, small-scale anisotropy also vanishes.

We have collected spectral information. The main observation concerns the velocity fields. By comparing the stratified spectral behavior with the unstratified behavior of the velocity fields, we have noted a substantial diversification in time for both low and high wave numbers for the vertical velocity fluctuations. Instead, for the horizontal components of the velocity fluctuation, differentiation is only clearly visible at the smallest scales, that is, for the highest wave numbers.

Looking ahead, we would like to conduct a simulation campaign on domains of a similar size to the size considered in this work, but including the aqueous liquid phase and the related collision and coalescence phenomena of water droplets, as has recently been done, albeit at a much smaller domain scale than the one considered here (Golshan *et al.*⁹ and Fossa *et al.*¹⁰). In particular, we would like to observe a longer time window, that is, a time corresponding to almost one minute of a three-phase (gas, vapor, and liquid) warm cloud instead of the few seconds of the present simulation.

However, it should be considered that droplet clustering introduces a further complexity to the structure of the clear air–cloud interface. In particular, the discontinuous distribution of droplets and droplet clusters in space means that different cores will require a very uneven computational effort at each time step, and this cannot be *a priori* predicted. In such a situation, where a physical modeling is still under evolution, it would be very difficult to force the code to a massively high level of parallelization. In fact, the shift from slab to pencil parallelization (which has already been achieved for the version of the code used in this work, where water droplets are not simulated) increases the time needed to exchange information between the cores by about eight times. This occurs because the amount of information exchanged by two adjacent cores is not homogeneous inside the computational domain, and, furthermore, it is likely that nonadjacent cores would also need to exchange information. Such a situation has a high probability of occurring over short time intervals, such as those that are comparable with a single computational time step, because turbulence hosts long-term phenomena, which can induce large droplet displacements, that is, droplet displacements to a domain portion in a core not adjacent to the core where the droplet departed from.

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AUTHORS DECLARATIONS

Conflicts of Interest

The authors have no conflicts to disclose.

Author Contributions

L. Gallana: Conceptualization (equal); Data curation (equal); Formal analysis (equal); Investigation (equal); Methodology (equal); Software (lead); Visualization (lead); Writing – original draft (supporting); Writing – review & editing (supporting). **S. Abdunabiev:** Data curation (equal); Investigation (equal); Software (equal); Visualization (equal); Writing – original draft (supporting); Writing – review & editing (supporting). **M. Golshan:** Investigation (equal); Writing – original draft (supporting); Writing – review & editing (supporting). **D. Tordella:** Conceptualization (lead); Data curation (lead); Formal analysis (lead); Funding acquisition (lead); Investigation (lead); Methodology (lead); Project administration (lead); Resources (lead); Software (supporting); Supervision (lead); Validation (lead); Visualization (equal); Writing – original draft (lead); Writing – review & editing (lead).

DATA AVAILABILITY

The data that support the findings of this study are available from the corresponding author upon reasonable request.

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