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Harmonic Pulse Testing for Well Performance Monitoring

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Abstract

Harmonic testing was developed as a form of well testing that can be applied during ongoing production or injection operations, as a pulsed signal is superimposed on the background pressure trend. Thus no interruption of well and reservoir production is needed before and during the test.

If the pulsed pressure and rate signal analysis is performed in the frequency domain, strong similarity exists between the derivative of the harmonic response function versus the harmonic period and the pressure derivative versus time, typical of conventional well testing. Thus the interpretation of harmonic well tests becomes very straightforward.

In this paper, we present the analytical models for the most commonly encountered well and reservoir scenarios and we validate the model for horizontal wells against real data of a harmonic test performed on a gas storage well in Italy.

Keywords: *well testing, harmonic testing, well performance monitoring, horizontal well, gas storage*

Highlights:

- Methodology for interpreting harmonic pulse testing in the frequency domain for horizontal wells and anisotropic formations
- Diagnostic plots analogous to conventional well testing for flow geometry and regime identification
- Advanced methodology for well performance monitoring without production interruption
- Validation on a field case: successful application of the methodology to a gas storage well

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1. Introduction

For decades, well tests have been widely used by the oil industry for evaluation of well productivity and reservoir properties, which provide key information for field development and facilities design (Horne, 1994; Bourdet, 2002; Lee et al., 2003; Kamal, 2009). Recent work has been directed towards complementing conventional well tests with less expensive and/or more environmentally friendly procedures (Hollaender et al., 2002a; Hollaender et al., 2002b; Beretta et al., 2007; Verga et al., 2008; Gringarten, 2008; Bertolini et al., 2009; Verga and Rocca, 2010; Verga et al., 2011; Verga et al., 2012; Rocca and Viberti, 2013; Verga et al., 2015, Verga et al., 2016). Harmonic well testing is one of those complementing methodologies: it may not replace conventional well testing, but it can be very effective for monitoring purposes. In conventional well tests, equilibrium conditions are required in the reservoir before the test; a single well can be produced at a time, inducing one or more pressure draw-down periods followed by a final pressure build-up which are the object of the interpretation. Conversely, a harmonic test is characterized by a periodic sequence of alternating production rates which can be superimposed on the background pressure trend and thus the test can be carried out during ongoing production or injection operations.

Even if harmonic tests resemble pulse tests (Johnson et al., 1966) because of the sequence of alternating production rates, some major differences exist. Pulse tests aim at assessing hydraulic connectivity between two wells without interrupting production from other wells. In addition to pulse test purposes, harmonic tests aim at assessing well and reservoir properties, such as skin and permeability. To this end, harmonic testing analysis is performed in the frequency domain as opposed to pulse test interpretation, which relies on the pressure and pressure derivative data as in conventional well testing.

The concept of harmonic testing was first proposed by Kuo (1972) and later developed by other authors (Black and Kipp, 1981; Kazi-Aoual et al., 1991; Rosa and Horne, 1997; Hollaender et al., 2002b, Copty and Findikakis, 2004; Despax et al., 2004; Renner and Messar, 2006; Rochon et al., 2008; Ahn and Horne, 2010; Fokker and Verga, 2011; Fokker et al., 2012; Fokker et al., 2013; Morozov 2013; Vinci et al., 2015; Sun et al., 2015, Salina Borello et al., 2017). The main advantage of this testing approach is it does not require the interruption of production nor the knowledge of previous rate history (Hollaender et al., 2002). In fact, the analysis in the frequency domain allows extraction and analysis of each periodic component of the pressure response in relation to the corresponding periodic component of the rate. The main drawback of harmonic testing is it takes longer to obtain the same information of conventional

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3 1 testing (Hollaender et al., 2002b). For this very reason, harmonic testing is inadequate for exploration
4 and appraisal wells, but it is a valid alternative to conventional well testing for monitoring well
5 2 performance.
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7 4 A qualitative example of conventional well test sequence (with multiple draw-downs and a build-up)
8 5 compared to a harmonic test is provided in fig. 1.
9 6

10 6 The basic concepts of harmonic testing are:
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- 12 1. If a harmonic rate of given frequency is imposed to a well, the corresponding reservoir pressure
13 16 response is still harmonic with the same frequency (Kuo, 1972).
14 17
- 15 2. A square pulse rate is equivalent to a linear superposition of simultaneous harmonic tests each
16 20 characterized by its own frequency (Fokker and Verga, 2011).
17 21
- 18 3. The area investigated by harmonic testing is a function of the adopted rate frequencies, which
19 24 should be selected in order to meet the specific testing targets (Ahn & Horne, 2010).
20 25
- 21 4. In order to maximize the information provided by harmonic pulse test (HPT) interpretation,
22 28 pressure data should be adequately pre-processed adopting detrending methodologies (Ahn &
23 30 Horne, 2010, Viberti, 2016) with the aim of separating pure periodic components of the signal
24 31 from non-periodic components. Therefore, detrending removes aperiodicity due to temporary test
25 34 interruption (i.e. well shut-in or significant rate deviation from that of the test design), generated
26 37 by technical and/or operational issues.
27 38
- 28 5. Periodicity of rate variation is a basic requirement for harmonic test interpretability. However,
29 40 the constant rate constraint over each flow period, strictly necessary for a conventional draw-
30 42 down analysis, is relaxed in harmonic interpretation because rate fluctuations mainly affect the
31 45 high frequency components (Hollaender et al., 2002), which are relevant to the near wellbore
32 46 region.
33 47
- 34 6. The log-log plot of the absolute value of the amplitude ratio between imposed rate and registered
35 49 well pressure, and the amplitude ratio derivative, vs. oscillation period ($T=2\pi/\omega$) is very similar
36 50 to the conventional log-log diagnostic plot (Hollaender et al., 2002b).
37 51
- 38 7. Harmonic test response shows a phase shift, which is the relative delay of the pressure cycle with
39 54 respect to the imposed flow cycle for each frequency. The phase shift can be used to assess the
40 57 skin (Kuo, 1972) or to identify flow regimes (Hollaender et al., 2002b) since the plot of phase
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3 shift vs. oscillation period tends to asymptotic values for specific flow regimes. However,
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5 compared to the log-log plot, it does not provide significant additional information (Hollaender
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7 et al., 2002b).
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9 10 11 **2. Harmonic Pulse Testing type-curves**

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13 Harmonic test type curves can be analytically derived for different well and reservoir scenarios by
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15 solving the diffusivity equation under the condition of a harmonic rate. Because of the harmonic nature
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17 of the imposed rate and induced pressure changes, HPT interpretation involves frequency analysis.
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19 Mathematical derivations as well as synthetic validations are reported in the appendix for the reader's
20
21 convenience.

22
23 The log-log plot of the absolute value of the amplitude ratio between imposed rate and registered well
24
25 pressure and the amplitude ratio derivative vs. the oscillation period ($T=2\pi/\omega$) provides diagnostic
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27 curves which are analogous to the conventional log-log diagnostic type-curves. However, despite the
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29 similarity in shape, the conventional time-domain curves are no longer applicable. In fact, a time shift of
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31 the derivative characteristic features is observed and differences exist as well between the transition
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33 periods from one flow regime to the following.

34 35 **2.1. Infinite acting radial flow (I.A.R.F.)**

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37 The dimensionless solution of the diffusivity equation for an infinite-acting homogeneous and isotropic
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39 gas reservoir drained by a fully penetrating vertical well, under radial symmetry, was already published
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41 by the authors (Salina Borello et al., 2017) in terms of Hankel functions. In the present paper the
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43 dimensionless solution is given in terms of modified Bessel functions K_0 and K_1 in a form analogous to
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45 Kazi-Aoual et al., 1991:

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$$m_D(T_D) = \frac{-K_0(\sqrt{i/T_D}) - S\sqrt{i/T_D}K_1(\sqrt{i/T_D})}{(1+iSC_D/T_D)\sqrt{i/T_D}K_1(\sqrt{i/T_D}) + iC_D/T_D K_0(\sqrt{i/T_D})} \quad (1)$$

where K_0 and K_1 are the Bessel function and m_D is the dimensionless pseudo-pressure:

$$m_D = \frac{R}{\Lambda} = \frac{1}{\Lambda} \frac{m(p)_{pulser}}{q_{sc}} \quad (2)$$

R is the dimensional amplitude ratio, Λ is a factor to make the pressure over gas rate ratio dimensionless (non-dimensionalization factor):

$$\Lambda = \frac{1}{\pi kh} \frac{T_R P_{sc}}{Z_{sc} T_{sc}} \quad (3)$$

C_D is the dimensionless wellbore storage:

$$C_D = \frac{c}{2\pi\phi c_{ti} h r_w^2} \quad (4)$$

T_D is the dimensionless oscillation period:

$$T_D = \frac{1}{2\pi} \frac{kT}{\mu_i c_{ti} \phi r_w^2} \quad (5)$$

Furthermore, T is the oscillation period; k is the reservoir permeability; h is the pay thickness; ϕ is the porosity; T_R is the reservoir temperature; μ_i and c_{ti} are the gas viscosity and the total compressibility at initial conditions, respectively; Z_{sc} is the gas compressibility factor at standard conditions, which can be approximated to unity; P_{sc} and T_{sc} are pressure and temperature at standard conditions, respectively; and S , C and r_w are the skin, wellbore storage and well radius, respectively.

Note that the argument of the Bessel function K_0 contains complex numbers; it was calculated using the algorithm by Amos (1986). In turn, also m_D assumes complex values.

It should be pointed out that equation (1) still holds true when skin incorporates non-Darcy effects (i.e. $S = \tilde{S} + Dq$), where the D factor can be estimated if different HPT are conducted at different background rates.

Note that the dimensionless expressions of m_D (eq.2) and C_D (eq. 4) are analogous to the ones of conventional well testing (Al-Hussainy et al., 1966; Bourdet, 2002), while T_D (eq. 5) differs by a factor $1/2\pi$ from the conventional t_D (Al-Hussainy et al., 1966):

$$t_D = \frac{kt}{\mu_i c_{ti} \phi r_w^2} = \frac{t}{t_c} \quad (6)$$

The derivative of R vs. the oscillation period T can then be calculated by (Hollaender et al., 2002b):

$$R'(T) = \frac{dR(T)}{d \ln T} = T \frac{dR(T)}{dT} \quad (7)$$

Being $R \in \mathbb{C}$, R' assumes complex values in turn.

For very long periods, the term $1/T_D$ becomes very small. Calculating the limit of eq. 1 for $T \rightarrow \infty$ and multiplying by factor Λ (eq. 3), the amplitude ratio and its derivative become, respectively:

$$R_{long T}(T) = - \frac{K_0(\sqrt{i/T_D})}{\sqrt{i/T_D} K_1(\sqrt{i/T_D})} \Lambda \quad (8)$$

$$T \frac{dR_{long T}}{dT} = - \frac{\Lambda}{2} \quad (9)$$

Eq. 9 indicates that the absolute value of the derivative tends to horizontal stabilization inversely proportional to kh . Moreover, the phase delay of eq. 8 assumes the characteristic value $\angle R = \angle -1 = \pi$.

It is easy to verify that for $T \rightarrow \infty$:

$$T \left| \frac{dR_{long T}}{dT} \right| = T \frac{d|R_{long T}|}{dT} \quad (10)$$

At short times, C_D/T_D becomes very large and wellbore storage dominates. Calculating the limit of eq. 1 for $T \rightarrow 0$ and multiplying by factor Λ , the response function and the derivative become, respectively:

$$R_{short T} = i \frac{T_D}{C_D} \Lambda \quad (11)$$

$$T \frac{dR_{short T}}{dT} = i \frac{T_D}{C_D} \Lambda = R_{short T} \quad (12)$$

Thus, the modulus of the response and the modulus of the response derivative both follow a linear trend with T , which corresponds to a line with a unit slope on a log-log plot. In this case the phase delay assumes the characteristic value $\angle R = \angle i = \pi/2$.

Analogously to conventional well test analysis, the modulus of the amplitude ratio ($|R|$) and the modulus of its derivative with respect to $\ln T$ ($|R'|$) are plotted against the corresponding oscillation period (T) on a log-log scale and the match point (x_M, y_M) is selected at the intercept of the horizontal stabilization and the linear wellbore storage trend. Thus for the gas reservoir we have:

$$kh = \frac{1}{4\pi} \frac{2T_R p_{sc}}{Z_{sc} T_{sc}} \frac{1}{\gamma_M} \quad (13)$$

$$C = 2x_M \frac{kh}{\mu} \quad (14)$$

It should be pointed out that, except for very early times and for late time behavior, the derivative of the

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4 modulus of R ($|R|' = T \frac{d|R|}{dT}$) and the modulus of the derivative of R ($|R'| = T \left| \frac{dR}{dT} \right|$) are not equal. A

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6 typical plot for R and R' is presented in fig. 2 where both the derivatives of the modulus of R ($|R|'$) and
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8 the modulus of the derivative of R ($|R'|$) are given. Note that wellbore storage effects last longer on $|R'|$.

9
10 A comparison of the proposed model in the frequency domain with a standard well test log-log plot for a
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12 single flow period is possible when proper non-dimensionalizations are adopted:

- 13 • *dimensionless log-log plot in the frequency domain*: the modulus of the dimensionless
14
15 pseudopressure in the frequency domain m_D ($|R/\Lambda|$), calculated according to eq. 1, and the
16
17 modulus of its derivative with respect to $\ln T$ ($|R'/\Lambda|$) are plotted against the dimensionless
18
19 oscillation period (T_D), calculated according to eq. 5;
- 20
21 • *dimensionless log-log plot in the time domain*: the dimensionless pseudopressure changes in the
22
23 time domain ($\Delta m(p)/\Lambda q$) and its derivative with respect to $\ln t$ ($\Delta m'(p)/\Lambda q$) are plotted against
24
25 the dimensionless time t_D (eq. 6).

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27 The comparison is shown in fig. 3. Notice that time derivatives are concordant in dimensionless time,
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29 which means that a lag factor 2π exists between oscillation period vs. elapsed time if the same
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31 investigation distance is considered (see eq. 5 vs. eq. 6).

32 33 34 35 36 2.2. Horizontal well

37
38 Fluid flow in a reservoir drained by a horizontal well cannot be described by a 2D equation in the near
39
40 wellbore zone. An alternative approach is required, and we have developed a similar approach to that
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42 described by Fokker and Verga (2008). Thus, we first split the well into segments of equal lengths (L_{seg}).
43
44 The overall pressure response is given by the superposition of the responses due to each producing well
45
46 segment (j). The fluxes into the segments are finally determined by requiring a prescribed total flux and
47
48 a constant pressure over the well.

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50 The solution of diffusivity equation at the well with a pulsing rate of period T_D reads (see Appendix A.1
51
52 for details):

$$53
54
55 m_D(T_D) = \frac{1}{\sum_{ij} [\Gamma_{ij}^{well} - S_{L_{seg}}^{-1}]_{ij}^{-1} - i \frac{C_D}{T_D}} \quad (15)$$

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59 where Γ^{well} is the matrix with values of Γ_{ij} calculated for segment position i due to reservoir fluid
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3 flow into segment j (eq. A.20) , and L_{seg} is the length of the well segment.

4
5 In the presence of vertical anisotropy, eq. 15 holds with:

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$$[x, y, z]^{eq} = \left[\frac{x}{\sqrt{\alpha}}, \frac{y}{\sqrt{\alpha}}, z\sqrt{\alpha} \right] \quad (16)$$

11
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$$h^{eq} = h\sqrt{\alpha} \quad (17)$$

13
14
$$L_{seg}^{eq} = \frac{L_{seg}}{\sqrt{\alpha}} \quad (18)$$

15
16
$$r_w^{eq} = \frac{1+\alpha}{2\sqrt{\alpha}} r_w \quad (19)$$

17
18
$$T_D^{eq} = T_D \frac{4}{(1+\alpha)^2} \quad (20)$$

19
20 where $\alpha = \sqrt{\frac{k_h}{k_v}}$ (21)

21
22 Details are given in appendixes A.1 and A.2.

23
24
25 In the horizontal well scenario a numerical approach is more convenient to calculate the derivative of R .
26
27 Comparison in dimensionless terms between the $|R'|$ and the pressure derivative in time of a single flow
28
29 period is shown in fig. 4 and fig. 5. Log-log plots are concordant in dimensionless time (fig. 4), even in
30
31 the presence of vertical anisotropy (fig. 5). Notice that, similarly to the pressure derivative in time, the
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33 derivative of R vs. period is initially dominated by wellbore storage; then it stabilizes at $\sqrt{k_h k_z} L$,
34
35 corresponding to radial flow developing in a vertical plane orthogonal to the well axis; subsequently,
36
37 linear flow develops and finally the kh stabilization is reached. Discussion and validation of this model
38
39 is given in appendix A.3.

40 41 42 **2.3. Partial penetration model**

43
44 The type-curves of a limited entry well can be developed in a way very similar to that of a horizontal
45
46 well (see appendix A.1 and A.2). The main difference is the flux orientation with respect to the
47
48 Cartesian axes.

49
50 Comparison in dimensionless terms between the $|R'|$ and the pressure derivative in time of a single flow
51
52 period is shown in fig. 6 and fig. 7. The log-log plot shows that the derivatives are quite concordant in
53
54 dimensionless time (fig. 6), even in the presence of vertical anisotropy (fig. 7).

55 56 57 **2.4. One fault model**

58
59 If a single no-flow boundary exists at distance d_F from the well, the contribution of an image well at
60
61

distance $2d_F$ from the well is added to the I.A.R.F. model (eq. 1), giving:

$$m_D(T_D) = \frac{-K_0(\sqrt{i/T_D}) - S \cdot \sqrt{i/T_D} K_1(\sqrt{i/T_D}) - K_0\left(\frac{2d_F}{r_w} \sqrt{i/T_D}\right)}{(1+iSC_D/T_D)\sqrt{i/T_D} K_1(\sqrt{i/T_D}) + iC_D/T_D K_0(\sqrt{i/T_D})} \quad (22)$$

Comparison in dimensionless terms between $|R'|$ and the pressure derivative in time of a single flow period is shown in fig. 8. Again, the log-log plots are quite concordant in dimensionless time.

2.5. Closed boundary

The solution for a closed gas reservoir is found by imposing no-flow boundary conditions at distance r_e , giving:

$$m_D(T_D) = \frac{-\left[K_0(\sqrt{i/T_D}) I_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) + K_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) I_0(\sqrt{i/T_D})\right] - S \sqrt{i/T_D} \left[K_1(\sqrt{i/T_D}) I_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) + K_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) I_1(\sqrt{i/T_D})\right]}{(1+iSC_D/T_D)\sqrt{i/T_D} \left[K_1(\sqrt{i/T_D}) I_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) - K_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) I_1(\sqrt{i/T_D})\right] + iC_D/T_D \left[K_0(\sqrt{i/T_D}) I_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) + K_1\left(\frac{r_e}{r_w} \sqrt{i/T_D}\right) I_0(\sqrt{i/T_D})\right]} \quad (23)$$

As shown in fig. 9, when the investigation distance r_e is reached, the derivative of Fourier spectrum firstly decreases with a trend similar to that of the build-up derivative; successively for $T_D \rightarrow \infty$ it rises with slope 1, analogously to draw-down derivative.

3. Application to a real case

The proposed methodology was applied to a real gas storage well. The areal dimension of the reservoir is $3.4 \times 1.1 \text{ km}^2$. Reservoir pressure and temperature at test time were 90 bar and $44.7 \text{ }^\circ\text{C}$, respectively.

The porosity in the pulser area is 0.14, the total compressibility is $0.0111405 \text{ bar}^{-1}$. The gas is 94.5% methane, 3.5 % ethane, 1% propane, 1% nitrogen. The well (well diameter $r_w = 9^{5/8}$ inches) is horizontal with a producing horizontal length of 161.6 m, navigating in the first 9 m of the reservoir pay.

The tested well departs from a slanted pilot well which crosses the entire net pay; a gamma ray log run in the pilot (fig. 10) shows the presence of a clay interlayer at 10 mTVD from the top. Therefore, a net pay of 10 m was adopted in the interpretation. A sketch of the reservoir cross-section is shown in fig. 11.

A square pulsing test with constant productions of $\pm 50 \cdot 10^3 \text{ Sm}^3/\text{day}$, lasting 24 hours each, was superposed on a background field production of $450 \cdot 10^3 \text{ Sm}^3/\text{day}$. Pressures were recorded downhole every 10 seconds (resolution = 0.0007 bar, accuracy = $\pm 0.02\%$ full scale), while rates were recorded at

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the well head every 30 seconds. Production rates and pressures recorded during the two tests are reported in fig. 12. A preexisting Flow After Flow (FAF) test was also available for the same well (see fig. 13 and tab. 1). The results from the interpretation of the FAF test, which involved higher rates with respect to those produced during the HPT, clearly showed negligible non-Darcy effects. This result is in agreement with the expected skin component due to non-Darcy effect calculated for the HPT test (see appendix A4 for details).

3.1. Results and discussion

Preliminarily, a rate resampling was performed following a step-wise constant approach, in order to have the same sampling of bottom-hole pressure data. Subsequently, a quality check on pressure and rate data was conducted. Rate data were sufficiently regular (fig. 14) both in time (3^o quartile of error distribution on hemi-period duration below 5 min. over 24h) and value (3rd quartile of error distribution on rate change about 10%). As a consequence the signal to noise ratio was about 5. Pressure data showed a similar signal to noise ratio ($\Delta p_{osc} \sim \pm 0.5$ bar, $\Delta p_e \sim \pm 0.1$ bar) which is ascribed to rate irregularity.

Then bottom-hole pressure data were processed in the frequency domain by applying the Fast Fourier Transform. The normalized pseudo-pressure and its derivative vs. oscillation period plotted on a log-log scale was compared, in dimensionless terms, with the conventional log-log plot of the build-up (BU) of the preexistent FAF test (fig. 15). Derivatives were in good agreement.

Interpretation of the HPT with the type-curve of eq. 15 is shown in fig. 16. Interpretation results in terms of well and petrophysical properties are listed in tab. 2 and compared with the build-up interpretation of the preexistent FAF test. Good agreement was found.

4. Conclusions

Analytical models for HPT interpretation on a graph analogous to the log-log diagnostic plot, but applied to the frequency domain, were derived and synthetically validated for the most common scenarios (I.A.R.F., single boundary, partial penetration, horizontal well, closed reservoir).

By defining a non-dimensionalization factor for oscillation period equal to $2\pi t_c$, good correspondence with the conventional log-log plot in dimensionless terms was observed for all models with the only exception of the transition zones. This implies that:

1. an interpretation approach analogous to conventional well test can be adopted – provided that adequate data processing and specific analytical solutions are implemented.
2. a 2π lag factor exists between the investigation distance from a conventional test with build-up duration t and a harmonic pulse test with oscillation period $T = t$.

This, in addition to a minimum number of 5 oscillation periods needed for HPT to be robust, confirms that HPT takes much longer than conventional well testing to obtain the same information. Thus, the longer duration needed for HPT makes it less suitable for late time investigation, such as field boundary identification. Conversely, an important value of the proposed approach, which is not meant to be a substitute for a standard test, lies in the possibility of monitoring well performance without significant field operation alterations.

The procedure for harmonic test interpretation was successfully applied to a horizontal well producing a gas storage reservoir with ongoing operations. The dimensionless log-log plot of the derivative of the amplitude ratio in the frequency domain was in good agreement with conventional build-up pressure derivative and the well test interpretation with the developed type-curves gave consistent results.

Nomenclature

β = turbulence factor, $1/L$

Γ = matrix of the pressure (or pseudo-pressure) field accounting for well segments contributions, dimensionless

μ = gas viscosity, m/Lt

Λ = non-dimensionalization factor, $(m/L^4 t^2)^{-1}$

ϕ = porosity, dimensionless

ω = angular frequency, θ/t

B = gas volume factor, dimensionless

C = wellbore storage, $L^4 t^2 / m$

C_D = dimensionless wellbore storage

c_t = total compressibility, Lt^2/m

D = non Darcy coefficient, $(L^3/t)^{-1}$

d_F = distance of single boundary from well, L

g_ω = pressure (or pseudo-pressure) response of the well for component ω , m/Lt^2 (m/Lt^3 for gas)

g_ω^j = pressure (or pseudo-pressure) response of the well segment j for component ω , m/Lt^2 (m/Lt^3 for gas)

\mathbf{g}_ω = vector of the pressure (or pseudo-pressure) responses of the well segments for component ω , m/Lt^2 (m/Lt^3 for gas)

h = pay thickness, L

k = permeability, L^2

m = pseudo-pressure, m/Lt^3

m_D = dimensionless pseudo-pressure

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- p = pressure, m/Lt²
- \tilde{q}_ω^{well} = scaled rate for the harmonic component ω including wellbore storage, m/Lt² (m/Lt³ for gas)
- \tilde{q}_ω^{sf} = scaled rate sand-face (no wellbore storage) for the harmonic component ω , m/Lt² (m/Lt³ for gas)
- $\tilde{q}_\omega^{j,sf}$ = scaled rate sand-face of the well segment j for component ω , m/Lt² (m/Lt³ for gas)
- R = amplitude ratio $m(p)/q_{sc}$, m/L⁴t²
- R' = derivative of amplitude ratio vs. T , m/L⁴t²
- r_e = external radius, L
- r_w = well radius, L
- S = skin, dimensionless
- t_c = characteristic time, t
- T = oscillation period, t
- T_f = fundamental oscillation period, t
- T_D = dimensionless oscillation period
- T_D^{eq} = dimensionless oscillation period for the equivalent isotropic scenario
- t_D = dimensionless time
- T_R = reservoir temperature, T
- Z = gas compressibility factor, dimensionless
- $\angle R$ = phase delay, θ

Constants

- i = imaginary unit, dimensionless
- T_{sc} = temperature at standard conditions, 293.15 K
- p_{sc} = pressure at standard conditions, 101.325 kPa
- R = gas constant, 8.314472 J K⁻¹ mol⁻¹

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Appendix

A.1 Development of the horizontal well solution

Flow in the reservoir close to a horizontal well cannot be described by a 2D equation. We used a similar approach to that of Fokker and Verga (2008). We split the well up into segments, calculated the pressure response of each segment due to the flow into said segment and into the others, and chose the fluxes into each segment in a way that the total flow was the prescribed value and the pressures were the same for all segments. The no-flow conditions at the upper and lower reservoir boundaries were fulfilled by positioning a vertical array of image sources.

In a homogeneous and isotropic reservoir containing slightly compressible fluid, the flow is described by the diffusivity equation:

$$\phi c_t \frac{\partial p}{\partial t} = \nabla \left[\frac{k}{\mu} \nabla p \right] \quad (\text{A.1})$$

where ϕ is the rock porosity, c_t is the total compressibility, k is the rock permeability, μ is the fluid viscosity, p is the pressure and t is the time.

In gas reservoirs, an analogous equation can be written by using the pseudo pressure function:

$$m(p) = 2 \int_{p_b}^p \frac{p' dp}{\mu Z} \quad (\text{A.2})$$

where Z is the gas compressibility factor and the limits of integration are between a base pressure p_b and the pressure of interest p .

This pseudo pressure is a standard function of pressure which was designed to linearize the diffusivity equation for gas (see, e.g. Al-Hussainy et al., 1966). We obtained:

$$\phi c_t \frac{\partial m}{\partial t} = \nabla \left[\frac{k}{\mu} \nabla m \right] \quad (\text{A.3})$$

When a piecemeal homogeneous subsurface is assumed, the diffusivity equation for oil is linear. For gas, it is not (the product μc_t depends on $m(p)$), but we treated the equation as linear by assuming small pressure disturbances. We obtained:

$$\frac{\partial m}{\partial t} = \eta \nabla^2 m \quad (\text{A.4})$$

where:

$$\eta = \frac{k}{\phi \mu c_t} \quad (\text{A.5})$$

Under the assumption of linearity, the pressure and flow solution of a reservoir with many wells and changing production rates could then be added to the solution of the harmonic test. A Fourier

transformation (FFT) picked out the signal present in the imposed frequency. Furthermore, there was no frequency mixing. Therefore, we considered each frequency component independently. The final pressure was then a superposition of the responses to all the frequency components present in the imposed flow rate, added to the background signal.

We wrote the pseudo-pressure solution for each frequency as the product of a space-dependent and a time-dependent function:

$$m_\omega(\mathbf{r}, t) = g_\omega(\mathbf{r})e^{i\omega t} \quad (\text{A.6})$$

The angular frequency was defined as $\omega = 2\pi/T$, with T the oscillation period of the imposed harmonic signal. This resulted in a time-independent differential equation for g :

$$i\omega g_\omega(\mathbf{r}) = \eta \nabla^2 g_\omega(\mathbf{r}) \quad (\text{A.7})$$

The case for an oil reservoir is the same, with the pressure p replacing the pseudo-pressure m .

For the scaling of the volumetric rates, we took for the two cases:

$$\tilde{q}^{gas} = \frac{2p_{sc}T_R}{Z_{sc}T_{sc}} \frac{q^{gas}}{2\pi hk} = \Lambda_{gas} q^{gas} \quad (\text{A.8})$$

$$\tilde{q}^{oil} = B\mu \frac{q^{oil}}{2\pi hk} = \Lambda_{oil} q^{gas} \quad (\text{A.9})$$

in which B is the formation volume factor and h is the reservoir thickness, q^{gas} and q^{oil} are rates at standard conditions; the rate is taken positive for production.

Considering a point source as a fundamental solution, the diffusivity equation for the pressure amplitude around it (eq. A.7) can be written as:

$$\zeta^2 g_\omega(r) = \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dg_\omega}{dr} \right) \quad (\text{A.10})$$

where:

$$\zeta = \sqrt{\frac{i\omega}{\eta}} = \frac{1}{r_w} \sqrt{\frac{i}{T_D}} \quad (\text{A.11})$$

Equation A.10 is known as a spherical Bessel equation, or alternatively, a Helmholtz equation.

For an infinite reservoir, the pressure disturbance vanishes at large distances from the well, as the net flow of the harmonic signal is zero (first boundary condition):

$$[g_\omega]_{r \rightarrow \infty} = 0 \quad (\text{A.12})$$

The second boundary condition is a harmonic signal on the flow rate into the well, corrected for the wellbore storage effect. In first instance the source flux was calculated at the sand face and was referred

to as \tilde{q}_ω^{sf} , to distinguish it from the \tilde{q}_ω^{well} introduced later on, which included the wellbore storage.

The fundamental solution for a point source in infinite space with vanishing pressure disturbance far away from the source, with strength \tilde{q}_ω^{sf} read:

$$g_\omega^p(r) = -\frac{h}{2} \frac{\exp[-\zeta r]}{r} \tilde{q}_\omega^{sf} \quad (\text{A.13})$$

The factor $h/2$ was introduced for convenience and as a means to make the expression non-dimensional.

In a finite-thickness horizontal layer with thickness h , the boundary conditions at the upper and lower boundaries were fulfilled by complementing this function with a 1-dimensional series of images. The expression for a point source in a horizontal layer was:

$$g_\omega^{pL}(r) = \gamma_\omega \tilde{q}_\omega^{sf} \quad (\text{A.14})$$

where:

$$\gamma_\omega = -\frac{h}{2} \sum_k \frac{\exp[-\zeta r_k]}{r_k} \quad (\text{A.15})$$

in which:

$$r_k = \sqrt{\rho^2 + (z - z_k)^2} \quad (\text{A.16})$$

and the index k ranges over the image sources. We used Poisson's formula to obtain a rapidly converging series of the Fourier transforms for values of $|\zeta| < 1$ (van Kruijsdijk, 1988). The expression became:

$$\gamma_\omega = -\frac{h}{2} \left\{ K_0(\zeta \rho) + 2 \sum_{n=1}^{\infty} K_0(\rho \sqrt{\zeta^2 + (n\pi/h)^2}) \cos\left(\frac{n\pi z}{h}\right) \cos\left(\frac{n\pi z_j}{h}\right) \right\} \quad (\text{A.17})$$

$$\rho^2 = (x - x_j)^2 + (y - y_j)^2 \quad (\text{A.18})$$

where (x_j, y_j, z_j) denotes the position of the j^{th} segment along the well and K_0 is the modified Bessel Function of the second kind.

The choice of the first or the second expressions for γ_ω (eq. (A.15) or (A.17), respectively) depends on the values of ζ and the distance to the source; this way any singularities of the Bessel function are avoided and the computation times minimized.

The pressure response at any position r_i due to a producing well segment j with a homogeneous distribution of the flux is an integral of this function over the well segment:

$$g_\omega^{j,sf}(r_i) = \Gamma_{ij} \tilde{q}_\omega^{j,sf} \quad (\text{A.19})$$

$$\Gamma_{ij} = \Gamma_j(r_i) = \int_0^1 \gamma_\omega[r_i(s_j)] ds_j \quad (\text{A.20})$$

where the variable s_j denotes the relative position along the well segment: while it changes from 0 to 1

the position (x_j, y_j, z_j) changes from the beginning to the end of the segment. We employed numerical integration.

We then proceeded to employ a pressure boundary condition in the well to determine the strengths of the different well segment sources.

The pressure at any point in the reservoir is the summation of the contributions from all well segments j . Therefore, the pressure amplitude at any position r_i due to all the segments read:

$$g_\omega(r_i) = \sum_j \Gamma_{ij} \tilde{q}_\omega^{j,sf} \quad (\text{A.21})$$

The pressure inside the well in a segment i presents a difference with the pressure in the reservoir, due to skin:

$$\Delta g_{\omega S} = S \frac{h}{L_{seg}} \tilde{q}_\omega^{i,sf} \quad (\text{A.22})$$

Thus, the pressure inside the well ($r=r_w$) in a segment i is:

$$g_\omega(r_w) = \left(\sum_j \Gamma_{ij} \tilde{q}_\omega^{j,sf} - S \frac{h}{L_{seg}} \tilde{q}_\omega^{i,sf} \right) \quad (\text{A.23})$$

The summation only operated on the first term, in which the influence of all well segments were modelled. The second term only operated on the flux that entered the segment under consideration. The collection of pressures in all segments i could thus be represented as a superposition of contributions of production into all segments, and a skin term dependent on the flux into that particular segment.

Representing the collection of these terms into a vector we wrote in vector notation:

$$\mathbf{g}_\omega = \left(\mathbf{\Gamma}^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right) \tilde{\mathbf{q}}_\omega^{sf} \quad (\text{A.24})$$

where \mathbf{g}_ω is the vector of yet unknown pressure amplitudes in the well; $\mathbf{\Gamma}^{well}$ is the matrix with values of Γ_{ij} calculated for segment position i due to reservoir fluid flow into segment j . Notice that $\mathbf{\Gamma}^{well}$ is a matrix of complex numbers.

If friction in the well is negligible, the pressure is constant – its magnitude being dependent on total rate magnitude and frequency. All elements of the vector \mathbf{g}_ω must then be identical to a single value g_ω . We therefore inverted eq. A.24 to calculate the distribution of fluxes over the segments of the well:

$$\tilde{\mathbf{q}}_\omega^{sf} = \left(\mathbf{\Gamma}^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right)^{-1} \mathbf{g}_\omega \quad (\text{A.25})$$

where $\tilde{\mathbf{q}}_\omega^{sf}$ is the vector of all fluxes into well segments. These fluxes do not have to be identical – an infinite-conductivity horizontal well typically shows larger influx towards the two producing endpoints. To incorporate the wellbore storage effect, the sum of all segment fluxes must be corrected for it. We have:

$$\tilde{q}_\omega^{well} e^{i\omega t} = \sum_i \tilde{q}_\omega^{i,sf} e^{i\omega t} - \frac{1}{\eta} r_w^2 C_D \frac{\partial}{\partial t} (m_\omega(r_w, t)) \quad (\text{A.26})$$

giving, after the substitution of eq. A.25 and A.6 and the definition of the appropriate parameters:

$$\tilde{q}_\omega^{well} = \sum_i \left[\left(\Gamma^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right)^{-1} \mathbf{g}_\omega \right]_i - i \frac{1}{T_D} C_D g_\omega \quad (\text{A.27})$$

The terms within the square brackets of eq. A.27 combine to the sum of the i^{st} row of the inverted matrix, multiplied by the constant number g_ω . The result of the complete summation is therefore the summation of all elements of the inverse matrix multiplied by the constant number g_ω . The response function was then given by:

$$m_D(T_D) = \frac{m_\omega(r_w, t)}{\tilde{q}_\omega e^{i\omega t}} = \frac{g_\omega}{\tilde{q}_\omega^{well}} = \frac{1}{\sum_{ij} \left[\Gamma^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right]_{ij}^{-1} - i \frac{C_D}{T_D}} \quad (\text{A.28})$$

The response in an observation point could be calculated by applying eq. A.21, in which we substitute the definition of eq. A.20 as an influence function for the pressure contribution at observation point r_{obs} resulting from the influx into well segment j . Furthermore we included eq. A.25 for the distribution of flow over the segments and A.28 (with $g_\omega = m_D(T_D) \tilde{q}_\omega^{well}$) for the solution of the response in the well:

$$m_{D\ obs}(T_D, r_{obs}) = \frac{g_\omega(r_{obs})}{\tilde{q}_\omega^{well}} = \frac{\sum_{jl} \Gamma_j(r_{obs}) \left(\Gamma^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right)^{-1}_{jl}}{\sum_{ij} \left(\Gamma^{well} - S \frac{h}{L_{seg}} \mathbf{I} \right)^{-1}_{ij} - i \frac{C_D}{T_D}} \quad (\text{A.29})$$

A.2 Reservoir with permeability anisotropy

For an anisotropic reservoir the horizontal and vertical permeabilities k_h and k_v are different and for the diffusivity equation we obtained:

$$\phi c \mu \frac{\partial m}{\partial t} = k_h \frac{\partial^2 m}{\partial x^2} + k_h \frac{\partial^2 m}{\partial y^2} + k_v \frac{\partial^2 m}{\partial z^2} \quad (\text{A.30})$$

The equation could be transformed into an isotropic equation by scaling the axes. We obtained:

$$\phi c \mu \frac{\partial m}{\partial t} = k' \left[\frac{\partial^2 m}{\partial x'^2} + \frac{\partial^2 m}{\partial y'^2} + \frac{\partial^2 m}{\partial z'^2} \right] \quad (\text{A.31})$$

$$x' = \frac{x}{\sqrt{\alpha}}; y' = \frac{y}{\sqrt{\alpha}}; z' = z \sqrt{\alpha} \quad (\text{A.32})$$

$$\alpha = \sqrt{\frac{k_h}{k_v}}; k' = \sqrt{k_h k_v} \quad (\text{A.33})$$

The complete treatment of appendix A.1 applies with the notion that all the parameters that refer to length, areal or volumetric quantities must be scaled according to eq. A.32 and A.33:

- the equivalent permeability reads $k^{eq} = k_h / \alpha$
- the rate q_{sc} and the wellbore storage C , being a volumetric quantity, must be scaled with $\frac{\sqrt{\alpha}}{\alpha}$

- the segments length L_{seg} must be scaled with $\frac{1}{\sqrt{\alpha}}$.
- an equivalent pay thickness $h^{eq} = h\sqrt{\alpha}$ should be considered
- an equivalent wellbore radius must be adopted (Babu & Odeh, 1989; Brigham, 1990):

$$r_w^{eq} = \frac{1+\alpha}{2\sqrt{\alpha}} r_w \quad (\text{A.34})$$

which results from the average between the scaling factor of the horizontal direction and the scaling factor of the vertical direction.

As a consequence the dimensionless oscillation period becomes:

$$T_D^{eq} = T_D \frac{4}{(1+\alpha)^2} \quad (\text{A.35})$$

Analogously the dimensionless wellbore storage becomes:

$$C_D^{eq} = C_D \frac{4}{(1+\alpha)^2} \quad (\text{A.36})$$

Notice that the T_D/C_D product is not scaled. The same happens to the non-dimensionalization factor Λ (eq.3) because of the scaling factors applied to pay, permeability and rate vanish.

A.3 Validation

A synthetic base case was constructed. The reservoir is homogeneous and isotropic with permeability $k = 100$ mD, porosity $\phi = 0.2$, pay thickness $h = 20$ m, pressure $p_i = 130$ bar and temperature $T_R = 45$ °C. The total compressibility is $c_t = 0.00665017$ bar⁻¹. The saturating fluid composition is 90% methane gas, 5% ethane, 1% propane, 1% carbon dioxide and 3% nitrogen. The well is horizontal with a producing length of 100 m and positioned in the middle of the pay thickness; the wellbore radius is $r_w = 0.1$ m; the wellbore storage is $C = 6.41 \cdot 10^{-6}$ m³/Pa and the skin is $S = 0$. The test history is made up of 6 periods of 48 h, each alternating a rate of $500 \cdot 10^3$ m³/day with a rate of $400 \cdot 10^3$ m³/day every 24 h. The pressure data was analytically generated by a commercial well-test simulator, imposing a sampling rate of 10 s. Validation against synthetic data is shown in fig. A.1 for different skin (fig. A1a) and anisotropy (fig. A1b) scenarios. The synthetic response can deviate from the model at high frequencies (short period components), due to the imperfection of the synthetically generated spectrum. However, the agreement improves at low frequencies (long period components) and becomes good when linear flow develops. Therefore, kh and skin are correctly identified.

A4. Estimation of non-Darcy skin component

The analytical expression for the non-Darcy factor D derived for horizontal well geometry is (Joshi, 1986):

$$D = \frac{khM}{2\pi L^2 \mu_g R T_{sc}} \beta \left(\frac{1}{r_w} \right) \quad (\text{A } 38)$$

where h is net pay of the formation; L is the horizontal well length, M is the gas molar mass, R is the gas constant, β is the turbulence factor, r_w is the well radius, k is the near-wellbore permeability, μ_g is gas viscosity, p_{sc} and T_{sc} stand for pressure and temperature at standard conditions, respectively. All parameters are expressed in SI units.

The turbulence factor β was calculated using the correlation suggested by Liu et al. (1995):

$$\beta = \frac{8.91 \times 10^8}{k\phi} \tau \quad (\text{A } 38)$$

where β is in 1/ft, near-wellbore permeability (k) is in mD and tortuosity (τ) was assumed as 0.67/ ϕ (Pape et al., 1999).

With the parameters of the analyzed real case we obtained $D = 2.4 \cdot 10^{-10}$ day/Sm³. Being 450 10³ Sm³/day the average rate value of the oscillation, the skin component due to non-Darcy effects is 1.1 10⁻⁴. As a consequence, the non-Darcy effects can be neglected. This result is in good agreement with the interpretation of the available FAF test.

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Captions:

Table 1: List of available well test for comparison.

Table 2: Comparison of interpretation results obtained from different tests and/or with different approaches.

Figure 1: Schematic of (a) a conventional well test sequence with multiple draw-downs and a build-up, compared to (b) harmonic test.

Figure 2: Response of a fully penetrating well in an infinite-acting reservoir: comparison, in dimensionless terms, between the pressure derivative in time of a single flow period (red) and the derivative in period of the Fourier spectrum of the entire oscillation sequence (blue).

Figure 3: I.A.R.F. model: comparison between $|R|^*$ (red) and $|R'|$ (blue).

Figure 4: Response of a fully penetrating horizontal well ($L=5h$): comparison, in dimensionless terms, of the pressure derivative in time of a single flow period (red) vs. the derivative in period of the Fourier spectrum of the entire oscillation sequence (blue).

Figure 5: Anisotropy effects ($k_v/k_h = 1, 0.1$) on the pressure derivative in time of a single flow period (empty dots) vs. the derivative in period of the Fourier spectrum of the entire oscillation sequence (full dots), in dimensionless terms, for a horizontal well with $L = 5h$.

Figure 6: Response of a partially penetrating vertical well ($h_w/h=0.1$): comparison, in dimensionless terms, between the pressure derivative in time of a single flow period (red) and the derivative in period of the Fourier spectrum of the entire oscillation sequence (blue).

Figure 7: Anisotropy effect ($k_v/k_h = 1, 0.1, 0.01$) on the pressure derivative in time of a single flow period (empty dots) vs. the derivative in period of the Fourier spectrum of the entire oscillation sequence (full dots), in dimensionless terms, for a partially penetrating vertical well ($h_w/h=0.1$).

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Figure 8: Response of a pulser well in a single boundary scenario ($d_F=500 r_w$): comparison, in dimensionless terms, of the pressure derivative in time of a single flow period (red) vs. the derivative in period of the Fourier spectrum of the entire oscillation sequence (blue).

Figure 9: Response of a pulser well in a closed reservoir scenario ($r_e = 3000 r_w$): comparison, in dimensionless terms, of the pressure derivative in time of a single flow period (build-up in red dots, draw-down in purple x) vs. the derivative in period of the Fourier spectrum of the entire oscillation sequence (blue dots).

Figure 10: Pilot well Gamma-ray log.

Figure 11: Sketch of the reservoir cross-section.

Figure 12: Rate history (blue) and registered BHP (red) of the HPT test Mar. 2016. The first and the last two hemi-periods were discarded to maximize data regularity.

Figure 13: Rate history (blue) and registered BHP (red) of the FAF test Dec. 2014.

Figure 14: Rate data quality check.

Figure 15: Comparison of dimensionless derivatives from HPT and FAF test.

Figure 16: Match of the HPT test data in the frequency domain: analogous of log lg plot (a) and Horner plot (b).

Figure A.1: Validation of the horizontal model (solid line) against synthetic data (dotted line) in different scenarios: sensitivity to skin (a) and anisotropy (b).

*Highlights

Highlights:

- Methodology for interpreting harmonic pulse testing in the frequency domain for horizontal wells and anisotropic formations
- Diagnostic plots analogous to conventional well testing for flow geometry and regime identification
- Advanced methodology for well performance monitoring without production interruption
- Validation on a field case: successful application of the methodology to a gas storage well

Figure 1

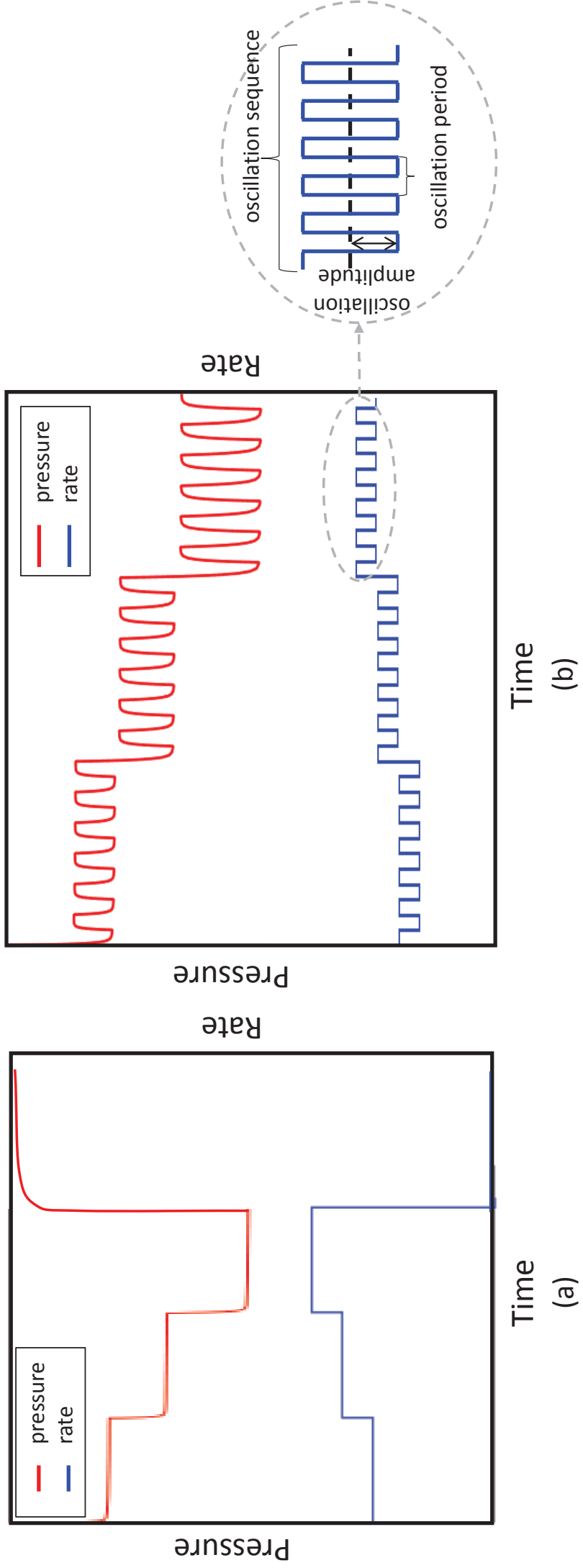


Figure 2

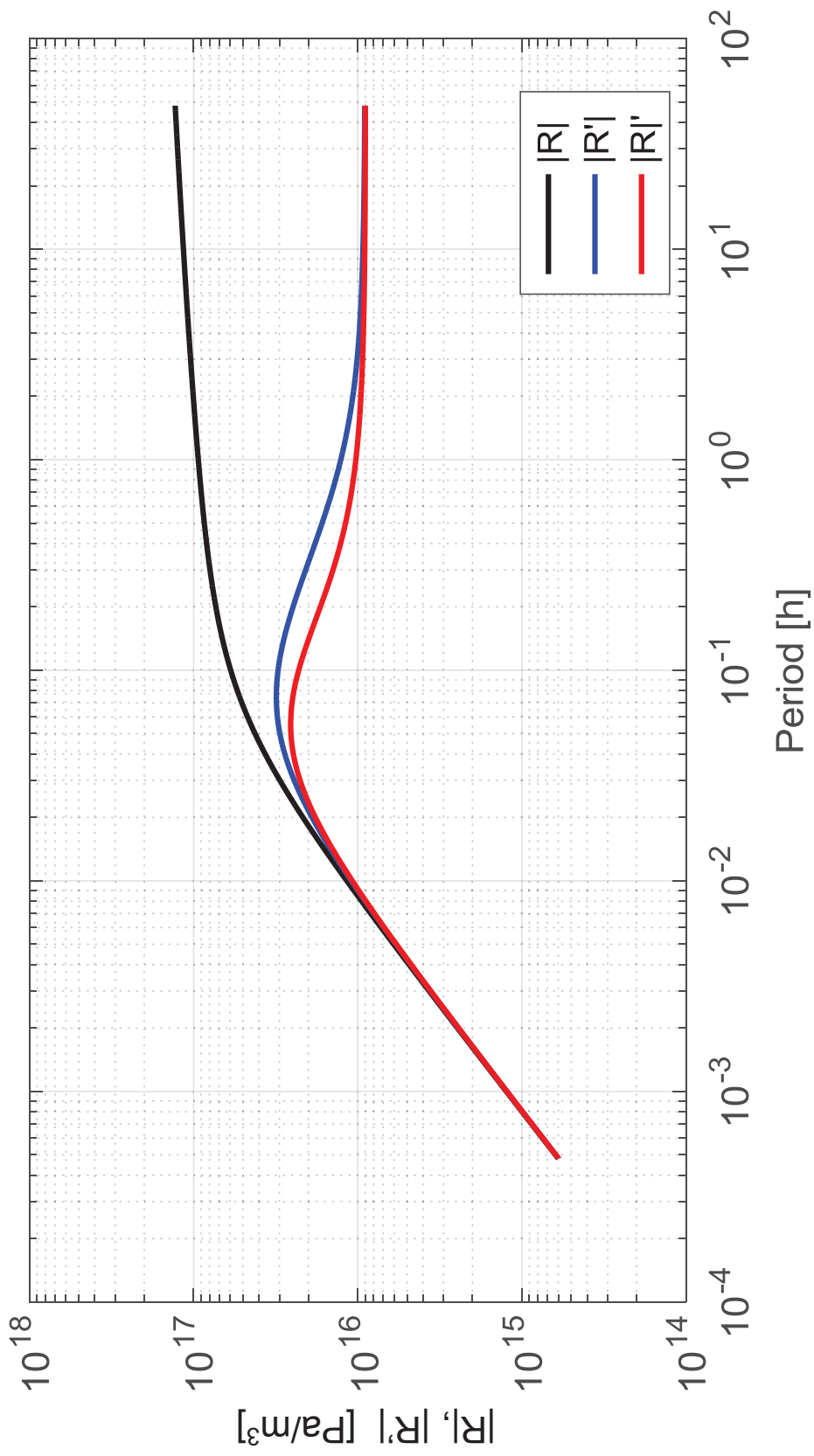


Figure 3

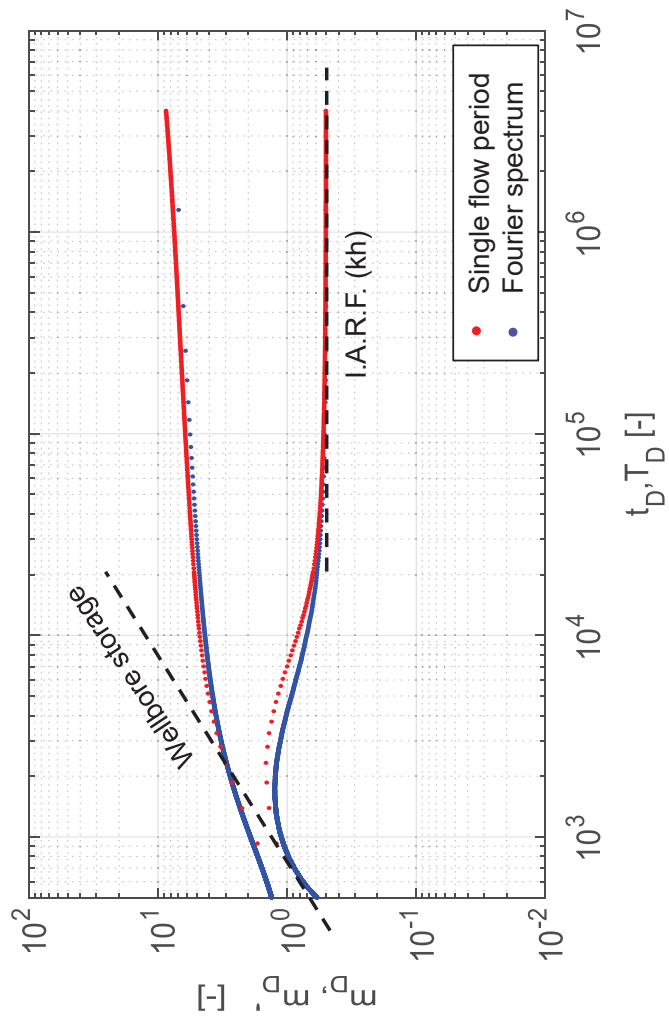


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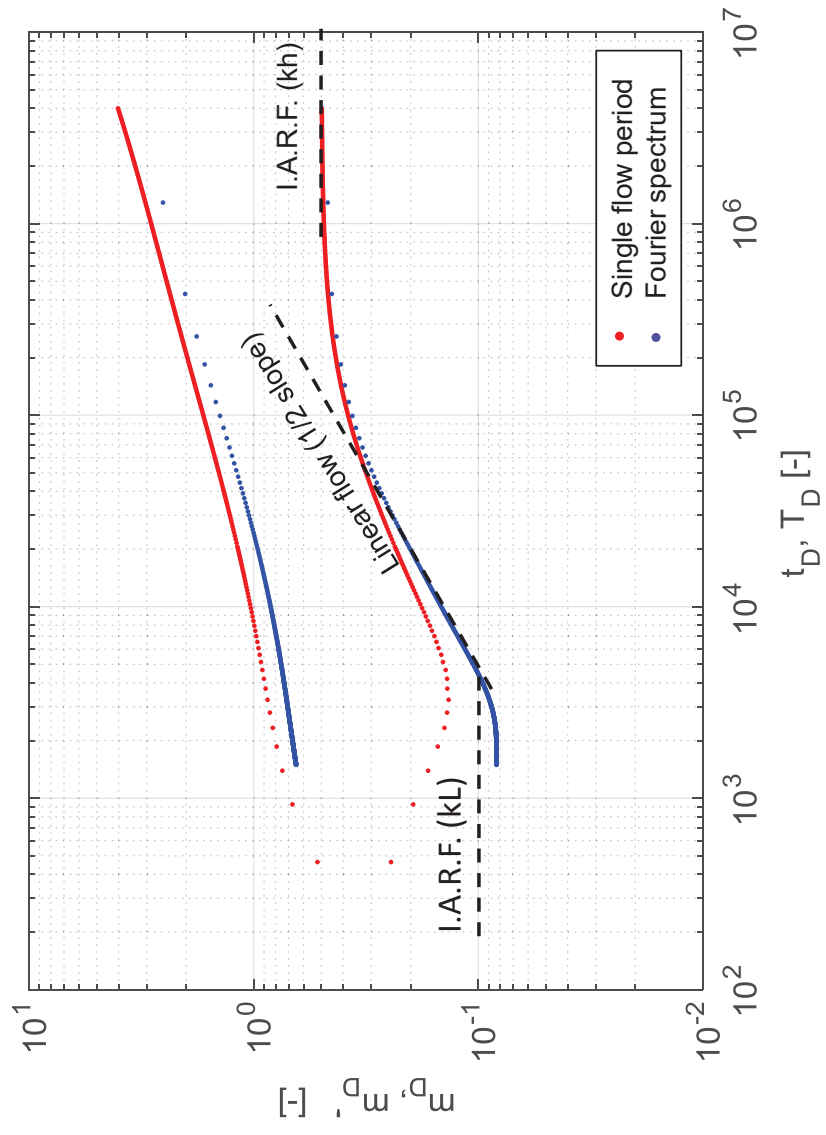


Figure 5

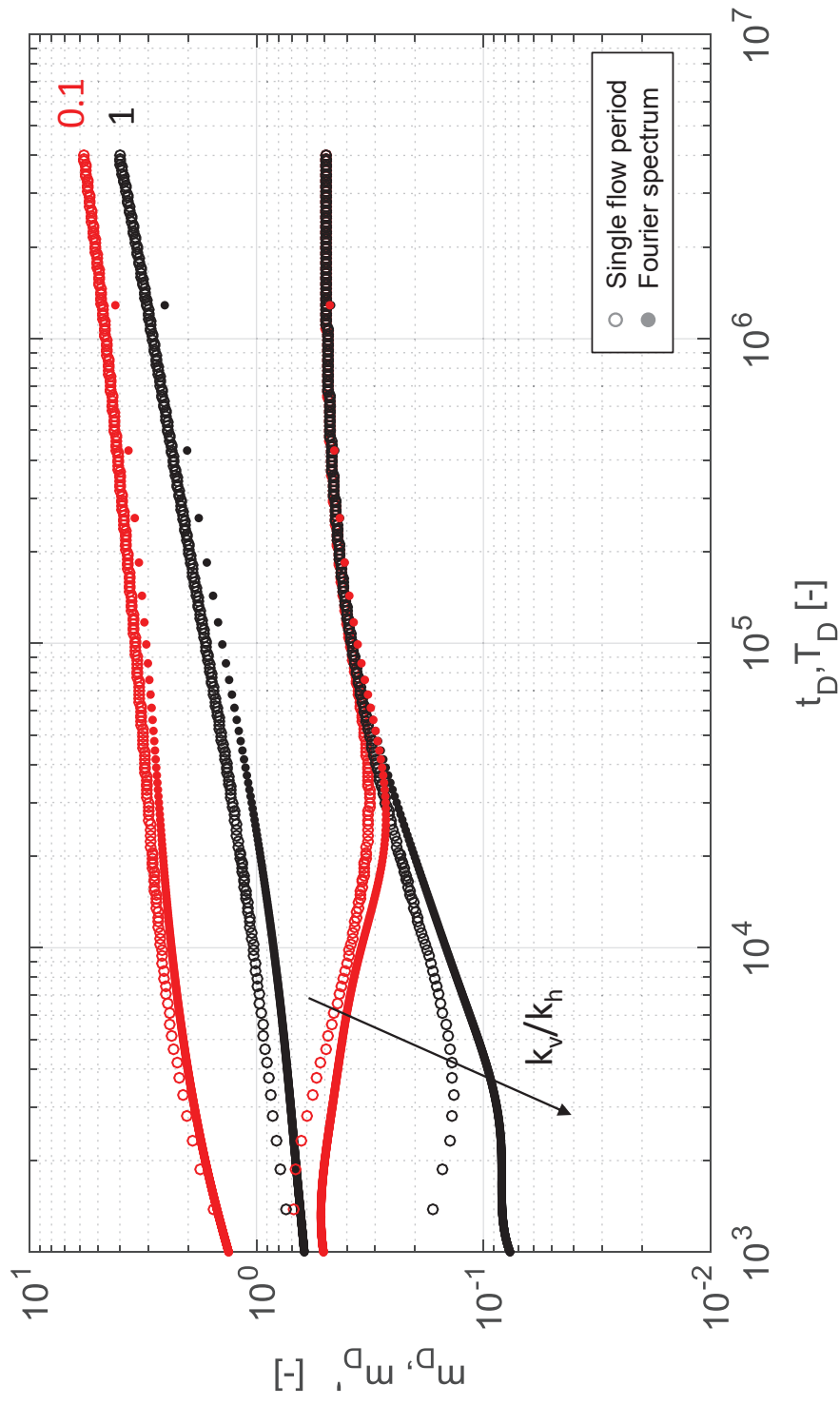


Figure 6

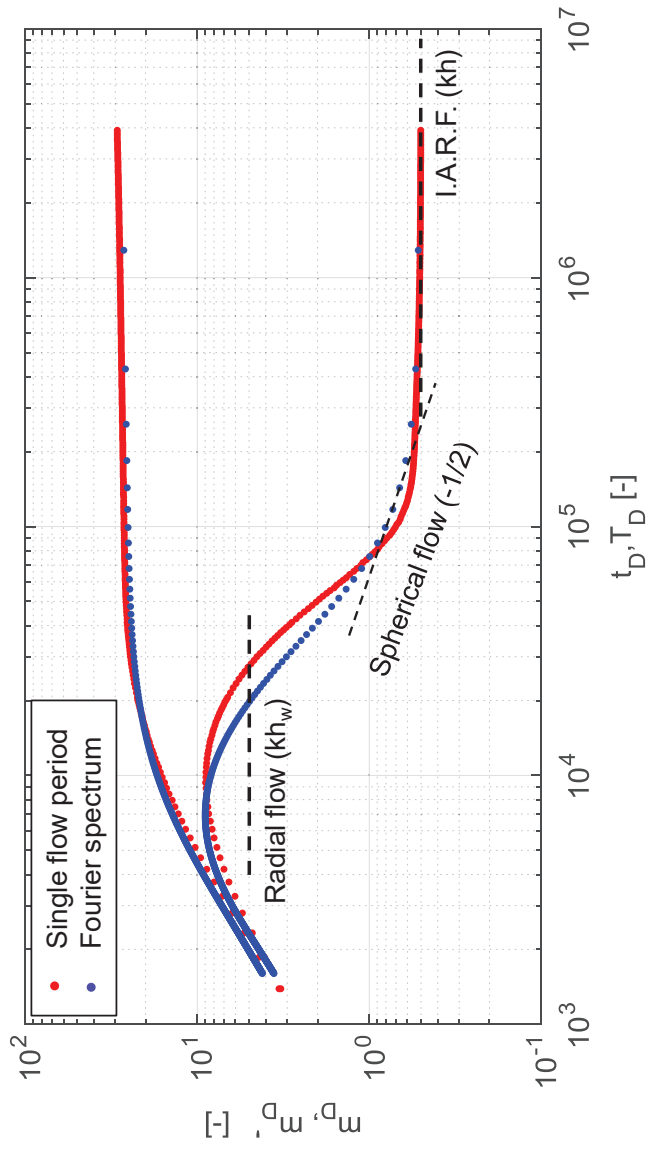


Figure 7

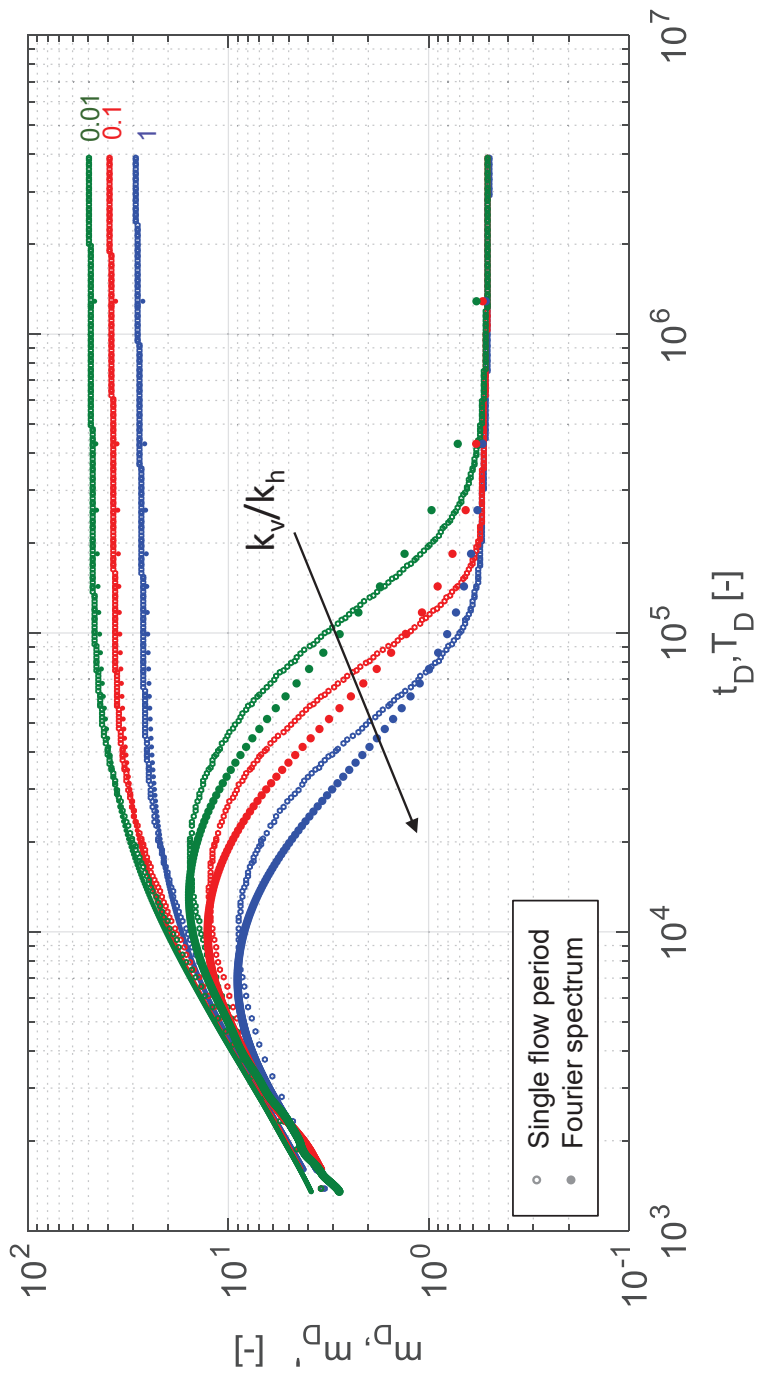


Figure 8

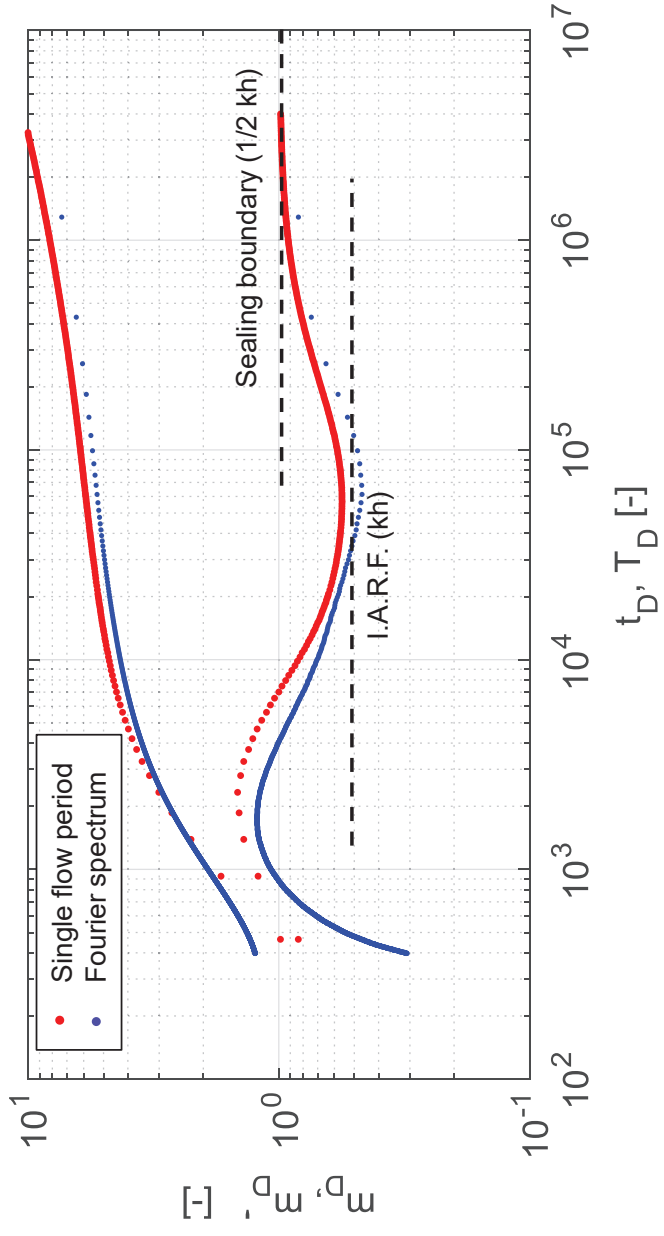


Figure 9

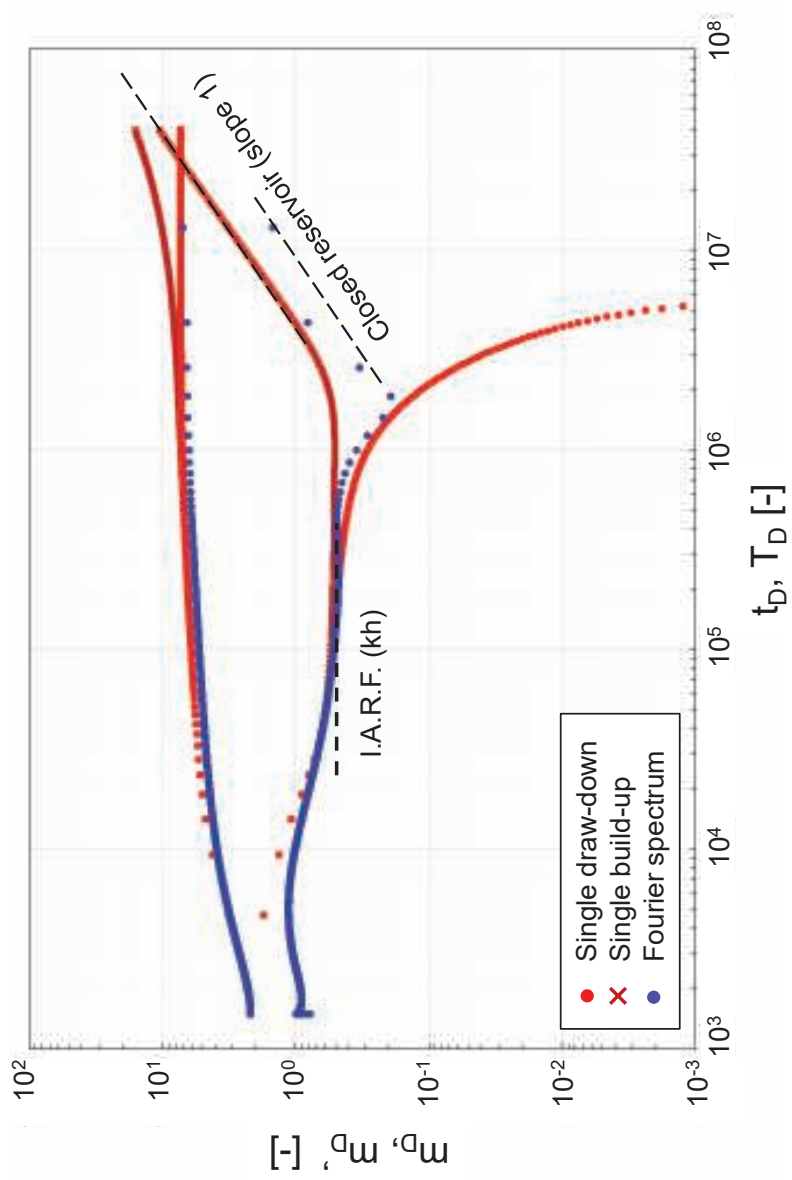


Figure 10

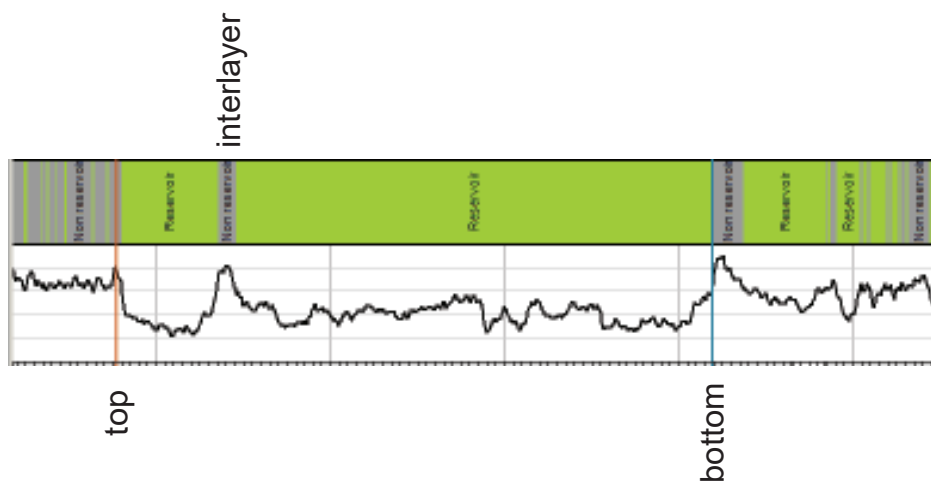
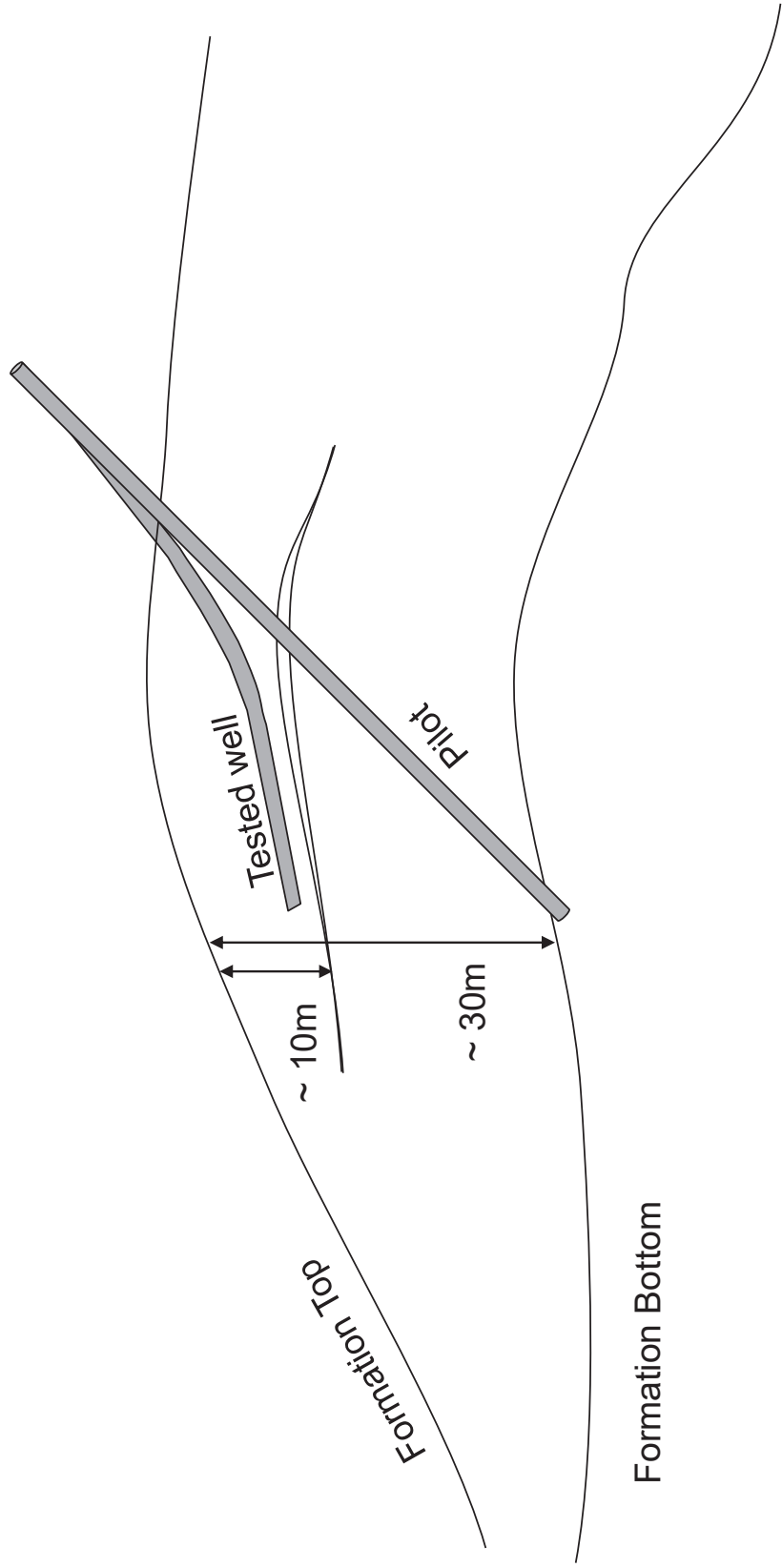


Figure 11



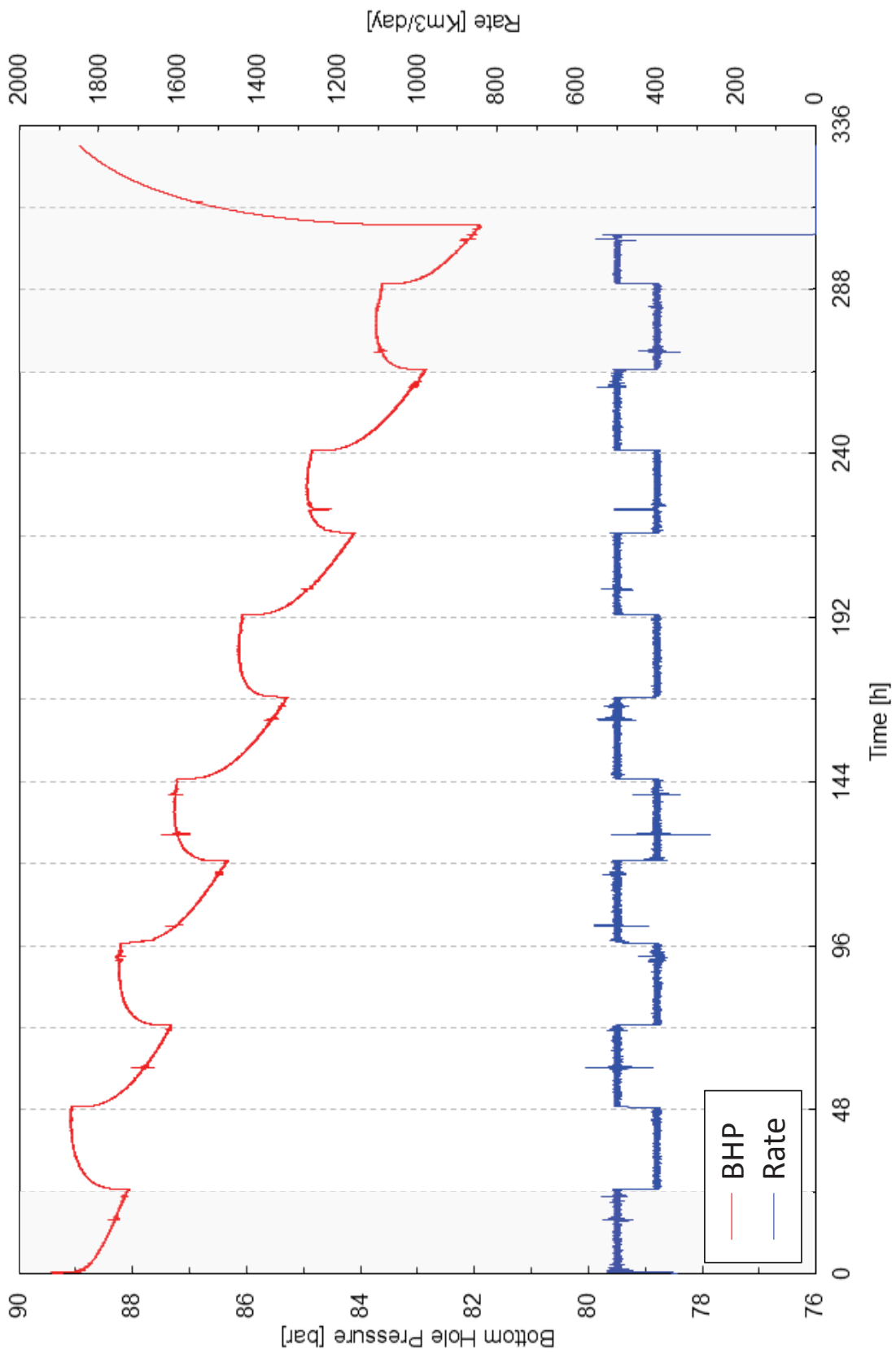


Figure 12

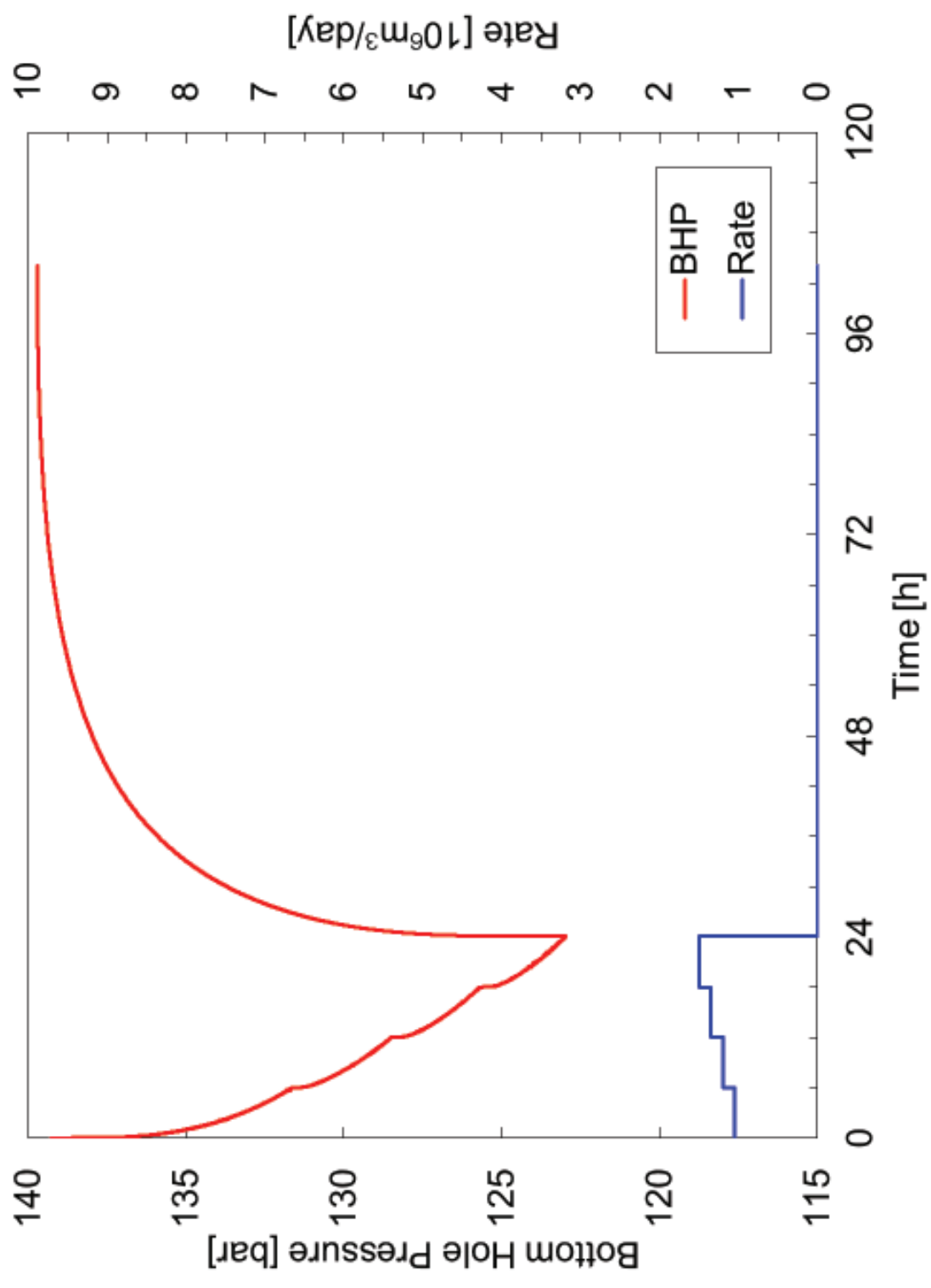


Figure 13

Figure 14

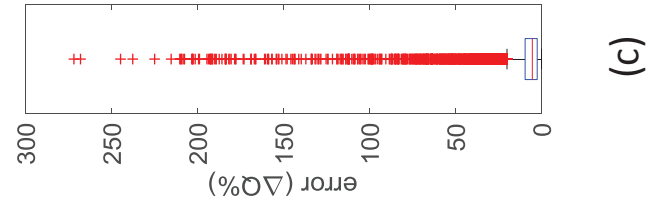
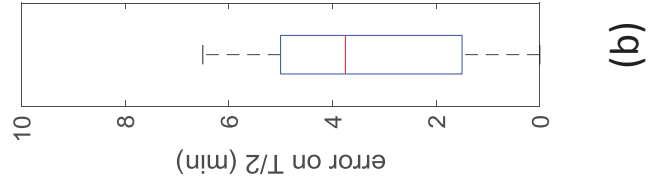
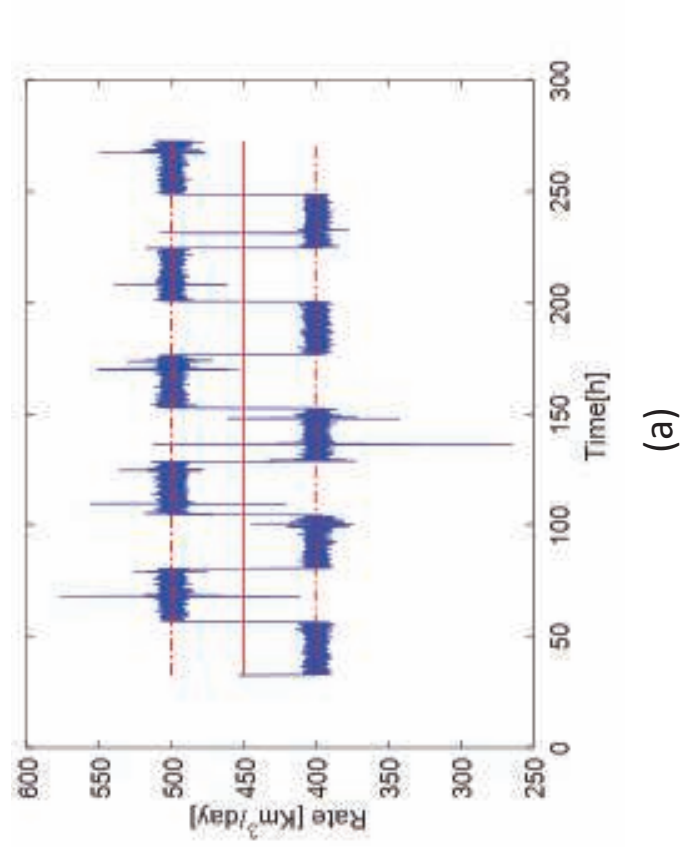


Figure 15

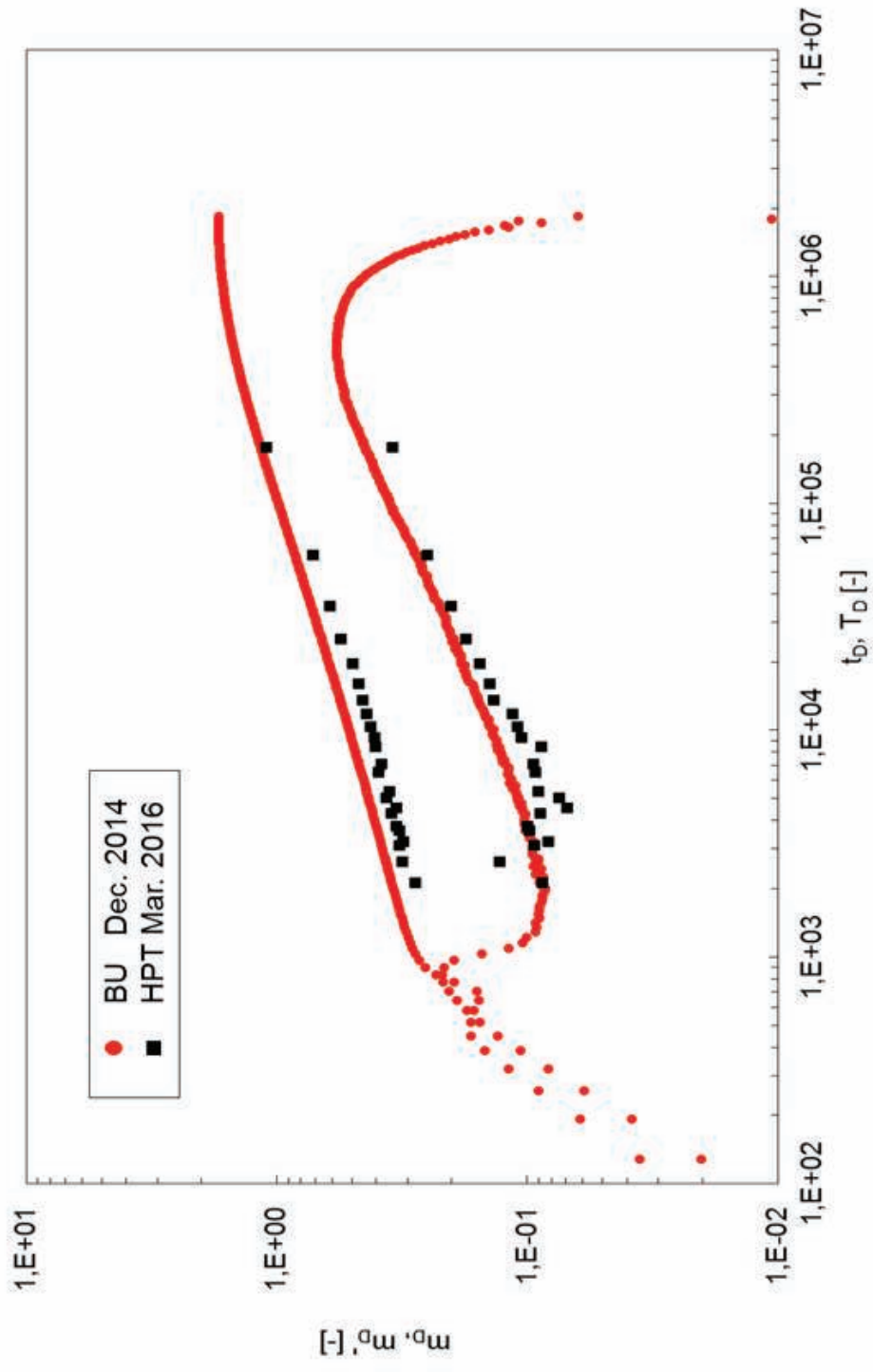


Figure 16

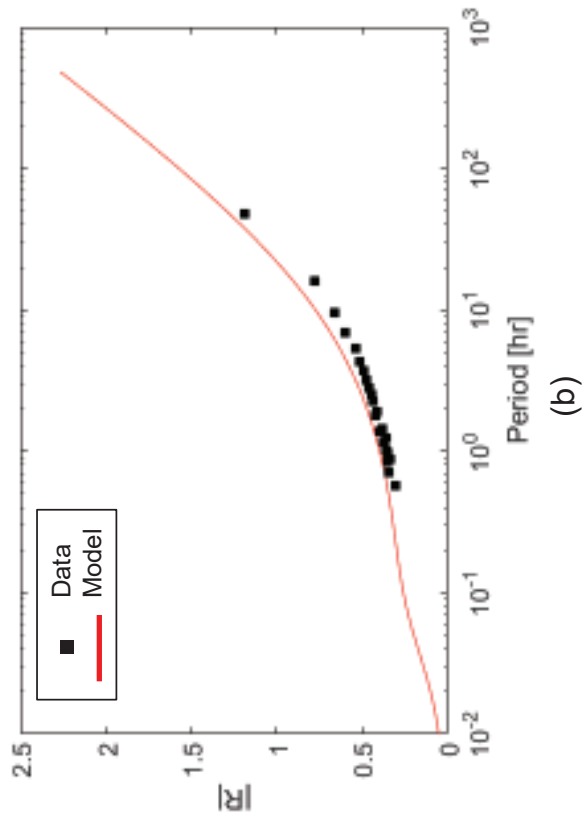
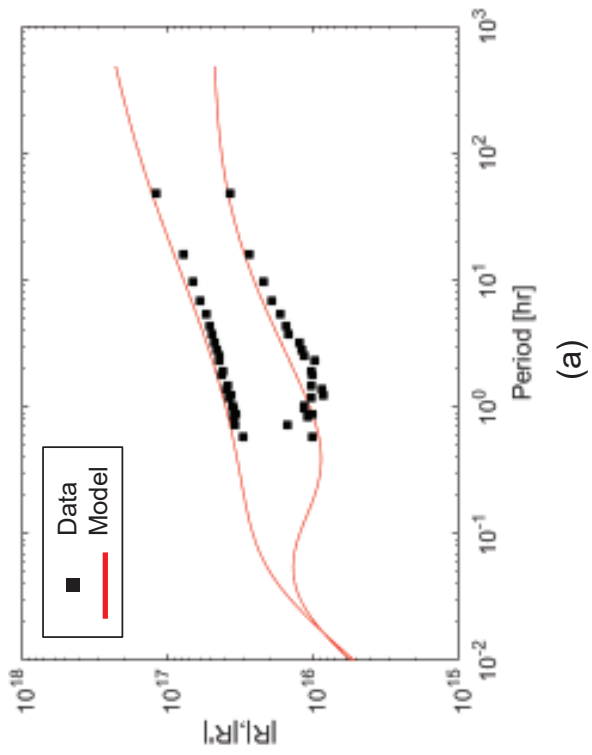


Figure A1

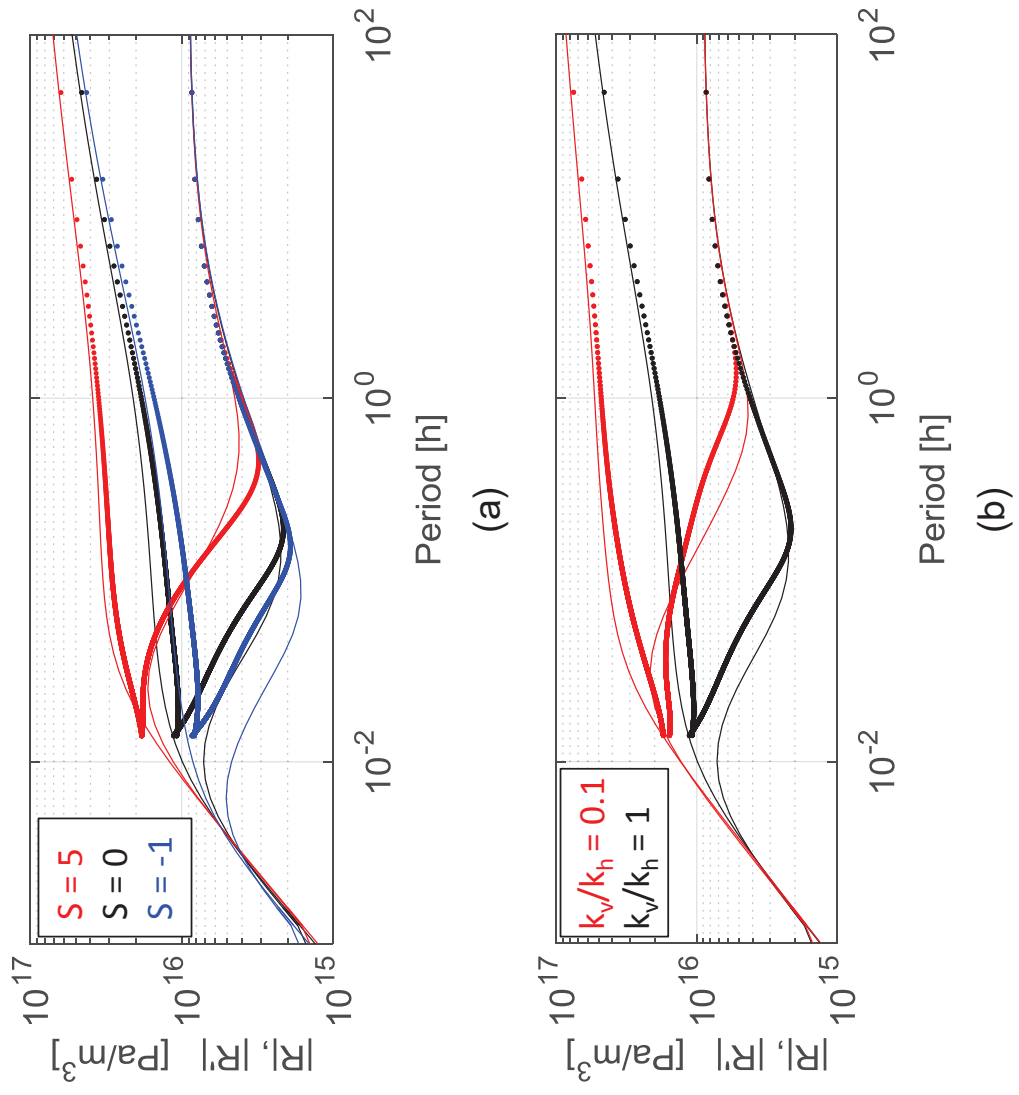


Table 1
[Click here to download Table: Table_1.docx](#)

Date	Test type	Notes	Interpretation
Dec. 2014	FAF	Preliminary shut-in Nearby wells shut during the test	Conventional
Mar. 2016	HPT	Storage under production. No well closure	Harmonic

Table 2[Click here to download Table: Table_2.docx](#)

	FAF BU Dec. 2014	HPT Mar. 2016
k (mD)	34	39
S (-)	0.2	0
C (Pa/m³)	$2 \cdot 10^{-5}$	$2 \cdot 10^{-5}$